STABILITY OF STATIONARY AND PERIODIC SOLUTIONS EQUATIONS IN BANACH SPACE

A.YA. DOROGOVTEV
Kiev University, Mechanics and Mathematics Department
Vladimirskaya 64, 252033 Kiev-33 Ukraine

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Linear difference and differential equations with operator coefficients and random stationary (periodic) input are considered. Conditions are presented for the mean stability of stationary (periodic) solutions under small perturbation of the coefficients.

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1. Introduction

The purpose of this paper is to study the stability of stationary or periodic in law solutions for the linear difference and differential equations in Banach space under small perturbation of coefficient-operators. The problem of stability of solutions for stochastic equations is studied intensively by different methods and for various dynamical stochastic systems. See Khasminskii [9] about the pioneering results and Khaminskii and Mandrekar [10], Arnold and Khasminskii [1], Baladi and Young [2], Hinrichsen and Pritchard [8] and Wirth and Hinrichsen [14] for modern methods, new results and more references. Our results are similar to Maslow [12], which are about stability of the solution of a Cauchy problem for operator equation in Banach space. We will also need some results of [3] concerning the existence and structure of stationary and periodic solutions of operator equations in Banach space. We consider stability of solutions in the mean on Z or on R and we deal only with bounded perturbation.

2. Assumptions

Let \((B, \| \cdot \| )\) be complex separable Banach space, \(0\) be the zero element in \(B\), and \(L(B)\) be the Banach space of bounded linear operators on \(B\) with the operator norm, also denoted by \(\| \cdot \| \). For the function \(x: \mathbb{R} \rightarrow B\), the continuity at a point \(t_0\) means that

\[\| x(t) - x(t_0) \| \rightarrow 0, \quad t \rightarrow t_0.\]
Function $x$ is differentiable at a point $t_0 \in \mathbb{R}$ if there is an element $y \in B$ such that
\[ \lim_{t \to t_0} \frac{x(t) - x(t_0)}{t - t_0} - y = 0, \quad t \to t_0. \]
The element $y$ is called the derivative of function $x$ at the point $t_0$ and is denoted by symbol $x'(t_0)$. With the help of these definitions, the classes $C(\mathbb{R}, B)$ and $C^1(\mathbb{R}, B)$ are defined by the usual manner. Let $\sigma(A)$ be spectrum of operator $A \in L(B)$. Denote $S = \{ z \in \mathbb{C} \mid |z| = 1 \}$.

In this paper we consider only $B$-valued random processes with discrete time parameter $\{x(n): n \in \mathbb{Z}\}$ or with continuous time parameter $\{x(t): t \in \mathbb{R}\}$, which is continuous on $\mathbb{R}$. For random elements and various concepts of convergence of random elements see [11]. The equality of random elements is always the equality with probability 1. The solution of a differential equation is a $B$-valued random process $\{x(t): t \in \mathbb{R}\}$ with continuous derivative $\{x'(t): t \in \mathbb{R}\}$. The uniqueness of the solution is within stochastic equivalence.

The $B$-valued process $\{x(n): n \in \mathbb{Z}\}$ or $\{x(t): t \in \mathbb{R}\}$ is called $\tau$-periodic with period $\tau \in \mathbb{N}$ or $\tau > 0$ if all finite-dimensional distributions are periodic with period $\tau$ in time shift. For details see [3].

3. Difference Equations

**Theorem 1:** Let operators $A \in L(B)$ and $\{A_m(n), n \in \mathbb{Z}, m \geq 1\} \subset L(B)$ satisfy the conditions
1. $\sigma(A) \cap S = \emptyset$;
2. $\delta_m = \sup \{ \| A_m(n) - A \| \mid n \in \mathbb{Z} \} \to 0, \quad m \to \infty$.

Then, $x(n + 1) = Ax(n) + y(n), \quad n \in \mathbb{Z}, \quad (1)$
and for every $m$ greater than some $m_0 \in \mathbb{N}$,

\[ x_m(n + 1) = A_m(n)x_m(n) + y(n), \quad n \in \mathbb{Z}, \quad (2) \]
has a unique stationary solution $\{x(n): n \in \mathbb{Z}\}$ and unique solution $\{x_m(n): n \in \mathbb{Z}\}$, respectively, for which

\[ E \| x(0) \| < +\infty, \sup_{n \in \mathbb{Z}} E \| x_m(n) \| < +\infty, \quad n \in \mathbb{Z}, \]
and

\[ \sup_{n \in \mathbb{Z}} E \| x_m(n) - x(n) \| \to 0, \quad m \to \infty \quad (3) \]
for each stationary $B$-valued process $\{y(n): n \in \mathbb{Z}\}$ with $E \| y(0) \| < +\infty$.

**Remark:** Theorem 1 in 3.1.1 in [3] states that condition (i) of Theorem 1 is equivalent to the existence of a unique stationary solution $\{x(n): n \in \mathbb{Z}\}$ with $E \| x(0) \| < +\infty$ of equation (1) for every stationary process $\{y(n): n \in \mathbb{Z}\}$ with $E \| y(0) \| < +\infty$.

**Proof of Theorem 1:** Let $\sigma_-(A) = \sigma(A) \cap \{ z \in \mathbb{C} \mid |z| < 1 \}$, $\sigma_+(A) = \{ z \in \mathbb{C} \mid |z| > 1 \}$.
\(\sigma(A) \setminus \sigma_-(A)\) and let \(P_- \) and \(P_+ \) be spectral projectors corresponding to spectral sets \(\sigma_-(A)\) and \(\sigma_+(A)\), respectively. As proved in [3], for every \(n \in \mathbb{Z}\), we have
\[x(n) = \sum_{j=-\infty}^{+\infty} G_j y(n-j-1),\]
where
\[G_j = (AP_-)^j I_{j \geq 0} - (AP_+)^j I_{j \leq -1}, \quad j \in \mathbb{Z}.
\]

The above series expansion of \(x(n)\) is convergent with probability 1 in norm \(B\) and \(E \| x(0) \| < +\infty\). Moreover, \(L = \sum_{j \in \mathbb{Z}} \| G_j \| < +\infty\).

Let \(m_0 \in \mathbb{Z}\) such that \(L \delta_m < 1\) for \(m > m_0\) and let \(m > m_0\). We prove the existence of a solution for equation (2) by showing that the sequence
\[x_m^n(0) = 0, \quad n \in \mathbb{Z},
\]
\[x^{j+1}_m(n+1) = A x^j_m(n) + (A_m(n) - A) x^j_m(n) + y(n), \quad n \in \mathbb{Z}; \quad j \geq 0,
\]
converges as \(j \to \infty\) to a solution of (2). First we have
\[\Delta_m^j \leq L \delta_m \Delta_m^{j-1}, \quad j \geq 1
\]
for \(\Delta_m^j = \sup_{n \in \mathbb{Z}} E \| x^{j+1}_m(n) - x^j_m(n) \| \). From [11], for every \(n \in \mathbb{Z}\), there is a random element \(x_m(n)\) such that \(x^j_m(n) \to x_m(n), j \to \infty\) with probability 1. In addition, \(\sup_{m \geq 1} \sup_{n \in \mathbb{Z}} E \| x_m(n) \| < +\infty\) and taking the limit in \(j\) in both sides of equality (4) we obtain equation (3). From (1) and (2) it follows that
\[\sup_{n \in \mathbb{Z}} E \| x(n) - x_m(n) \| \leq L \delta_m E \| x_m(n) \|
\]
and
\[\sup_{n \in \mathbb{Z}} E \| x(n) - x_m(n) \| \leq \frac{L \delta_m}{1 - L \delta_m} E \| y(0) \|.
\]

Theorem 1 is proved. \(\square\)

**Remarks:**
1. Theorem 1 may be generalized to encompass more general perturbations. Let
\[\{A_m^{\nu}(n) \mid n \in \mathbb{Z}, \nu \geq 0, m \geq 1\} \subset L(B)
\]
and
\[\delta_m^{\nu} = \sup_{n \in \mathbb{Z}} \| A_m^{\nu}(n) - A \| + \sum_{\nu=1}^{\infty} \sup_{n \in \mathbb{Z}} \| A_m^{\nu}(n) \| \to 0, m \to \infty.
\]

Then the conclusion of Theorem 1 is valid for the solutions of the equations
\[x^{n+1}_m(n) + \sum_{\nu=0}^{\infty} A_m^{\nu}(n) x_m(n-\nu) + y(n), \quad n \in \mathbb{Z}; \quad m \geq 1.
\]

2. All processes, which occurred in Theorem 1, are stationary connected processes.

Let \(\{A(n) \mid n \in \mathbb{Z}\} \subset L(B)\) and, for a fixed \(\tau \in \mathbb{N}\), let \(A(n + \tau) = A(n), n \in \mathbb{Z}.
\]
Define $B = A(\tau - 1)A(\tau - 2)...A(1)A(0)$.

**Theorem 2:** Let operators $\{A(n): n \in \mathbb{Z}\}$ and $\{A_m(n), n \in \mathbb{Z}, m \geq 1\} \subset L(B)$ satisfy the conditions

(i) $\sigma(B) \cap S = \emptyset$;

(ii) $\sup_{n \in \mathbb{Z}} ||A_m(n) - A(n)|| \to 0, \ m \to \infty$.

Then,

$$x(n + 1) = A(n)x(n) + y(n), \ n \in \mathbb{Z}$$ (6)

and for every $m$ greater some $m_0 \in \mathbb{N}$ the equation

$$x_m(n + 1) = A_m(n)x_m(n) + y(n), \ n \in \mathbb{Z}$$ (7)

has a unique $\tau$-periodic solution $\{x(n): n \in \mathbb{Z}\}$ and unique solution $\{x_m(n): n \in \mathbb{Z}\}$, respectively, for which

$$E \|x(k)\| < +\infty, \ k = 1, 2, \ldots, \tau; \sup_{n \in \mathbb{Z}} E \|x_m(n)\| < +\infty$$

and

$$\sup_{n \in \mathbb{Z}} E \|x_m(n) - x(n)\| \to 0, \ m \to \infty$$

for each $\tau$-periodic process $\{y(n): n \in \mathbb{Z}\}$ with $E \|y(k)\| < +\infty, \ k = 1, 2, \ldots, \tau$.

**Proof:** The proof of Theorem 2 is similar to that of Theorem 1 and we give only new arguments. First, notice that for each process $\{y(n): n \in \mathbb{Z}\}$ with $\sup_{n \in \mathbb{Z}} E \|y(n)\| < +\infty$, equation (1) under condition (i) of Theorem 1 and condition (ii) of Theorem 2 has a unique solution $\{x(n): n \in \mathbb{Z}\}$ with $\sup_{n \in \mathbb{Z}} E \|x(n)\| < +\infty$.

The proof of this statement follows along the lines of proof of Theorem 1.

It is easily seen that the solution $\{x(n): n \in \mathbb{Z}\}$ for equation (6) satisfies the equation

$$x((\nu + 1)\tau) = Bx(\nu\tau) + z(\nu), \ \nu \in \mathbb{Z}$$ (8)

with

$$z(\nu) = \sum_{t=1}^{\tau-1} A(\tau - 1)A(\tau - 2)...A(\tau - t)y((\nu + 1)\tau - t - 1) + y((\nu + 1)\tau - 1), \ \nu \in \mathbb{Z}$$.

Then, using the previous statement, we define $\{x(\nu\tau): \nu \in \mathbb{Z}\}$ as a solution for equation (8) and with

$$x(\nu\tau + 1): = A(0)x(\nu\tau) + y(\nu\tau)$$

$$x(\nu\tau + 2): = A(1)x(\nu\tau + 1) + y(\nu\tau + 1)$$

$$...........................$$

$$x(\nu\tau + \tau - 1): = A(\tau - 2)x(\nu\tau + \tau - 2) + y(\nu\tau + \tau - 2),$$

we have the solutions $\{x(n): n \in \mathbb{Z}\}$ of equation (6).

Now, using the approximating method of Theorem 1, it is easy to prove the existence of solution to equation (7) for every $m$ greater than some $m_0 \in \mathbb{N}$. Theorem 2 is proved.
4. Differential Equations with Random Forces

Theorem 3: If operators \( \{A; A_m(t) \mid m \geq 1, t \in \mathbb{R}\} \subset L(B) \) satisfy the following conditions:

(i) \( \sigma(A) \cap i\mathbb{R} = \emptyset; \)
(ii) \( \forall m \geq 1: A_m \in C(\mathbb{R}, L(B)); \)
(iii) \( \int_{\mathbb{R}} \| A_m(t) - A \|^2 dt \to 0, m \to \infty, \)

then

\[
x'(t) = Ax(t) + \xi(t), \quad t \in \mathbb{R}
\]

and for every \( m \) greater than some \( m_0 \in \mathbb{N} \), the equation

\[
x_m'(t) = A_m(t)x_m(t) + \xi(t), \quad t \in \mathbb{R}
\]

has a unique stationary solution \( \{x(t): t \in \mathbb{R}\} \) and unique solution \( \{x_m(t): t \in \mathbb{R}\} \), respectively, with

\[
E \| x(0) \| < +\infty; \sup_{t \in \mathbb{R}} E \| x_m(t) \| < +\infty
\]

and

\[
\sup_{t \in \mathbb{R}} E \| x(t) - x_m(t) \| \to 0, \quad m \to \infty
\]

for each stationary process \( \{\xi(t): t \in \mathbb{R}\} \) with \( E \| \xi(0) \| \) \( < +\infty \).

Proof: In [3], 7.1.1 it was shown that condition (i) of Theorem 3 is equivalent to the existence of a unique stationary solution \( \{x(t): t \in \mathbb{R}\} \) to equation (9) with \( E \| x(0) \| < +\infty \) for each stationary process \( \{\xi(t): t \in \mathbb{R}\} \) with \( E \| \xi(0) \| < +\infty \).

Moreover, with probability 1 for every \( t \in \mathbb{R} \),

\[
x(t) = \int_{\mathbb{R}} G(t-s)\xi(s)ds,
\]

where \( G(t) = -e^{At}P_+I_{(t < 0)}(t) + e^{At}P_-I_{(t > 0)}(t), \quad t \in \mathbb{R} \) with spectral projectors \( P_- \) and \( P_+ \) corresponding to spectral sets \( \sigma(A) \cap \{z \mid \text{Re}z < 0\} \) and \( \sigma(A) \cap \{z \mid \text{Re}z > 0\} \), respectively. The integral in (11) is a Bochner integral [15] with respect to Lebesgue measure on \( \mathbb{R} \). It is known that \( \| G(t) \| \leq Le^{-a|t|}, \quad t \in \mathbb{R} \) with some \( L \geq 0, a > 0 \). In similar way, we can prove the existence of a unique solution \( \{x_m(t): t \in \mathbb{R}\} \) of equation (10) for \( m \) sufficiently large. Moreover, for each \( t \in \mathbb{R} \),

\[
x_m(t) = \int_{\mathbb{R}} G(t-s)(A_m(t)-A)x_m(s)ds + x(t), \quad m \geq m_0
\]

and

\[
\sup_{m \geq 1} \sup_{t \in \mathbb{R}} E \| x_m(t) \| < +\infty.
\]

Then the conclusion of Theorem 3 follows from (11), (12), and condition (iii).

The following theorem is a consequence of Theorem 2. The proof is similar so that of Theorem 3 and is omitted. Let

\[
A \in C(\mathbb{R}, L(B)); A(t + \tau) = A(t), \quad t \in \mathbb{R}
\]

and let \( U: \mathbb{R} \to L(B) \) be an invertible valued solution to the problem...
\[ \begin{aligned}
U'(t) - A(t)U(t), \quad t \in \mathbb{R}; \\
U(0) = I,
\end{aligned} \]

where \( I \) is the identity operator, see [13].

**Theorem 4:** Let operators \( \{A, A_m\} \subset C(\mathbb{R}, L(B)), \; m \geq 1 \) satisfy the following conditions

(i) \( A(t + \tau) = A(t), \; t \in \mathbb{R}; \)

(ii) \( \sigma(U(\tau)) \cap S = \emptyset; \)

(iii) \( \int_{\mathbb{R}} \| A(t) - A_m(t) \| dt \to 0, \; m \to \infty. \)

Then, \( x'(t) = A(t)x(t) + \xi(t), \; t \in \mathbb{R} \), and for every sufficiently large \( m \) the equation

\[ x'_m(t) = (A(t) + A_m(t))x_m(t) + \xi(t), \; t \in \mathbb{R} \]

has a unique \( \tau \)-periodic solution \( \{x(t) : t \in \mathbb{R}\} \) and \( \{x_m(t) : t \in \mathbb{R}\} \), respectively, with

\[ \sup_{0 \leq t \leq \tau} E \| x(t) \| < +\infty, \sup_{t \in \mathbb{R}} E \| x_m(t) \| < +\infty, \]

and

\[ \sup_{t \in \mathbb{R}} E \| x(t) - x_m(t) \| \to 0, \; m \to \infty \]

for each \( \tau \)-periodic process \( \{\xi(t) : t \in \mathbb{R}\} \) with

\[ \int_0^{\tau} E \| \xi(s) \| ds < +\infty. \]

Consider also the following generalization of the last theorem.

**Condition A:** Let the function \( A \in C(\mathbb{R}, L(B)) \) have exponential dichotomy on \( \mathbb{R} \) with exponent index \( a > 0 \) and coefficient \( L \) as in [7].

**Theorem 5:** Let operators \( \{A, A_m\} \subset C(\mathbb{R}, L(B)), \; m \geq 1 \) satisfy the following conditions

(i) Condition A for the function \( A \);

(ii) \( \int_{\mathbb{R}} \| A(t) - A_m(t) \| dt \to 0, \; m \to \infty. \)

Then, \( x'(t) = A(t)x(t) + \xi(t), \; t \in \mathbb{R} \) and for every sufficiently large \( m \),

\[ x'_m(t) = (A(t) + A_m(t))x_m(t) + \xi(t), \; t \in \mathbb{R} \]

has unique solutions \( \{x(t) : x \in \mathbb{R}\} \) and \( x_m(t) : t \in \mathbb{R}\) with

\[ \sup_{t \in \mathbb{R}} E \| x(t) \| < +\infty, \sup_{t \in \mathbb{R}} E \| x_m(t) \| < +\infty \]

and

\[ \sup_{t \in \mathbb{R}} E \| x(t) - x_m(t) \| \to 0, \; m \to \infty \]

for each process \( \{\xi(t) : t \in \mathbb{R}\} \) with \( \sup_{t \in \mathbb{R}} E \| \xi(t) \| < +\infty. \)

**Remarks:**

1. Theorems 1-5 may be generalized to nonlinear equations, which are nearly linear as in [3]. The nonlinear equation of Riccati type [4] shall be considered in the next paper.

2. See [5, 6] for analogous results under some other conditions.
References


