Research Article

A New Computational Technique for Common Solutions between Systems of Generalized Mixed Equilibrium and Fixed Point Problems

Pongsakorn Sunthrayuth and Poom Kumam

Department of Mathematics, Faculty of Science, King Mongkut’s University of Technology Thonburi (KMUTT), Bang Mod, Bangkok 10140, Thailand

Correspondence should be addressed to Poom Kumam; poom.kum@kmutt.ac.th

Received 18 February 2013; Accepted 1 April 2013

Academic Editor: Wei-Shih Du

Copyright © 2013 P.Sunthrayuth and P.Kumam. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

We introduce a new iterative algorithm for finding a common element of a fixed point problem of amenable semigroups of nonexpansive mappings, the setsolutionsofasystemofageneralsystemofgeneralizedequilibriuminarealHilbertspace. Then, we prove the strong convergence of the proposed iterative algorithm to a common element of the above three sets under some suitable conditions. As applications, at the end of the paper, we apply our results to find the minimum-norm solutions which solve some quadratic minimization problems. The results obtained in this paper extend and improve many recent ones announced by many others.

1. Introduction

Throughout this paper, we denoted by $\mathbb{R}$ the set of all real numbers. We always assume that $H$ is a real Hilbert space with inner product $\langle \cdot, \cdot \rangle$ and induced norm $\| \cdot \|$ and $C$ is a nonempty, closed, and convex subset of $H$. $P_C$ denotes the metric projection of $H$ onto $C$. A mapping $T : C \to C$ is said to be $L$-Lipschitzian if there exists a constant $L > 0$ such that

$$
\|Tx - Ty\| \leq L\|x - y\|, \quad \forall x, y \in C. \quad (1)
$$

If $0 < L < 1$, then $T$ is a contraction, and if $L = 1$, then $T$ is a nonexpansive mapping. We denote by $\text{Fix}(T)$ the set of all fixed points set of the mapping $T$; that is, $\text{Fix}(T) = \{x \in C : Tx = x\}$.

A mapping $F : C \to H$ is said to be monotone if

$$
\langle Fx - Fy, x - y \rangle \geq 0, \quad \forall x, y \in C. \quad (2)
$$

A mapping $F : C \to H$ is said to be strongly monotone if there exists $\eta > 0$ such that

$$
\langle Fx - Fy, x - y \rangle \geq \eta\|x - y\|^2, \quad \forall x, y \in C. \quad (3)
$$

Let $\varphi : C \to \mathbb{R}$ be a real-valued function, $\Theta : C \times C \to \mathbb{R}$ an equilibrium bifunction, and $\Psi : C \to H$ a nonlinear mapping. The generalized mixed equilibrium problem is to find $x^* \in C$ such that

$$
\Theta(x^*, y) + \varphi(y) - \varphi(x^*) + \langle \Psi x^*, y - x^* \rangle \geq 0, \quad \forall y \in C, \quad (4)
$$

which was introduced and studied by Peng and Yao [1]. The set of solutions of problem (4) is denoted by $\text{GMEP}(\Theta, \varphi, \Psi)$. As special cases of problem (4), we have the following results.

(1) If $\Psi = 0$, then problem (4) reduces to mixed equilibrium problem. Find $x^* \in C$ such that

$$
\Theta(x^*, y) + \varphi(y) - \varphi(x^*) \geq 0, \quad \forall y \in C, \quad (5)
$$

which was considered by Ceng and Yao [2]. The set of solutions of problem (5) is denoted by $\text{MEP}(\Theta)$. (2) If $\varphi = 0$, then problem (4) reduces to generalized equilibrium problem. Find $x^* \in C$ such that

$$
\Theta(x^*, y) + \langle \Psi x^*, y - x^* \rangle \geq 0, \quad \forall y \in C, \quad (6)
$$
which was considered by S. Takahashi and W. Takahashi [3]. The set of solutions of problem (6) is denoted by \( \text{GEP}(\Theta, \Psi) \).

(3) If \( \Psi = \varphi = 0 \), then problem (4) reduces to an equilibrium problem. Find \( x^* \in C \) such that
\[
\Theta(x^*, y) \geq 0, \quad \forall y \in C. \tag{7}
\]
The set of solutions of problem (7) is denoted by \( \text{EP}(\Theta) \).

(4) If \( \Theta = \varphi = 0 \), then problem (4) reduces to a classical variational inequality problem. Find \( x^* \in C \) such that
\[
\langle \Psi x^*, y - x^* \rangle \geq 0, \quad \forall y \in C. \tag{8}
\]
The set of solutions of problem (8) is denoted by \( \text{VI}(C, \Psi) \). It is known that \( x^* \in C \) is a solution of the problem (8) if and only if \( x^* \) is a fixed point of the mapping \( P_C(I - \lambda \Psi) \), where \( \lambda > 0 \) is a constant and \( I \) is the identity mapping.

The problem (4) is very general in the sense that it includes several problems, namely, fixed point problems, optimization problems, saddle point problems, complementarity problems, variational inequality problems, minimax problems, Nash equilibrium problems in noncooperative games, and others as special cases. Numerous problems in physics, optimization, and economics reduce to find a solution of problem (4) (see, e.g., [4–9]). Several iterative methods to solve the fixed point problems, variational inequality problems, and equilibrium problems are proposed in the literature (see, e.g., [1–3, 10–18]) and the references therein.

Let \( A_1, A_2 : C \rightarrow H \) be two mappings. Ceng and Yao [12] considered the following problem of finding \( (x^*, y^*) \in C \times C \) such that
\[
G_2 (x^*, x) + \langle A_2 y^*, x - x^* \rangle + \frac{1}{\lambda_2} \langle x^* - y^*, x - x^* \rangle \geq 0, \quad \forall x \in C, \tag{9}
\]
\[
G_1 (y^*, y) + \langle A_1 x^*, y - y^* \rangle + \frac{1}{\lambda_1} \langle y^* - x^*, y - y^* \rangle \geq 0, \quad \forall y \in C, \tag{10}
\]
which is called a general system of generalized equilibria, where \( \lambda_1 > 0 \) and \( \lambda_2 > 0 \) are two constants. In particular, if \( G_1 = G_2 = G \) and \( A_1 = A_2 = A \), then problem (9) reduces to the following problem of finding \( (x^*, y^*) \in C \times C \) such that
\[
G(x^*, x) + \langle Ay^*, x - x^* \rangle + \frac{1}{\lambda_2} \langle x^* - y^*, x - x^* \rangle \geq 0, \quad \forall x \in C, \tag{11}
\]
\[
G(y^*, y) + \langle Ax^*, y - y^* \rangle + \frac{1}{\lambda_1} \langle y^* - x^*, y - y^* \rangle \geq 0, \quad \forall y \in C, \tag{12}
\]
which is called a new system of generalized equilibria, where \( \lambda_1 > 0 \) and \( \lambda_2 > 0 \) are two constants.

If \( G_1 = G_2 = \Theta, \lambda_1 = \lambda_2 = 1 \), and \( y^* = y^* \), then problem (9) reduces to problem (7).

If \( G_1 = G_2 = 0 \), then problem (9) reduces to a general system of variational inequalities. Find \( (x^*, y^*) \in C \times C \) such that
\[
\langle \lambda_2 A_2 y^* + x^* - y^*, x - x^* \rangle \geq 0, \quad \forall x \in C, \tag{13}
\]
\[
\langle \lambda_1 A_1 x^* + y^* - x^*, y - y^* \rangle \geq 0, \quad \forall y \in C, \tag{14}
\]
where \( \lambda_1 > 0 \) and \( \lambda_2 > 0 \) are two constants, which is introduced and considered by Ceng et al. [19].

In 2010, Ceng and Yao [12] proposed the following relaxed extragradient-like method for finding a common solution of generalized mixed equilibrium problems, a system of generalized equilibria (9), and a fixed point problem of a k-strictly pseudocontractive self-mapping \( S \) on \( C \) as follows:

\[
z_n = S^G(\xi_n) \left( x_n - r_n \Psi x_n \right),
\]
\[
y_n = S^G_1 \left[ S^G_2 \left( z_n - \lambda_2 A_2 z_n \right) - \lambda_1 A_1 S^G_2 \left( z_n - \lambda_2 A_2 z_n \right) \right],
\]
\[
x_{n+1} = \alpha_n x + \beta_n x_n + \gamma_n y_n + \delta_n S y_n, \quad \forall n \geq 0, \tag{15}
\]
where \( \Psi, A_1, A_2 : C \rightarrow H \) are \( \alpha \)-inverse strongly monotone, \( \alpha_1 \)-inverse strongly monotone, and \( \alpha_2 \)-inverse strongly monotone, respectively. They proved strong convergence of the related extragradient-like algorithm (12) under some appropriate conditions \( \{\alpha_n\}, \{\beta_n\}, \{\gamma_n\}, \) and \( \{\delta_n\} \subset [0, 1] \) satisfying \( 0 < \alpha_n + \beta_n + \gamma_n + \delta_n = 1 \), for all \( n \geq 0 \), to \( \bar{x} = \Pi_{T^*} \bar{x} \), where \( \Omega = \text{Fix}(S) \cap \text{GMEP}(\Theta, \varphi, \Psi) \cap \text{Fix}(K) \), with the mapping \( K : C \rightarrow C \) defined by
\[
Kx = S^G_1 \left[ S^G_2 \left( x - \lambda_2 A_2 x \right) - \lambda_1 A_1 S^G_2 \left( x - \lambda_2 A_2 x \right) \right],
\]
\[
\forall x \in C. \tag{16}
\]

Very recently, Ceng et al. [11] introduced an iterative method for finding fixed points of a nonexpansive mapping \( T \) on a nonempty, closed, and convex subset \( C \) in a real Hilbert space \( H \) as follows:
\[
x_{n+1} = \Pi_C \left[ \alpha_n x_n + (I - \alpha_n \mu F) T x_n \right], \quad \forall n \geq 0, \tag{17}
\]
where \( \Pi_C \) is a metric projection from \( H \) onto \( C \), \( V \) is an \( L \)-Lipschitzian mapping with a constant \( L \geq 0 \) and \( F \) is a \( k \)-Lipschitzian and \( \eta \)-strongly monotone operator with constants \( k, \eta > 0 \) and \( 0 < \mu < 2 \eta / k^2 \). Then, they proved that the sequences generated by (14) converge strongly to a unique solution of variational inequality as follows:
\[
\langle (\mu F - \eta V) x^*, x^* - x \rangle \geq 0, \quad \forall x \in \text{Fix}(T). \tag{18}
\]
In this paper, motivated and inspired by the previous facts, we first introduce the following problem of finding \((x_1^*, x_2^*, \ldots, x_M^*) \in X \times X \times \cdots \times X\) such that
\[
G_M(x_1^*, x_1) + \left\langle A_{M}x_M^*, x_1 - x_1^* \right\rangle + \frac{1}{\lambda_M} \left\langle x_1^* - x_M^*, x_1 - x_1^* \right\rangle \geq 0, \quad \forall x_1 \in C,
\]
\[
G_{M-1}(x_M^*, x_M) + \left\langle A_{M-1}x_{M-1}^*, x_M - x_M^* \right\rangle + \frac{1}{\lambda_{M-1}} \left\langle x_M^* - x_{M-1}^*, x_M - x_M^* \right\rangle \geq 0, \quad \forall x_M \in C,
\]
\[\vdots\]
\[
G_2(x_2^*, x_2) + \left\langle A_2x_2^*, x_2 - x_2^* \right\rangle + \frac{1}{\lambda_2} \left\langle x_2^* - x_2^*, x_2 - x_2^* \right\rangle \geq 0, \quad \forall x_2 \in C,
\]
\[
G_1(x_2^*, x_2) + \left\langle A_1x_1^*, x_2 - x_2^* \right\rangle + \frac{1}{\lambda_1} \left\langle x_1^* - x_1^*, x_2 - x_2^* \right\rangle \geq 0, \quad \forall x_2 \in C,
\]
which is called a more general system of generalized equilibria in Hilbert spaces, where \(\lambda_i > 0\) for all \(i \in \{1, 2, \ldots, M\}\). In particular, if \(M = 2\), \(x_1^* = x^*\), \(x_2^* = y^*\), \(x_1 = x\), and \(x_2 = y\), then problem (16) reduces to problem (9). Finally, by combining the relaxed extragradient-like algorithm (12) with the general iterative algorithm (14), we introduce a new iterative method for finding a common element of a fixed point problem of a nonexpansive semigroup, the set solutions of a general system of generalized equilibria in a real Hilbert space. We prove the strong convergence of the proposed iterative algorithm to a common element of the previous three sets under some suitable conditions. Furthermore, we apply our results to finding the minimum-norm solutions which solve some quadratic minimization problem. The main result extends various results existing in the current literature.

2. Preliminaries

Let \(S\) be a semigroup. We denote by \(\ell^\infty\) the Banach space of all bounded real-valued functions on \(S\) with supremum norm. For each \(s \in S\), we define the left and right translation operators \(l(s)\) and \(r(s)\) on \(\ell^\infty\) by
\[
(l(s)f)(t) = f(st), \quad (r(s)f)(t) = f(ts),
\]
for each \(t \in S\) and \(f \in \ell^\infty\), respectively. Let \(X\) be a subspace of \(\ell^\infty\) containing 1. An element \(\mu\) in the dual space \(X^*\) of \(X\) is said to be a mean on \(X\) if \(\|\mu\| = \mu(1) = 1\). It is well known that \(\mu\) is a mean on \(X\) if and only if
\[
\inf_{x \in S} f(s) \leq \mu(f) \leq \sup_{x \in S} f(s),
\]
for each \(f \in X\). We often write \(\mu_x(f(t))\) instead of \(\mu(f)\) for \(\mu \in X^*\) and \(f \in X\).

Let \(X\) be a translation invariant subspace of \(\ell^\infty\) (i.e., \(l(s)X \subset X\) and \(r(s)X \subset X\) for each \(s \in S\)) containing 1. Then, a mean \(\mu\) on \(X\) is said to be left invariant (resp., right invariant) if \(l(s)f) = \mu(f)\) (resp., \(r(s)f) = \mu(f)\) for each \(s \in S\) and \(f \in X\). A mean \(\mu\) on \(X\) is said to be invariant if \(\mu\) is both left and right invariant [20–22]. \(S\) is said to be left (resp., right) amenable if \(X\) has a left (resp., right) invariant mean. \(S\) is a amenable if \(S\) is left and right amenable. In this case, \(\ell^\infty\) also has an invariant mean. As is well known, \(\ell^\infty\) is amenable when \(S\) is commutative subsemigroup; see [23]. A net \(|\mu_x|\) of means on \(X\) is said to be left regular if
\[
\lim_{\alpha} \|l_s^\alpha \mu_x - \mu_x\| = 0,
\]
for each \(s \in S\), where \(l_s^\alpha\) is the adjoint operator of \(l_s\).

Let \(C\) be a nonempty, closed, and convex subset of \(H\). A family \(\delta = \{T(s) : s \in S\}\) is called a nonexpansive semigroup on \(C\) if for each \(s \in S\), the mapping \(T(s) : C \rightarrow C\) is nonexpansive and \(T(st) = T(ts)\) for each \(s, t \in S\). We denote by \(Fix(\delta)\) the set of common fixed point of \(\delta\); that is,
\[
Fix(\delta) = \bigcap_{s \in S} Fix(T(s)) = \{x \in C : T(s)x = x\}.
\]

Throughout this paper, the open ball of radius \(r\) centered at 0 is denoted by \(B_r\), and for a subset \(D\) of \(C\) by \(\overline{D}\). We denote the closed convex hull of \(D\). For \(\varepsilon > 0\) and a mapping \(T : D \rightarrow H\), the set of \(\varepsilon\)-approximate fixed point of \(T\) is denoted by \(F_\varepsilon(T,D)\); that is, \(F_\varepsilon(T,D) = \{x \in D : \|x - Tx\| \leq \varepsilon\}\).

In order to prove our main results, we need the following lemmas.

**Lemma 1** [23–25]. Let \(f\) be a function of a semigroup \(S\) into a Banach space \(E\) such that the weak closure of \(\{f(t) : t \in S\}\) is weakly compact, and let \(X\) be a subspace of \(\ell^\infty\) containing all the functions \(t \mapsto \langle f(t), x^* \rangle\) with \(x^* \in E^*\). Then, for any \(\mu \in X^*\), there exists a unique element \(f_\mu\) in \(E\) such that
\[
\langle f_\mu, x^* \rangle = \mu_\mu(f(t), x^*),
\]
for all \(x^* \in E^*\). Moreover, if \(\mu\) is a mean on \(X\), then
\[
\int f(t) d\mu(t) = \overline{\inf}\{f(t) : t \in S\}.
\]
One can write \(f_\mu\) by \(\int f(t)d\mu(t)\).

**Lemma 2** [23–25]. Let \(C\) be a closed and convex subset of a Hilbert space \(H\), \(\delta = \{T(s) : s \in S\}\) a nonexpansive semigroup from \(C\) into \(C\) such that \(Fix(\delta) \neq \emptyset\) and \(X\) a subspace of \(\ell^\infty\) containing 1, the mapping \(t \mapsto \langle T(t)x, y \rangle\) an element of \(X\) for each \(x \in C\) and \(y \in H\), and \(\mu\) a mean on \(X\).

If one writes \(T(\mu)x\) instead of \(\int T(t)x d\mu(t)\), then the following hold:

(i) \(T(\mu)\) is nonexpansive mapping from \(C\) into \(C\);
(ii) \(T(\mu)x = x\) for each \(x \in Fix(\delta)\);
(iii) \(T(\mu)x \in \overline{\inf}\{T(t)x : t \in S\}\) for each \(x \in C\);
(iv) if \( \mu \) is left invariant, then \( T(\mu) \) is a nonexpansive retraction from \( C \) onto \( \text{Fix}(\delta) \).

Let \( H \) be a real Hilbert space with inner product \( \langle \cdot, \cdot \rangle \) and norm \( \| \cdot \| \), and let \( C \) be a nonempty, closed, and convex subset of \( H \). We denote the strong convergence and the weak convergence of \( \{x_n\} \) to \( x \in H \) by \( x_n \to x \) and \( x_n \rightharpoonup x \), respectively. Also, a mapping \( I : C \to C \) denotes the identity mapping. For every point \( x \in H \), there exists a unique nearest point of \( C \), denoted by \( P_C x \), such that

\[
\| x - P_C x \| \leq \| x - y \|, \quad \forall y \in C.
\] (23)

Such a projection \( P_C \) is called the metric projection of \( H \) onto \( C \). We know that \( P_C \) is a firmly nonexpansive mapping of \( H \) onto \( C \); that is,

\[
(x - y, P_C x - P_C y) \geq \| P_C x - P_C y \|^2, \quad \forall x, y \in H.
\] (24)

It is known that

\[
z = P_C x \iff \langle x - z, y - z \rangle \leq 0, \quad \forall x \in H, \quad y \in C.
\] (25)

In a real Hilbert space \( H \), it is well known that

\[
\| x - y \|^2 = \| x \|^2 - \| y \|^2 - 2 \langle x - y, y \rangle,
\] (26)

\[
\| \lambda x + (1 - \lambda) y \|^2 = \lambda \| x \|^2 + (1 - \lambda) \| y \|^2 - \lambda (1 - \lambda) \| x - y \|^2,
\] (27)

for all \( x, y \in H \) and \( \lambda \in [0, 1] \).

If \( A : C \to H \) is \( \alpha \)-inverse strongly monotone, then it is obvious that \( A \) is \( 1/\alpha \)-Lipschitz continuous. We also have that, for all \( x, y \in C \) and \( \lambda > 0 \),

\[
\| (I - \lambda A) x - (I - \lambda) y \|^2 = \| x - y \|^2 - 2 \lambda \langle A x - A y, x - y \rangle + \lambda^2 \| A x - A y \|^2
\]

\[
\leq \| x - y \|^2 + \lambda (\lambda - 2\alpha) \| A x - A y \|^2.
\] (28)

In particular, if \( \alpha < 2\alpha \), then \( I - \lambda A \) is a nonexpansive mapping from \( C \) to \( H \).

For solving the equilibrium problem, let us assume that the bifunction \( \Theta : C \times C \to \mathbb{R} \) satisfies the following conditions:

(A1) \( \Theta(x, x) = 0 \) for all \( x \in C \);

(A2) \( \Theta \) is monotone, that is, \( \Theta(x, y) + \Theta(y, x) \leq 0 \) for each \( x, y \in C \);

(A3) \( \Theta \) is upper semicontinuous, that is, for each \( x, y, z \in C \),

\[
\limsup_{t \to 0^+} \Theta(tz + (1 - t)x, y) \leq \Theta(x, y);
\] (29)

(A4) \( \Theta(\cdot, \cdot) \) is convex and weakly lower semicontinuous for each \( x \in C \);

(B1) for each \( x \in H \) and \( r > 0 \), there exists a bounded subset \( D_x \subset C \) and \( y_x \in C \) such that for all \( z \in C \) \( D_x \),

\[
\Theta(z, y_x) + \varphi(y_x) - \varphi(z) + \frac{1}{r} \langle y_x - z, z - x \rangle < 0;
\] (30)

(B2) \( C \) is a bounded set.

Lemma 3 (see [1]). Let \( C \) be a nonempty, closed, and convex subset of a real Hilbert space \( H \). Let \( \Theta : C \times C \to \mathbb{R} \) be a bifunction satisfying conditions (A1) – (A4), and let \( \varphi : C \to \mathbb{R} \) be a lower semicontinuous and convex function. For \( r > 0 \) and \( x \in H \), define a mapping \( S_r^{(\theta, \varphi)} : H \to C \) as follows:

\[
S_r^{(\theta, \varphi)}(x) = \left\{ y \in C : \Theta(y, z) + \varphi(z) - \varphi(y) + \frac{1}{r} \langle y - z, z - x \rangle \geq 0, \forall z \in C \right\}.
\] (31)

Assume that either (B1) or (B2) holds. Then, the following hold:

(i) \( S_r^{(\theta, \varphi)} \neq \emptyset \) for all \( x \in H \) and \( S_r^{(\theta, \varphi)} \) is single valued;

(ii) \( S_r^{(\theta, \varphi)} \) is firmly nonexpansive, that is, for all \( x, y \in H \),

\[
\| S_r^{(\theta, \varphi)} x - S_r^{(\theta, \varphi)} y \|^2 \leq \| S_r^{(\theta, \varphi)} x - S_r^{(\theta, \varphi)} y, x - y \|;
\] (32)

(iii) \( \text{Fix}(S_r^{(\theta, \varphi)}) = \text{MEP}(\Theta, \varphi) \);

(iv) \( \text{MEP}(\Theta, \varphi) \) is closed and convex.

Remark 4. If \( \varphi = 0 \), then \( S_r^{(\theta, \varphi)} \) is rewritten as \( S_r^{\theta} \) (see [12, Lemma 2.1] for more details).

Lemma 5 (see [26]). Let \( \{x_n\} \) and \( \{l_n\} \) be bounded sequences in a Banach space \( X \), and let \( \{\beta_n\} \) be a sequence in \( [0, 1] \) with \( 0 < \liminf_{n \to \infty} \beta_n \leq \limsup_{n \to \infty} \beta_n < 1 \). Suppose that \( x_{n+1} = (1 - \beta_n) x_n + \beta_n x_n \) for all integers \( n \geq 0 \) and \( \limsup_{n \to \infty} (l_{n+1} - l_n) \leq 0 \). Then, \( \lim_{n \to \infty} \| x_n - x \| = 0 \).

Lemma 6 (Demiclosedness Principle [27]). Let \( C \) be a nonempty, closed, and convex subset of a real Hilbert space \( H \). Let \( T : C \to C \) be a nonexpansive mapping with \( \text{Fix}(T) \neq \emptyset \). If \( \{x_n\} \) is a sequence in \( C \) that converges weakly to \( x \) and if \( (I - T)x_n \) converges strongly to \( y \), then \( (I - T)x = y \); in particular, if \( y = 0 \), then \( x \in \text{Fix}(T) \).

Lemma 7 (see [28]). Assume that \( \{a_n\} \) is a sequence of nonnegative real numbers such that

\[
a_{n+1} \leq (1 - \sigma_n) a_n + \delta_n,
\] (33)

where \( \{\sigma_n\} \) is a sequence in \( (0, 1) \) and \( \{\delta_n\} \) is a sequence in \( \mathbb{R} \) such that

(i) \( \sum_{n=0}^{\infty} \sigma_n = \infty \);

(ii) \( \limsup_{n \to \infty} (\delta_n/\sigma_n) \leq 0 \) or \( \sum_{n=0}^{\infty} |\delta_n| < \infty \).

Then, \( \lim_{n \to \infty} a_n = 0 \).
The following lemma can be found in [29, 30]. For the sake of the completeness, we include its proof in a real Hilbert space version.

**Lemma 8.** Let \( C \) be a nonempty, closed, and convex subset of a real Hilbert space \( H \). Let \( F : C \to X \) be a \( k \)-Lipschitzian and \( \eta \)-strongly monotone operator. Let \( 0 < \mu < 2\eta/k^2 \) and \( \tau = \mu(\eta - \mu k^2/2) \). Then, for each \( t \in (0, \min\{1, 1/2\tau\}) \), the mapping \( S : C \to H \) defined by \( S := 1 - t\mu F \) is a contraction with constant \( 1 - t\tau \).

**Proof.** Since \( 0 < \mu < 2\eta/k^2 \) and \( t \in (0, \min\{1, 1/2\tau\}) \), this implies that \( 1 - t\tau \in (0, 1). \) For all \( x, y \in C \), we have

\[
\|Sx - Sy\|^2 = \|(1 - t\mu F)x - (1 - t\mu F)y\|^2 \\
= \|(x - y) - t\mu(Fx - Fy)\|^2 \\
= \|x - y\|^2 - 2t\mu\langle Fx - Fy, x - y \rangle \\
+ t^2\mu^2\|Fx - Fy\|^2 \\
\leq \|x - y\|^2 - 2t\mu\|x - y\|^2 \\
+ t^2\mu^2\|x - y\|^2 \\
\leq \left[1 - t\mu(2\eta - \mu k^2)\right]\|x - y\|^2 \\
= \left[1 - 2t\mu\left(\eta - \frac{\mu k^2}{2}\right)\right]\|x - y\|^2 \\
\leq \left[1 - t\mu\left(\eta - \frac{\mu k^2}{2}\right)\right]^2\|x - y\|^2 \\
= (1 - t\tau)^2\|x - y\|^2.
\]

It follows that

\[
\|Sx - Sy\| \leq (1 - t\tau)\|x - y\|.
\]

Hence, we have that \( S := 1 - t\mu F \) is a contraction with constant \( 1 - t\tau \). This completes the proof. \( \square \)

**Lemma 9.** Let \( C \) be a nonempty, closed, and convex subset of a real Hilbert space \( H \). Let \( A_i : C \to H \) be a nonlinear mapping. For given \( (x_1^*, x_2^*, \ldots, x_M^*) \in C \times C \times \cdots \times C \), where \( x^* = x_1^*, \ldots, x_i^* = S_{\lambda_i}^{G_{\lambda_i}}((1 - \lambda_{i-1}A_{i-1})x_i^*) \), for \( i = 2, 3, \ldots, M \), and \( x_1^* = S_{\lambda_1}^{G_{\lambda_1}}((1 - \lambda_1A_1)x_1^*) \), then \( (x_1^*, x_2^*, \ldots, x_M^*) \) is a solution of the problem (16) if and only if \( x^* \) is a fixed point of the mapping \( K \) defined as in Lemma 9.

**Proof.** Let \( (x_1^*, x_2^*, \ldots, x_M^*) \in C \times C \times \cdots \times C \) be a solution of the problem (16). Then, we have

\[
G_M(x_1^*, x_1) + \langle A_Mx_M^*, x_1 - x_1^* \rangle + \frac{1}{\lambda_M}\langle x_1^* - x_M^*, x_1 - x_1^* \rangle \geq 0, \quad \forall x_1 \in C,
\]

\[
G_{M-1}(x_M^*, x_M) + \langle A_{M-1}x_{M-1}, x_M - x_M^* \rangle + \frac{1}{\lambda_{M-1}}\langle x_M^* - x_{M-1}^*, x_M - x_M^* \rangle \geq 0, \quad \forall x_M \in C,
\]

\[
\vdots
\]

\[
G_2(x_3^*, x_3) + \langle A_2x_3^*, x_3 - x_3^* \rangle + \frac{1}{\lambda_2}\langle x_3^* - x_2^*, x_3 - x_3^* \rangle \geq 0, \quad \forall x_3 \in C,
\]

\[
G_1(x_2^*, x_2) + \langle A_1x_2^*, x_2 - x_2^* \rangle + \frac{1}{\lambda_1}\langle x_2^* - x_1^*, x_2 - x_2^* \rangle \geq 0, \quad \forall x_2 \in C,
\]

\( \square \)
Let $C$ be a nonempty, closed, and convex subset of a real Hilbert space $H$. Let $\Theta_k : C \times C \to \mathbb{R} (k = 1, 2, \ldots, N)$ a finite family of bifunctions which satisfy (A1)–(A4), $\varphi_k : C \to \mathbb{R} (k = 1, 2, \ldots, N)$ a finite family of lower semicontinuous and convex functions, and $\Psi_k : C \to H (k = 1, 2, \ldots, N)$ a finite family of a $\mu_k$-inverse strongly monotone mapping and $\Lambda_k : C \to H (k = 1, 2, \ldots, N)$ a finite family of an $\alpha_k$-inverse strongly monotone mapping. Let $S$ be a semigroup, and let $\delta = [T(t) : t \in S]$ be a nonexpansive semigroup on $X$ such that $\text{Fix}(\delta) \neq \emptyset$. Let $X$ be a left invariant subspace of $\mathcal{E}(S)$ such that $x \in X$ and the function $t \mapsto (T(t)x, y)$ is an element of $X$ for $x \in C$ and $y \in H$. Let $\{\mu_k\}$ be a left regular sequence of means on $X$ such that $\lim_{k \to \infty} \mu_{k+1} - \mu_k = 0$. Let $F : C \to H$ be a $\mu$-Lipschitzian and $\eta$-strongly monotone operator with constants $\mu, \eta > 0$, and let $V : C \to H$ be an $L$-Lipschitzian mapping with a constant $L \geq 0$. Let $0 < \mu < 2\eta^2/k^2$ and $0 \leq \gamma < \frac{\mu}{\eta + \mu k^2/2}$. Assume that $X = \bigcap_{k=1}^{N} \text{GMEP}(\Theta_k, \varphi_k, \Psi_k) \cap (K) \cap \text{Fix}(\delta) \neq \emptyset$, where $K$ is defined as in Lemma 9. For given $x_1 \in C$, let $\{x_n\}$ be a sequence defined by

\[
\begin{align*}
    x_n & = S_{\lambda_n}^{\Theta_k, \varphi_k, \Psi_k} (I - r_{N_k} \Psi_k) S_{\lambda_{n-1}}^{\Theta_k, \varphi_k, \Psi_k} (I - r_{N_{n-1}} \Psi_k) x_n, \\
    y_n & = S_{\lambda_n}^{\Theta_k, \varphi_k, \Psi_k} (I - r_{N_k} \Psi_k) S_{\lambda_{n-1}}^{\Theta_k, \varphi_k, \Psi_k} (I - r_{N_{n-1}} \Psi_k) x_n, \\
    x_{n+1} & = \beta_n x_n + (1 - \beta_n) \gamma V x_n + (1 - \alpha_n \mu F) T (\mu_n) y_n, \\
    \gamma V x_n & = \liminf_{n \to \infty} \gamma V x_n, \\
    r_{N_k} & = \frac{1}{(k - 1) + \rho_k}, \\
    \gamma & = \frac{\mu}{\eta + \mu k^2/2}, \\
    \lambda_n & = \frac{1}{n}. 
\end{align*}
\]

where $\{\alpha_n\}$, $\{\beta_n\}$ are sequences in $(0, 1)$, and $\{r_{N_k}\}_{k=1}^{N}$ is a sequence such that $\{r_{N_k}\}_{k=1}^{N} \subset [a_k, b_k] \subset (0, 2/k)$ satisfying the following conditions:

(C1) $\lim_{n \to \infty} \alpha_n = 0$ and $\sum_{n=1}^{\infty} \alpha_n = \infty$;

(C2) $0 < \liminf_{n \to \infty} \beta_n \leq \limsup_{n \to \infty} \beta_n < 1$;

(C3) $\lim_{n \to \infty} r_{N_k} < 1$ and $\lim_{n \to \infty} (r_{N_k}/r_{N_{k+1}}) = 1$ for all $k \in \{1, 2, \ldots, N\}$.

Then, the sequence $\{x_n\}$ defined by (39) converges strongly to $\bar{x} \in X$ as $n \to \infty$, where $\bar{x}$ solves uniquely the variational inequality

\[
\langle (\mu F - \gamma V) \bar{x}, \bar{x} - v \rangle \leq 0, \quad \forall v \in X. 
\]

Equivalently, one has $\bar{x} = P_{X} (I - \mu F + \gamma V) \bar{x}$.

Proof. Note that from condition (C1), we may assume, without loss of generality, that $\alpha_n \leq \min\{1, 1/2\}$ for all $n \in N$. First, we show that $\{x_n\}$ is bounded. Set

\[
G_n^k := S_{\lambda_n}^{\Theta_k, \varphi_k, \Psi_k} (I - r_{N_k} \Psi_k) S_{\lambda_{n-1}}^{\Theta_k, \varphi_k, \Psi_k} (I - r_{N_{n-1}} \Psi_k),
\]

\[
\forall k \in \{1, 2, \ldots, M\}, \quad n \in N.
\]

By Lemma 10, we have $x^* = Q^M x^*$. It follows from (42) that

\[
\|
\begin{align*}
    u_n - x^* & = \|G_n^M x_n - G_n^M x^*\| \leq \|x_n - x^*\|. 
\end{align*}
\]

By Lemma 10, we have $x^* = Q^M x^*$. It follows from (42) that

\[
\|
\begin{align*}
    y_n - x^* & = \|G_n^M u_n - Q^M x^*\| \leq \|u_n - x^*\| \leq \|x_n - x^*\|.
\end{align*}
\]

Set

\[
\begin{align*}
    z_n & := P_{X} [\alpha_n y V x_n + (I - \alpha_n \mu F) T (\mu_n) y_n], \\
    \forall n \in N.
\end{align*}
\]

Then, we can rewrite (39) as $x_{n+1} = \beta_n x_n + (1 - \beta_n) z_n$. From Lemma 8 and (43), we have

\[
\begin{align*}
    \|z_n - x^*\| & = \|P_{X} [\alpha_n y V x_n + (I - \alpha_n \mu F) T (\mu_n) y_n] - P_{X} x^*\| \\
    & \leq \alpha_n \|y V x_n - \mu F x^*\| + (1 - \alpha_n \mu F) \|T (\mu_n) y_n - x^*\| \\
    & \leq \alpha_n \|y V x_n - \mu F x^*\| + (1 - \alpha_n \tau) \|T (\mu_n) y_n - x^*\| \\
    & \leq \alpha_n \|y V x_n - \mu F x^*\| + (1 - \alpha_n \tau) \|y V x_n - \mu F x^*\| \\
    & \leq (1 - \alpha_n \tau) \|y V x_n - \mu F x^*\|. 
\end{align*}
\]
It follows from (45) that
\[
\|x_{n+1} - x^*\|
= \|\beta_n (x_n - x^*) + (1 - \beta_n) (x_n - x^*)\|
\leq \beta_n \|x_n - x^*\| + (1 - \beta_n) \|x_n - x^*\|
\leq \beta_n \|x_n - x^*\| + (1 - \beta_n)
\times \left[ \left( 1 - \alpha_n (\tau - \gamma L) \right) \|x_n - x^*\| + \alpha_n \|\nabla x^* - \mu F x^*\| \right]
= \left( 1 - \alpha_n (1 - \beta_n) (\tau - \gamma L) \right) \|x_n - x^*\|
\quad + \alpha_n (1 - \beta_n) (\tau - \gamma L) \left\| \frac{\|\nabla x^* - \mu F x^*\|}{\tau - \gamma L} \right\|
\] (46)

By induction, we have
\[
\|x_n - x^*\| \leq \max \left\{ \|x_1 - x^*\|, \frac{\|\nabla x^* - \mu F x^*\|}{\tau - \gamma L} \right\}, \quad \forall n \geq 1.
\] (47)

Hence, \{x_n\} is bounded, and so are \{V x_n\} and \{(FT(\mu_n)) y_n\}.

Next, we show that
\[
\lim_{n \to \infty} \|x_{n+1} - x_n\| = 0.
\] (48)

Observe that
\[
\lim_{n \to \infty} \|T(\mu_{n+1}) y_n - T(\mu_n) y_n\| = 0.
\] (49)

Indeed,
\[
\|T(\mu_{n+1}) y_n - T(\mu_n) y_n\|
= \sup_{1 \leq i \leq 1} \left| \langle T(\mu_{n+1}) y_n - T(\mu_n) y_n, z \rangle \right|
= \sup_{1 \leq i \leq 1} \left| \langle (\mu_{n+1})_i z - (\mu_n)_i z, T(s) y_n, z \rangle \right|
\leq \|\mu_{n+1} - \mu_n\| \sup_{s \in S} \|T(s) y_n\|.
\] (50)

Since \{y_n\} is bounded and \lim_{n \to \infty} \|\mu_{n+1} - \mu_n\| = 0, then (49) holds. We observe that
\[
\|y_{n+1} - y_n\| = \left\| Q^M u_{n+1} - Q^M u_n \right\|
\leq \|u_{n+1} - u_n\|.
\] (51)

Let \{\omega_n\} be a bounded sequence in C. Now, we show that
\[
\lim_{n \to \infty} \left\| G_N^\kappa \omega_n - G_N^\kappa \omega_n \right\| = 0.
\] (52)

For the previous purpose, put \(D_k^N = S^\kappa(I - r_k \Psi_k),\) and we first show that
\[
\lim_{n \to \infty} \left\| D_{n+1}^N - D_n^N \right\| = 0, \quad \forall k \in \{1,2,\ldots,N\}.
\] (53)

In fact, since \(D_k^N \omega_n \in GMEP(\Theta_k, \varphi_k, \Psi_k)\) and \(D_{n+1}^N \omega_n \in GMEP(\Theta_k, \varphi_k, \Psi_k),\) we have
\[
\Theta_k \left( D_k^N \omega_n, y \right) + \varphi_k (y) - \varphi_k (D_k^N \omega_n)
+ \langle \Psi_k \omega_n, y - D_k^N \omega_n \rangle
+ \frac{1}{r_{k,n}} \left( y - D_k^N \omega_n, D_k^N \omega_n - \omega_n \right) \geq 0,
\forall y \in C,
\] (54)

\[
\Theta_k \left( D_{n+1}^N \omega_n, y \right) + \varphi_k (y) - \varphi_k (D_{n+1}^N \omega_n)
+ \langle \Psi_k \omega_n, y - D_{n+1}^N \omega_n \rangle
+ \frac{1}{r_{k,n+1}} \left( y - D_{n+1}^N \omega_n, D_{n+1}^N \omega_n - \omega_n \right) \geq 0,
\forall y \in C.
\] (55)

Substituting \(y = D_{n+1}^N \omega_n\) in (54) and \(y = D_k^N \omega_n\) in (55), then add these two inequalities, and using (A2), we obtain
\[
\left( D_{n+1}^N \omega_n - D_n^N \omega_n, \frac{1}{r_{k,n}} (D_k^N \omega_n - \omega_n) \right)
- \frac{1}{r_{k,n+1}} (D_{n+1}^N \omega_n - \omega_n) \geq 0.
\] (56)

Hence,
\[
\left( D_{n+1}^N \omega_n - D_n^N \omega_n, D_k^N \omega_n - D_{n+1}^N \omega_n \right)
- \omega_n - \frac{r_{k,n}}{r_{k,n+1}} (D_{n+1}^N \omega_n - \omega_n) \geq 0;
\] (57)

we derive from (57) that
\[
\left\| D_{n+1}^N \omega_n - D_n^N \omega_n \right\|^2
\leq \left( D_{n+1}^N \omega_n - D_n^N \omega_n, \frac{1}{r_{k,n}} (D_k^N \omega_n - \omega_n) \right)
- \frac{r_{k,n}}{r_{k,n+1}} \left\| D_k^N \omega_n - \omega_n \right\|,
\] (58)

which implies that
\[
\left\| D_{n+1}^N \omega_n - D_k^N \omega_n \right\| \leq \left( D_{n+1}^N \omega_n - D_k^N \omega_n, \frac{1}{r_{k,n+1}} (D_k^N \omega_n - \omega_n) \right),
\] (59)
Noticing that condition (C3) implies that (53) holds, from the definition of $G_n^N$ and the nonexpansiveness of $D_n^j$, we have

$$
\|G_n^N \omega_n - G_{n+1}^N \omega_n\| \\
= \|D_n^N G_n^N \omega_n - D_{n+1}^N G_{n+1}^N \omega_n\| \\
\leq \|D_n^N G_n^N \omega_n - D_{n+1}^N G_{n+1}^N \omega_n\| \\
+ \|D_{n+1}^N G_{n+1}^N \omega_n - D_{n+1}^N G_{n+1}^N \omega_n\| \\
\leq \|D_n^N G_n^N \omega_n - D_{n+1}^N G_{n+1}^N \omega_n\| \\
+ \|G_n^N \omega_n - G_{n+1}^N \omega_n\| \\
\leq \|D_n^N G_n^N \omega_n - D_{n+1}^N G_{n+1}^N \omega_n\| \\
+ \|D_n^N G_n^N \omega_n - D_{n+1}^N G_{n+1}^N \omega_n\| \\
\leq \|D_n^N G_n^N \omega_n - D_{n+1}^N G_{n+1}^N \omega_n\| \\
+ \|P_n^N G_n^N \omega_n - D_{n+1}^N G_{n+1}^N \omega_n\| \\
+ \|P_n^N G_n^N \omega_n - D_{n+1}^N G_{n+1}^N \omega_n\| \\
+ \cdots \\
+ \|D_n^2 \omega_n - D_{n+1}^2 \omega_n\| + \|D_n^1 \omega_n - D_{n+1}^1 \omega_n\|,
$$

for which (52) follows by (53). Since $u_n = G_n^N x_n$ and $u_{n+1} = G_{n+1}^N x_{n+1}$, we have

$$
\|u_n - u_{n+1}\| \\
= \|G_n^N x_n - G_{n+1}^N x_{n+1}\| \\
\leq \|G_n^N x_n - G_{n+1}^N x_n\| + \|G_{n+1}^N x_n - G_{n+1}^N x_{n+1}\| \\
\leq \|G_n^N x_n - G_{n+1}^N x_n\| + \|G_{n+1}^N x_n - G_{n+1}^N x_{n+1}\|.
$$

Put a constant $M_1 > 0$ such that

$$
M_1 = \sup_{n \geq 1} \|y\| Vx_n \| + \mu\|FT(t_{n+1})y_{n+1}\|,
$$

From definition of $[z_n]$, we note that

$$
\|z_{n+1} - z_n\| \\
= \|P_C [\alpha_{n+1} yVx_{n+1} + (I - \alpha_{n+1} \mu F T) (\mu_{n+1}) y_{n+1}] \\
- P_C [\alpha_n yVx_n + (I - \alpha_n \mu F T) (\mu_n) y_n]\| \\
\leq \alpha_{n+1}\|yVx_{n+1} - \mu FT(\mu_{n+1}) y_{n+1}\| \\
+ \alpha_n\|yVx_n - \mu FT(\mu_n) y_n\| \\
+ \|T(\mu_{n+1}) y_{n+1} - T(\mu_n) y_n\| \\
\leq \alpha_{n+1} \|yVx_{n+1} - \mu FT(\mu_{n+1}) y_{n+1}\| \\
+ \alpha_n\|yVx_n - \mu FT(\mu_n) y_n\| \\
+ \|T(\mu_{n+1}) y_{n+1} - T(\mu_n) y_n\|.
$$

It follows from (51), (61), and (63) that

$$
\|z_{n+1} - z_n\| \leq (\alpha_{n+1} + \alpha_n) M_1 + \|G_n^N x_n - G_{n+1}^N x_{n+1}\| \\
+ \|x_{n+1} - x_n\| + \|T(\mu_{n+1}) y_{n+1} - T(\mu_n) y_n\|.
$$

From condition (C1), (49), and (52), we have

$$
\lim_{n \to \infty} (\|z_{n+1} - z_n\| - \|x_{n+1} - x_n\|) \leq 0.
$$

Hence, by Lemma 5, we obtain

$$
\lim_{n \to \infty} \|z_n - x_n\| = 0.
$$

Consequently,

$$
\lim_{n \to \infty} \|x_{n+1} - x_n\| = \lim_{n \to \infty} (1 - \beta_n) \|z_n - x_n\| = 0.
$$

From condition (C1), we have

$$
\|z_n - T(\mu_n) y_n\| \\
= \|P_C [\alpha_n yVx_n + (I - \alpha_n \mu F T) T(\mu_n) y_n] - P_C T(\mu_n) y_n\| \\
\leq \alpha_n \|yVx_n - \mu FT(\mu_n) y_n\| \to 0 \quad \text{as} \quad n \to \infty.
$$

From (66) and (68), we have

$$
\|x_n - T(\mu_n) y_n\| \leq \|x_n - z_n\| \\
+ \|z_n - T(\mu_n) y_n\| \to 0 \quad \text{as} \quad n \to \infty.
$$

Set $z_n = P_C v_n$, where $v_n = \alpha_n yVx_n + (I - \alpha_n \mu F T) T(\mu_n) y_n$. From (25), we have

$$
\|z_n - x^*\| = \langle v_n - x^*, z_n - x^*\rangle \\
+ \langle P_C v_n - v_n, P_C v_n - x^*\rangle \\
\leq \langle v_n - x^*, z_n - x^*\rangle \\
= \alpha_n \langle yVx_n - \mu F x^*, z_n - x^*\rangle \\
+ \langle (I - \alpha_n \mu F) (T(\mu_n) y_n - x^*), z_n - x^*\rangle.
$$
From (72) and (75), we have
\[
\|x_{n+1} - x^*\|^2 \\
\leq \beta_n \|x_n - x^*\|^2 + (1 - \beta_n) \|G_{k}^{k-1} x_n - \Psi_k x^*\|^2 \\
+ 2\alpha_n (1 - \beta_n) M_2,
\]
which in turn implies that
\[
(1 - \beta_n) r_{k,n} (2\mu_k - r_{k,n}) \|\Psi_k G_{k}^{k-1} x_n - \Psi_k x^*\|^2 \\
\leq \|x_n - x^*\|^2 - \|x_{n+1} - x^*\|^2 + 2\alpha_n (1 - \beta_n) M_2 \\
\leq \left(\|x_n - x^*\|^2 + \|x_{n+1} - x^*\|^2\right) \|x_{n+1} - x_n\| \\
+ 2\alpha_n (1 - \beta_n) M_2.
\]
Since \(\lim_{n \to \infty} \inf_{k \geq 1} (1 - \beta_k) > 0\), \(0 < r_{k,n} < 2\mu_k\), for all \(k \in \{1, 2, \ldots, N\}\), from (C1) and (67), we obtain that
\[
\lim_{n \to \infty} \|\Psi_k G_{k}^{k-1} x_n - \Psi_k x^*\|^2 = 0, \quad \forall k \in \{1, 2, \ldots, N\}.
\]
which in turn implies that
\begin{align*}
\|G_n^{-1}x_n - x^*\|^2 &\leq \|G_n^{-1}x_n - x^*\|^2 \\
- &\left(\|G_n^{-1}x_n - G_n^k x_n - r_{k,n}(\Psi_k G_n^{-1}x_n - \Psi_k x^*)\|^2 + 2\beta_n (1 - \beta_n) M_2\right),
\end{align*}
(80)

Substituting (81) into (76), we have
\begin{align*}
\|G_n^{-1}x_n - x^*\|^2 &\leq \|G_n^{-1}x_n - x^*\|^2 \\
- &\left(\|G_n^{-1}x_n - G_n^k x_n - r_{k,n}(\Psi_k G_n^{-1}x_n - \Psi_k x^*)\|^2 + 2\beta_n (1 - \beta_n) M_2\right),
\end{align*}
(81)

which in turn implies that
\begin{align*}
&\|G_n^{-1}x_n - x^*\|^2 \\
&\leq \left(\|G_n^{-1}x_n - x^*\|^2 + (1 - \beta_n) \right) \\
&\times \left(\|G_n^{-1}x_n - x^*\|^2 - \|G_n^{-1}x_n - G_n^k x_n\|^2 + 2r_{k,n}\|G_n^{-1}x_n - G_n^k x_n\|\|\Psi_k G_n^{-1}x_n - \Psi_k x^*\| \right) \\
&\quad + 2a_n (1 - \beta_n) M_2,
\end{align*}
(82)

which in turn implies that
\begin{align*}
&\|G_n^{-1}x_n - x^*\|^2 \\
&\leq \left(\|G_n^{-1}x_n - x^*\|^2 + (1 - \beta_n) \right) \\
&\times \left(\|G_n^{-1}x_n - x^*\|^2 - \|G_n^{-1}x_n - G_n^k x_n\|^2 + 2r_{k,n}\|G_n^{-1}x_n - G_n^k x_n\|\|\Psi_k G_n^{-1}x_n - \Psi_k x^*\| \right) \\
&\quad + 2a_n (1 - \beta_n) M_2.
\end{align*}
(83)

Since \(\lim_{n \to \infty} (1 - \beta_n) > 0\), from (C1), (67), and (79), we obtain that (73) holds. Consequently,
\begin{align*}
\|x_n - u_n\| &\leq \|G_n^0 - G_n^N x_n\| \\
&\leq \|G_n^0 x_n - G_n^1 x_n\| + \|G_n^1 x_n - G_n^2 x_n\| + \cdots \\
&\quad + \|G_n^N - x_n - G_n^N x_n\| \\
&\rightarrow 0 \quad \text{as } n \to \infty.
\end{align*}
(84)

Next, we show that
\begin{align*}
\lim_{n \to \infty} \|A_i Q^{-1} u_n - A_i Q^{-1} x^*\| = 0, \quad \forall i \in \{1, 2, \ldots, M\}.
\end{align*}
(85)

From (28), we have
\begin{align*}
&\|Q^M u_n - Q^M x^*\|^2 \\
&= \|S_{\lambda, A}^M (I - \lambda A M) Q^{-1} u_n - S_{\lambda, A}^M (I - \lambda A M) Q^{-1} x^*\|^2 \\
&\leq \|A M Q^{-1} u_n - A M Q^{-1} x^*\|^2 + \lambda M (\lambda M - 2a_M).
\end{align*}
(86)

By induction, we have
\begin{align*}
&\|Q^M u_n - Q^M x^*\|^2 \\
&\leq \|u_n - x^*\|^2 + \sum_{i=1}^{M} \lambda_i (\lambda_i - 2a_i) \|A_i Q^{-1} u_n - A_i Q^{-1} x^*\|^2 \\
&\leq \|x_n - x^*\|^2 + \sum_{i=1}^{M} \lambda_i (\lambda_i - 2a_i) \|A_i Q^{-1} u_n - A_i Q^{-1} x^*\|^2.
\end{align*}
(87)

From (72) and (75), we have
\begin{align*}
&\|x_{n+1} - x^*\|^2 \leq \beta_n \|x_n - x^*\|^2 + (1 - \beta_n) \|Q^M u_n - Q^M x^*\|^2 \\
&\quad + 2a_n (1 - \beta_n) M_2.
\end{align*}
(88)
Substituting (87) into (88), we have
\[
\|x_{n+1} - x^*\|^2 \\
\leq \beta_n \|x_n - x^*\|^2 + (1 - \beta_n) \\
\times \left\{ \|x_n - x^*\|^2 + \sum_{i=1}^{M} (\lambda_i - 2\alpha_i) \|A_i Q^{-1} u_n - A_i Q^{-1} x^*\|^2 \right\} \\
+ 2\alpha_n (1 - \beta_n) M_2 \\
= \|x_n - x^*\|^2 + (1 - \beta_n) \sum_{i=1}^{M} (\lambda_i - 2\alpha_i) \|A_i Q^{-1} u_n - A_i Q^{-1} x^*\|^2 \\
+ 2\alpha_n (1 - \beta_n) M_2,
\]
which in turn implies that
\[
(1 - \beta_n) \sum_{i=1}^{M} (2\alpha_i - \lambda_i) \|A_i Q^{-1} u_n - A_i Q^{-1} x^*\|^2 \\
\leq \|x_n - x^*\|^2 - \|x_{n+1} - x^*\|^2 + 2\alpha_n (1 - \beta_n) M_2 \\
\leq \|(x_n - x^* + \|x_{n+1} - x^*\|)\|x_{n+1} - x_n\| \\
+ 2\alpha_n (1 - \beta_n) M_2.
\]
Since \( \lim \inf_{n \to \infty} (1 - \beta_n) > 0 \), from (C1) and (67), we obtain that (85) holds.

On the other hand, from (24) and (26), we have
\[
\|Q^M u_n - Q^M x^*\|^2 \\
\leq \frac{1}{2} \left( \|Q^{M-1} u_n - Q^{M-1} x^*\|^2 + \|Q^M u_n - Q^M x^*\|^2 \right) \\
- \|Q^{M-1} u_n - Q^M u_n + Q^M x^* - Q^{M-1} x^*\|^2 \\
- \lambda_M \left( A_M Q^{M-1} u_n - A_M Q^{M-1} x^* \right)^2, \\
\]
which in turn implies that
\[
\|Q^M u_n - Q^M x^*\|^2 \\
\leq \|Q^{M-1} u_n - Q^{M-1} x^*\|^2 \\
- \|Q^{M-1} u_n - Q^M u_n + Q^M x^* - Q^{M-1} x^*\|^2 \\
- \lambda_M \left( A_M Q^{M-1} u_n - A_M Q^{M-1} x^* \right)^2 \\
+ \|Q^{M-1} u_n - Q^M u_n + Q^M x^* - Q^{M-1} x^*\|^2 \\
+ 2\lambda_M \left( Q^{M-1} u_n - Q^M u_n + Q^M x^* - Q^{M-1} x^* \right) \\
\times \left( A_M Q^{M-1} u_n - A_M Q^{M-1} x^* \right).
\]
By induction, we have
\[
\|Q^M u_n - Q^M x^*\|^2 \\
\leq \|u_n - x^*\|^2 \\
- \sum_{i=1}^{M} \|Q^{i-1} u_n - Q^i u_n + Q^i x^* - Q^{i-1} x^*\|^2 \\
+ \sum_{i=1}^{N} 2\lambda_i \|Q^{i-1} u_n - Q^i u_n + Q^i x^* - Q^{i-1} x^*\| \\
\times \|A_i Q^{i-1} u_n - A_i Q^{i-1} x^*\|^2 \\
\leq \|x_n - x^*\|^2 - \sum_{i=1}^{N} \|Q^{i-1} u_n - Q^i u_n + Q^i x^* - Q^{i-1} x^*\|^2 \\
+ \sum_{i=1}^{N} 2\lambda_i \|Q^{i-1} u_n - Q^i u_n + Q^i x^* - Q^{i-1} x^*\| \\
\times \|A_i Q^{i-1} u_n - A_i Q^{i-1} x^*\|^2.
\]
Substituting (93) into (88), we have
\[\|x_{n+1} - x^*\|^2 \leq \beta_n \|x_n - x^*\|^2 + (1 - \beta_n) \times \left\{ \|x_n - x^*\|^2 - \sum_{i=1}^M \|Q^{-1}u_n - Q^i x_n + Q'^i x^* - Q^{-1} x^*\|^2 \right\} \]
\[+ \sum_{i=1}^M 2\lambda_i \|Q^{-1}u_n - Q^i x_n + Q'^i x^* - Q^{-1} x^*\| \times \|A_i Q^{-1}u_n - A_i Q^{-1} x^*\| \]
\[+ 2\alpha_n (1 - \beta_n) M_2 \]
\[\leq \|x_n - x^*\|^2 - (1 - \beta_n) \sum_{i=1}^M \|Q^{-1}u_n - Q^i x_n + Q'^i x^* - Q^{-1} x^*\|^2 \]
\[+ (1 - \beta_n) \sum_{i=1}^M 2\lambda_i \|Q^{-1}u_n - Q^i x_n + Q'^i x^* - Q^{-1} x^*\| \times \|A_i Q^{-1}u_n - A_i Q^{-1} x^*\| \]
\[+ 2\alpha_n (1 - \beta_n) M_2 \]
\[
(94)
\]
which in turn implies that
\[
(1 - \beta_n) \sum_{i=1}^M \|Q^{-1}u_n - Q^i x_n + Q'^i x^* - Q^{-1} x^*\|^2 \]
\[\leq \|x_n - x^*\|^2 - \|x_{n+1} - x^*\|^2 \]
\[+ (1 - \beta_n) \sum_{i=1}^M 2\lambda_i \|Q^{-1}u_n - Q^i x_n + Q'^i x^* - Q^{-1} x^*\| \times \|A_i Q^{-1}u_n - A_i Q^{-1} x^*\| \]
\[+ 2\alpha_n (1 - \beta_n) M_2 \]
\[\leq (\|x_n - x^*\|^2 + \|x_{n+1} - x^*\|^2) \|x_{n+1} - x_n\| \]
\[+ (1 - \beta_n) \sum_{i=1}^M 2\lambda_i \|Q^{-1}u_n - Q^i x_n + Q'^i x^* - Q^{-1} x^*\| \times \|A_i Q^{-1}u_n - A_i Q^{-1} x^*\| \]
\[+ 2\alpha_n (1 - \beta_n) M_2 \]
\[
(95)
\]
Since \(\lim_{n \to \infty} (1 - \beta_n) > 0\), from (C1), (67), and (85), we obtain that
\[
\lim_{n \to \infty} \|Q^{-1}u_n - Q'u_n + Q'^ix^* - Q^{-1}x^*\| = 0,
\]
\[\forall i \in \{1, 2, \ldots, M\}.
\]
Consequently,
\[\|u_n - y_n\| = \|Q^0u_n - Q^My_n\| \leq \sum_{i=1}^M \|Q^{-1}u_n - Q'u_n + Q'i x^* - Q^{-1}x^*\\]
\[\rightarrow 0 \text{ as } n \to \infty.
\]
It follows from (84) and (97) that
\[\|x_n - y_n\| \leq \|x_n - u_n\| + \|u_n - y_n\| \rightarrow 0 \text{ as } n \to \infty.
\]
Next, we show that
\[\lim_{n \to \infty} \|x_n - T(t)x_n\| = 0, \quad \forall t \in S.
\]
Put
\[M^* = \max \left\{ \|x_1 - x^*\|, \frac{1}{\tau - \gamma L} \|\gamma y x^* - \mu F x^*\| \right\}.
\]
Set \(D = \{ y \in C : \|y - x^*\| \leq M^* \}\). We remark that \(D\) is nonempty, bounded, closed, and convex set, and \(\{x_n\}, \{y_n\}\), and \(\{z_n\}\) are in \(D\). We will show that
\[\limsup_{n \to \infty} \sup_{y \in D} \|T(\mu_n)y - T(t)T(\mu_n)y\| = 0, \quad \forall t \in S.
\]
To complete our proof, we follow the proof line as in [31] (see also [23, 32, 33]). Let \(\varepsilon > 0\). By [34, Theorem 1.2], there exists \(\delta > 0\) such that
\[\mathcal{C} F_0 (T(t); D) + B_\delta \subset F_\varepsilon (T(t); D), \quad \forall t \in S.
\]
Also by [34, Corollary 1.1], there exists a natural number \(N\) such that
\[
\left\| \frac{1}{N+1} \sum_{t'=0}^N T(t')y - T(t) \left( \frac{1}{N+1} \sum_{t'=0}^N T(t')y \right) \right\| \leq \delta,
\]
for all $t, s \in S$ and $y \in D$. Let $t \in S$. Since $\{\mu_n\}$ is strongly left regular, there exists $n_0 \in \mathbb{N}$ such that \( \|\mu_n - \mu_n^p\| \leq \delta \|(M^* + \|w\|) \) for all $n \geq n_0$ and $i = 1, 2, \ldots, N$. Then, we have

\[
\sup_{y \in D} \left\| T(\mu_n) y - \left( \frac{1}{N + 1} \sum_{i=0}^{N} T(i') s \right) y d\mu_n(s) \right\|
\]

\[
= \sup_{y \in D} \sup_{|z|=1} \langle T(\mu_n) y, z \rangle - \left( \frac{1}{N + 1} \sum_{i=0}^{N} T(i') s \right) y \mu_n(s), z \rangle \sup_{y \in D} \sup_{|z|=1} \left( \frac{1}{N + 1} \sum_{i=0}^{N} T(i') s \right) y \mu_n(s), z \rangle
\]

\[
= \sup_{y \in D} \sup_{|z|=1} \left( \frac{1}{N + 1} \sum_{i=0}^{N} \langle T(i') s \rangle y \mu_n(s), z \rangle \right)
\]

\[
\leq \frac{1}{N + 1} \sum_{i=0}^{N} \sup_{y \in D} \sup_{|z|=1} \left( \langle T(i') s \rangle y \mu_n(s), z \rangle \right)
\]

\[
\leq \max_{i=1,2,\ldots,N} \left\| \mu_n - \mu_n^p \right\| (M^* + \|w\|) \leq \delta, \quad \forall n \geq n_0.
\]

(104)

On the other hand, by Lemma 2, we have

\[
\int \frac{1}{N + 1} \sum_{i=0}^{N} T(i') s \right) y d\mu_n(s) \in \overline{co} \left\{ \frac{1}{N + 1} \sum_{i=0}^{N} T(i') s \right) T(s) y : s \in S \}. \tag{105}
\]

Combining (103)–(105), we have

\[
T(\mu_n) y = \frac{1}{N + 1} \sum_{i=0}^{N} T(i') s \right) y d\mu_n(s)
\]

\[
+ \left( T(\mu_n) y - \frac{1}{N + 1} \sum_{i=0}^{N} T(i') s \right) y d\mu_n(s) \right)
\]

\[
\in \overline{co} \left\{ \frac{1}{N + 1} \sum_{i=0}^{N} T(i') s \right) T(s) y : s \in S \} + B_\delta
\]

\[
\subset \overline{co} F_\delta (T(t) ; D) + B_\delta.
\]

(106)

for all $y \in D$ and $n \geq n_0$. Therefore,

\[
\lim \sup_{n \to \infty} \sup_{y \in D} \| T(\mu_n) y - T(t) T(\mu_n) y \| \leq \epsilon.
\]

(107)

Since $\epsilon > 0$ is arbitrary, we obtain that (101) holds. Let $t \in S$ and $\epsilon > 0$. Then, there exists $\delta > 0$ satisfying (102). From (101) and condition (C2), there exists $a, b \in (0, 1)$ such that $0 < a \leq \beta_n \leq b < 1$ and $T(\mu_n) y \in F_\delta (T(t) ; D)$ for all $y \in D$. From (69), there exists $k_0 \in \mathbb{N}$ such that $\|x_n - T(\mu_n) y_n\| < \delta/b$ for all $n > k_0$. Then, from (102) and (106), we have

\[
x_{n+1} = \beta_n x_n + (1 - \beta_n) T(\mu_n) y_n
\]

\[
= T(\mu_n) y_n + \beta_n (x_n - T(\mu_n) y_n)
\]

\[
\in F_\delta (T(t) ; D) + B_\delta \subset F_\delta (T(t) ; D),
\]

for all $n > k_0$. Hence, $\lim_{n \to \infty} \|x_n - T(t)x_n\| \leq \epsilon$. Since $\epsilon > 0$ is arbitrary, we obtain that (99) holds.

Next, we show that

\[
\lim_{n \to \infty} \sup_{y \in D} \| yV \bar{x} - \mu F \bar{x}, z_n - \bar{x} \| \leq 0,
\]

(109)

where $\bar{x} = P_Y (I - \mu F + \gamma V) \bar{x}$. To show this, we choose a subsequence $\{y_n\}$ of $\{x_n\}$ such that

\[
\lim_{n \to \infty} \sup_{y \in D} \| yV \bar{x} - \mu F \bar{x}, x_n - \bar{x} \| = \lim_{i \to \infty} \left( yV \bar{x} - \mu F \bar{x}, x_n - \bar{x} \right).
\]

(110)

Since $\{x_n\}$ is bounded, there exists a subsequence $\{x_n\}$ of $\{x_n\}$ such that $x_n \to v$. Now, we show that $v \in F$. 

(i) We first show that $v \in \text{Fix}(\delta)$. From (99), we have $\|x_n - T(t)x_n\| \to 0$ as $n \to \infty$. Then, from Demiclosedness Principle 2.6, we get $v \in \text{Fix}(\delta)$.

(ii) We show that $v \in \text{Fix}(K)$, where $K$ is defined as in Lemma 9. Then, from (97), we have

\[
\|y_n - Ky_n\| = \|Ky_n - Ky_n\| \leq \|y_n - y\| \to 0 \quad \text{as} \quad n \to \infty.
\]

(111)

and from (98), we also have $\|x_n - Kx_n\| \to 0$. By Demiclosedness Principle 2.6, we get $v \in \text{Fix}(K)$.

(iii) We show that $v \in \bigcap_{k=1}^{\infty} \text{GMEP}(\Theta_k, \phi_k, \Psi_k)$. Note that $G_n x_n = \bar{s}(\phi_k \Psi_k, (I - r_{k,n} \phi_k \Psi_k) x_n, x_n)$, for all $k \in \{1, 2, \ldots, N\}$. Then, we have

\[
\Theta_k (G_n x_n, y) + \phi_k (y) - \phi_k (G_n x_n)
\]

\[
+ \langle \Psi_k G_n x_n, y - G_n x_n \rangle
\]

\[
+ \frac{1}{r_{k,n}} \langle y - G_n x_n, G_n x_n - G_n x_n \rangle \geq 0.
\]

(112)

Replacing $n$ by $n_i$ in the last inequality and using (A2), we have

\[
\phi_k (y) - \phi_k (G_n x_n) + \langle \Psi_k G_n x_n, y - G_n x_n \rangle
\]

\[
+ \frac{1}{r_{k,n}} \langle y - G_n x_n, G_n x_n - G_n x_n \rangle \geq \Theta_k (y, G_n x_n).
\]

(113)
Let \( y_t = ty + (1 - t)v \) for all \( t \in (0, 1) \) and \( y \in C \). This implies that \( y_t \in C \). Then, we have
\[
\langle y_t - G_n^{k} x_n, \Psi_k y_t \rangle \\
\geq \varphi_k \left( G_n^{k} x_n - \varphi_k (y_t) + \langle y_t - G_n^{k} x_n, \Psi_k y_t \rangle \\
- \langle y_t - G_n^{k} x_n, G_n^{k} x_n - G_n^{k-1} x_n \rangle \right)/r_{k,n} + \Theta_k \left( y_t, G_n^{k} x_n \right) \\
= \varphi_k \left( G_n^{k} x_n - \varphi_k (y_t) + \langle y_t - G_n^{k} x_n, \Psi_k y_t - \Psi_k G_n^{k} x_n \rangle \\
+ \langle y_t - G_n^{k} x_n, \Psi_k G_n^{k} x_n - \Psi_k G_n^{k-1} x_n \rangle \right)/r_{k,n} \\
- \langle y_t - G_n^{k} x_n, G_n^{k} x_n - G_n^{k-1} x_n \rangle \right)/r_{k,n} + \Theta_k \left( y_t, G_n^{k} x_n \right).
\]
(114)

From (73), we have \( \| \Psi_k G_n^{k} x_n - \Psi_k G_n^{k-1} x_n \| \to 0 \) as \( i \to \infty \). Furthermore, by the monotonicity of \( \Psi_k \), we obtain \( \langle y_t - G_n^{k} x_n, \Psi_k y_t - \Psi_k G_n^{k} x_n \rangle \geq 0 \). Then, from (A4), we obtain
\[
\langle y_t - v, \Psi_k y_t \rangle \geq \varphi_k (v) - \varphi_k (y_t) + \Theta_k \left( y_t, v \right).
\]
(115)

Using (A1), (A4), and (115), we also obtain
\[
0 = \Theta_k \left( y_t, y_t \right) + \varphi_k (y_t) - \varphi_k (y_t) \\
\leq t \Theta_k \left( y_t, y \right) + (1 - t) \Theta_k \left( y, v \right) + (1 - t) \varphi_k (v) - \varphi_k (y_t) \\
\leq t \Theta_k \left( y_t, y \right) + \varphi_k (y) - \varphi_k (y_t) + (1 - t) \left( \varphi_k (v) - \varphi_k (y_t) \right) \\
= t \Theta_k \left( y_t, y \right) + \varphi_k (y) - \varphi_k (y_t) + (1 - t) \left( y - v, \Psi_k y_t \right),
\]
(116)

and, hence,
\[
0 \leq \Theta_k \left( y_t, y \right) + \varphi_k (y) - \varphi_k (y_t) + (1 - t) \left( y - v, \Psi_k y_t \right).
\]
(117)

Letting \( t \to 0 \) and using (A3), we have, for each \( y \in C \),
\[
0 \leq \Theta_k \left( v, y \right) + \varphi_k (y) - \varphi_k (v) + \langle y - v, \Psi_k v \rangle.
\]
(118)

This implies that \( v \in \text{GMEP}(\Theta_k, \varphi_k, \Psi_k) \). Hence, \( v \in \bigcap_{k=1}^{N} \text{GMEP}(\Theta_k, \varphi_k, \Psi_k) \). Therefore,
\[
v \in \mathcal{F} := \bigcap_{k=1}^{N} \text{GMEP}(\Theta_k, \varphi_k, \Psi_k) \cap \text{Fix}(K) \cap \text{Fix}(\mathcal{S}).
\]
(119)

From (66) and (110), we obtain
\[
\lim \sup_{n \to \infty} \langle yV\bar{x} - uF\bar{x}, z_n - \bar{x} \rangle = \lim \sup_{n \to \infty} \langle yV\bar{x} - uF\bar{x}, x_n - \bar{x} \rangle \\
= \lim_{t \to \infty} \langle yV\bar{x} - uF\bar{x}, x_n - \bar{x} \rangle \\
= \langle yV\bar{x} - uF\bar{x}, v - \bar{x} \rangle \leq 0.
\]
(120)

Finally, we show that \( x_n \to \bar{x} \) as \( n \to \infty \). Notice that \( z_n = P_{C} y_n \), where \( y_n = \alpha_n yVx_n + (I - \alpha_n uF)(\mu_n) y_n \). Then, from (25), we have
\[
\| z_n - \bar{x} \|^2 = \langle v_n - \bar{x}, z_n - \bar{x} \rangle + \langle P_{C} y - v, P_{C} y - \bar{x} \rangle \\
\leq \langle v_n - \bar{x}, z_n - \bar{x} \rangle \\
= \alpha_n \langle yV\bar{x} - uF\bar{x}, z_n - \bar{x} \rangle \\
+ \alpha_n \langle yV\bar{x} - uF\bar{x}, z_n - \bar{x} \rangle \\
+ \langle (I - \alpha_n uF) (T (\mu_n) y_n - \bar{x}) , z_n - \bar{x} \rangle \\
\leq (1 - \alpha_n (1 - \beta_n) (\tau - \gamma L)) \| x_n - \bar{x} \|^2 \\
+ \alpha_n \langle yV\bar{x} - uF\bar{x}, z_n - \bar{x} \rangle.
\]
(121)

It follows from (121) that
\[
\| x_{n+1} - \bar{x} \|^2 \leq \beta_n \| x_n - \bar{x} \|^2 + (1 - \beta_n) \| x_n - \bar{x} \|^2 \\
\leq \beta_n \| x_n - \bar{x} \|^2 + (1 - \beta_n) \\
\times \left\{ (1 - \alpha_n (1 - \beta_n) (\tau - \gamma L)) \| x_n - \bar{x} \|^2 \\
+ \alpha_n \langle yV\bar{x} - uF\bar{x}, z_n - \bar{x} \rangle \right\} \\
\leq (1 - \alpha_n (1 - \beta_n) (\tau - \gamma L)) \| x_n - \bar{x} \|^2 \\
+ \alpha_n \langle yV\bar{x} - uF\bar{x}, z_n - \bar{x} \rangle.
\]
(122)

Put \( \sigma_n := \alpha_n (1 - \beta_n) (\tau - \gamma L) \) and \( \delta_n := \alpha_n (1 - \beta_n) \langle yV\bar{x} - uF\bar{x}, z_n - \bar{x} \rangle \). Then, (122) reduces to formula
\[
\| x_{n+1} - \bar{x} \|^2 \leq (1 - \sigma_n) \| x_n - \bar{x} \|^2 + \delta_n.
\]
(123)

It is easily seen that \( \sum_{n=1}^{\infty} \sigma_n = \infty \), and (using (120))
\[
\lim \sup_{n \to \infty} \delta_n = \frac{1}{\tau - \gamma L} \lim \sup_{n \to \infty} \langle yV\bar{x} - uF\bar{x}, z_n - \bar{x} \rangle \leq 0.
\]
(124)

Hence, by Lemma 7, we conclude that \( x_n \to \bar{x} \) as \( n \to \infty \). This completes the proof.

Using the results proved in [35] (see also [32]), we obtain the following results.

**Corollary 12.** Let \( C, H, \Theta_k, \varphi_k, \Psi_k, A_k, F, \) and \( V \) be the same as in Theorem 11. Let \( S \) and \( T \) be nonexpansive mappings on \( C \) with \( ST = TS \). Assume that \( \mathcal{F} := \text{Fix}(S) \cap \text{Fix}(T) \cap \bigcap_{k=1}^{N} \text{GMEP}(\Theta_k, \varphi_k, \Psi_k) \cap \text{Fix}(K) \neq \emptyset \), where \( K \) is defined as in
Lemma 9. Let \( \{\alpha_n\} \), \( \{\beta_n\} \), and \( \{r_{k,n}\}^N_{k=1} \) be sequences satisfying (C1)–(C3). Then, the sequence \( \{x_n\} \) defined by
\[
{x_n} = S^{(\Omega, \varphi)}_{\{r_{k,n}\}^N_{k=1}} \left( I - r_{N,n} \Psi_N \right) S^{(\Omega, \varphi)}_{\{r_{k,n}\}^N_{k=1}} \cdot (\Omega, \varphi) \cdot x_n,
\]
\[
\times \left( I - r_{N-1,n} \Psi_{N-1} \right) \cdots I - r_{1,n} \Psi_1 \right) x_n,
\]
\[
y_n = \sum_{j=0}^{N-1} \left( I - \lambda_j A_{M-1} \right) y_n,
\]
\[
x_{n+1} = \beta_n x_n + (1 - \beta_n)
\]
\[
\times P \left[ a_n y V x_n + (I - a_n \mu F) \sum_{j=0}^{N-1} \int_0^{\infty} (I - \alpha_j) T \left( s \right) y_n ds \right],
\]
converges strongly to \( \bar{x} \in \mathcal{F} \), where \( \bar{x} \) solves uniquely the variational inequality (40).

Corollary 13. Let \( C, H, \Theta, \varphi, \Psi, A, F, \) and \( V \) be the same as in Theorem II. Let \( \delta \) be a strongly continuous nonexpansive semigroup on \( C \). Assume that \( \Omega = \text{Fix}(\delta) \cap \bigcap_{n=1}^{\infty} \text{GMEP}(\Theta, \varphi, \Psi) \cap K \neq \emptyset \), where \( K \) is defined as in Lemma 9. Let \( \{\alpha_n\} \), \( \{\beta_n\} \), and \( \{r_{k,n}\}^N_{k=1} \) be sequences satisfying (C1)–(C3). Then, the sequence \( \{x_n\} \) defined by
\[
{x_n} = S^{(\Omega, \varphi)}_{\{r_{k,n}\}^N_{k=1}} \left( I - r_{N,n} \Psi_N \right) S^{(\Omega, \varphi)}_{\{r_{k,n}\}^N_{k=1}} \cdot (\Omega, \varphi) \cdot x_n,
\]
\[
\times \left( I - r_{N-1,n} \Psi_{N-1} \right) \cdots I - r_{1,n} \Psi_1 \right) x_n,
\]
\[
y_n = \sum_{j=0}^{N-1} \left( I - \lambda_j A_{M-1} \right) y_n,
\]
\[
x_{n+1} = \beta_n x_n + (1 - \beta_n)
\]
\[
\times P \left[ a_n y V x_n + (I - a_n \mu F) \sum_{j=0}^{N-1} \int_0^{\infty} (I - \alpha_j) T \left( s \right) y_n ds \right],
\]
converges strongly to \( \bar{x} \in \mathcal{F} \), where \( \bar{x} \) solves uniquely the variational inequality (40).

Corollary 14. Let \( C, H, \Theta, \varphi, \Psi, A, F, \) and \( V \) be the same as in Theorem II. Let \( \delta \) be a strongly continuous nonexpansive semigroup on \( C \). Assume that \( \Omega = \text{Fix}(\delta) \cap \bigcap_{n=1}^{\infty} \text{GMEP}(\Theta, \varphi, \Psi) \cap K \neq \emptyset \), where \( K \) is defined as in Lemma 9. Let \( \{\alpha_n\} \), \( \{\beta_n\} \), and \( \{r_{k,n}\}^N_{k=1} \) be sequences satisfying (C1)–(C3). Then, the sequence \( \{x_n\} \) defined by
\[
{x_n} = S^{(\Omega, \varphi)}_{\{r_{k,n}\}^N_{k=1}} \left( I - r_{N,n} \Psi_N \right) S^{(\Omega, \varphi)}_{\{r_{k,n}\}^N_{k=1}} \cdot (\Omega, \varphi) \cdot x_n,
\]
\[
\times \left( I - r_{N-1,n} \Psi_{N-1} \right) \cdots I - r_{1,n} \Psi_1 \right) x_n,
\]
\[
y_n = \sum_{j=0}^{N-1} \left( I - \lambda_j A_{M-1} \right) y_n,
\]
\[
x_{n+1} = \beta_n x_n + (1 - \beta_n)
\]
\[
\times P \left[ a_n y V x_n + (I - a_n \mu F) \sum_{j=0}^{N-1} \int_0^{\infty} (I - \alpha_j) T \left( s \right) y_n ds \right],
\]
where \( \{\alpha_n\} \) is a decreasing sequence in \( (0, \infty) \) with \( \lim_{n \to \infty} \alpha_n = 0 \), converges strongly to \( \bar{x} \in \Omega \), where \( \bar{x} \) solves uniquely the variational inequality (40).

4. Some Applications

In this section, as applications, we will apply Theorem II to find minimum-norm solutions \( \bar{x} = P_\Omega(0) \) of some variational inequalities. Namely, find a point \( \bar{x} \) which solves uniquely the following quadratic minimization problem:
\[
\|\bar{x}\|^2 = \min_{x \in \Omega} \|x\|^2.
\]
Minimum-norm solutions have been applied widely in several branches of pure and applied sciences, for example, defining the pseudoinverse of a bounded linear operator, signal processing, and many other problems in a convex polyhedron and a hyperplane (see [36, 37]).

Recently, some iterative methods have been studied to find the minimum-norm fixed point of nonexpansive mappings and their generalizations (see, e.g. [38–49] and the references therein).

Using Theorem II and Corollaries 12, 13, and 14, we immediately have the following results, respectively.

Theorem 15. Let \( C \) and \( H \) be the same as in Theorem II. Let \( \delta = \{T(t) : t \in S\} \) be a nonexpansive semigroup on \( C \) such that \( \mathcal{F} = \text{Fix}(\delta) \neq \emptyset \). Let \( \{\alpha_n\} \) and \( \{\beta_n\} \) be sequences satisfying (C1)–(C3). Then, the sequence \( \{x_n\} \) defined by
\[
x_{n+1} = \beta_n x_n + (1 - \beta_n) P \left[ \left( 1 - \alpha_n \right) T \left( \mu_n \right) x_n \right],
\]
converges strongly to \( \bar{x} \in \mathcal{F} \), where \( \bar{x} = P_\mathcal{F}(0) \) is the minimum-norm fixed point of \( \mathcal{F} \), where \( \bar{x} \) solves uniquely the quadratic minimization problem (128).

Theorem 16. Let \( C \) and \( H \) be the same as in Corollary 12. Let \( S \) and \( T \) be nonexpansive mappings on \( C \) with \( ST = TS \) such
that $\mathcal{F} := \text{Fix}(S) \cap \text{Fix}(T) \neq \emptyset$. Let $\{\alpha_n\}$ and $\{\beta_n\}$ be sequences satisfying (C1)–(C3). Then, the sequence $\{x_n\}$ defined by
\[
x_{n+1} = \beta_n x_n + (1 - \beta_n) P_C \left[ (1 - \alpha_n) \frac{1}{n^2} \sum_{j=0}^{n-1} s^j T^j x_n \right], \quad \forall n \geq 1,
\]
converges strongly to $\bar{x} \in \mathcal{F}$, where $\bar{x} = P_\mathcal{F}(0)$ is the minimum-norm fixed point of $\mathcal{F}$, where $\bar{x}$ solves uniquely the quadratic minimization problem (128).

**Theorem 17.** Let $C$ and $H$ be the same as in Corollary 13. Let $\delta = \{T(t) : t > 0\}$ be a strongly continuous nonexpansive semigroup on $C$ such that $\mathcal{F} := \text{Fix}(\delta) \neq \emptyset$. Let $\{\alpha_n\}$ and $\{\beta_n\}$ be sequences satisfying (C1)–(C3). Then, the sequence $\{x_n\}$ defined by
\[
x_{n+1} = \beta_n x_n + (1 - \beta_n) P_C \left[ (1 - \alpha_n) \frac{1}{t_n} \int_0^{t_n} T(s)x_n ds \right], \quad \forall n \geq 1,
\]
where $\{t_n\}$ is an increasing sequence in $(0, \infty)$ with $\lim_{n \to \infty} t_n = 1$, converges strongly to $\bar{x} \in \mathcal{F}$, where $\bar{x} = P_\mathcal{F}(0)$ is the minimum-norm fixed point of $\mathcal{F}$, where $\bar{x}$ solves uniquely the quadratic minimization problem (128).

**Theorem 18.** Let $C$ and $H$ be the same as in Corollary 14. Let $\delta = \{T(t) : t > 0\}$ be a nonexpansive semigroup on $C$ such that $\mathcal{F} := \text{Fix}(\delta) \neq \emptyset$. Let $\{\alpha_n\}$ and $\{\beta_n\}$ be sequences satisfying (C1)–(C3). Then, the sequence $\{x_n\}$ defined by
\[
x_{n+1} = \beta_n x_n + (1 - \beta_n) P_C \left[ (1 - \alpha_n) \frac{1}{t_n} \int_0^{t_n} T(s)x_n ds \right], \quad \forall n \geq 1,
\]
where $\{\alpha_n\}$ is a decreasing sequence in $(0, \infty)$ with $\lim_{n \to \infty} \alpha_n = 0$, converges strongly to $\bar{x} \in \mathcal{F}$, where $\bar{x} = P_\mathcal{F}(0)$ is the minimum-norm fixed point of $\mathcal{F}$, where $\bar{x}$ solves uniquely the quadratic minimization problem (128).

**Acknowledgment**

The authors were supported by the Higher Education Research Promotion and National Research University Project of Thailand, Office of the Higher Education Commission (Grant no. NRU56000508).

**References**


