ON GENERAL AND REPRODUCTIVE SOLUTIONS OF FINITE EQUATIONS

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Abstract. Prešić and his followers have studied the general and reproductive solutions of a certain equation over a finite set. In this paper we provide simple characterizations of these solutions.

The concept of general or parametric solution of an equation is well known in various contexts. Schröder [21, vol. 1], introduced reproductive general solutions of Boolean equations, which were extensively studied by Löwenheim [13], [14] and his followers (the term “reproductive” was introduced by Löwenheim [14]; cf. Rudeanu [19]). Prešić [15] initiated the axiomatic study of general solutions and reproductive general solutions, i.e., for the most general concept of equation. This line of research was followed by Prešić [17], Bozić [9], Banković [1], [2], [3], Rudeanu [20] and Chvalina [10]. In their monograph [12], unfortunately unpublished, Keckić and Prešić showed that the concept of reproductive solution is very important in various fields of mathematics.

A further step was taken by Prešić [16], who considered the case of equations over a finite set, on which he introduced a certain algebraic structure yielding a reproductive solution in compact form; see also Ghilezan [11]. Then Prešić [18] introduced within this framework an equation which generalizes Boolean and Post equations in one unknown and for which he obtained all reproductive solutions. Other descriptions of all general solutions and all reproductive solutions were then obtained by Banković [4]–[8].

In this paper we provide simpler characterizations of the general and reproductive solutions of that equation.

We first recall all necessary prerequisites.

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Let $T = \{t_0, t_1, \ldots, t_m\}$ be a finite set and 0, 1 two elements which may be either outside $T$ or two distinguished elements of $T$. Define two binary partial operations $+$ and $\cdot$ on $T \cup \{0, 1\}$ by the following conditions:
\[
x + 0 = 0 + x = x,
\]
\[
x \cdot 0 = 0 \cdot x = 0,
\]
\[
x \cdot 1 = 1 \cdot x = x,
\]
for every $x \in T \cup \{0, 1\}$; the operation $\cdot$ is usually denoted by concatenation. Define also
\[
x^y = \begin{cases} 1, & \text{if } x = y, \\ 0, & \text{if } x \neq y, \end{cases}
\]
for every $x, y \in T \cup \{0, 1\}$, as well as a family $\sum_{i=0}^{n} x_i$ of partial operations given by
\[
\sum_{i=0}^{m} x_i = x_0, \quad \sum_{i=0}^{n+1} x_i = \left( \sum_{i=0}^{n} x_i \right) + x_{n+1} \quad (n \in \mathbb{N}).
\]

**Proposition 1.** Every function $f : T \to T$ can be written in the form
\[
f(x) = \sum_{i=0}^{m} f_i x^i \quad (\forall x \in T),
\]
where the coefficients are uniquely determined by
\[
f_k = f(t_k) \quad (k = 0, 1, \ldots, m).
\]

*Proof.* For each $k = 0, 1, \ldots, m$, the equality
\[
f(t_k) = \sum_{i=0}^{m} f(t_i) t_k^i
\]
holds because the right-hand side of (6) contains the term $f(t_k) t_k^k = f(t_k)$, while the other terms are 0. Conversely, (4) implies, for each $k = 0, 1, \ldots, m$,
\[
f(t_k) = \sum_{i=0}^{m} f_i t_k^i = f_k t_k^k = f_k.
\]

The equation introduced by Presić and studied by him and Banković is
\[
a_0 x^{t_0} + a_1 x^{t_1} + \ldots + a_m x^{t_m} = 0,
\]
where \( a_0, a_1, \ldots, a_m \in \{0,1\} \) and the unknown \( x \in T \). Let us denote by \( S \) the (possibly empty) set of solutions of equation (7).

**Remark [18].** For \( x = t_k \) the left-hand side of equation (7) reduces to \( a_k \), hence

\[
t_k \in S \Leftrightarrow a_k = 0 \quad (k = 0,1,\ldots,m),
\]

therefore equation (7) is consistent if and only if \( a_k = 0 \) for some \( k \). In other words, taking also into account the associativity of the operation \( \cdot \) on \( \{0,1\} \), we see that the consistency condition for equation (7) is

\[
a_0a_1 \ldots a_m = 0.
\]

The next definition is borrowed from the axiomatic framework introduced by Prešič [15].

**Definition.** Suppose equation (7) is consistent. A function \( f:T \rightarrow T \) is called a general solution of equation (7) if \( f(T) = S \). By a reproductive general solution or simply a reproductive solution of equation (7) is meant a general solution \( f \) such that \( s = f(s) \) for all \( s \in S \).

The next lemma is in fact valid for any equation over a finite set.

**Lemma 1 [4].** A function \( f:T \rightarrow T \) is a general solution of equation (7) if and only if it fulfills

(i) \( f(T) \subseteq S \), and

(ii) there is a permutation \( \beta \) of \( \{0,1,\ldots,m\} \) such that

\[
t_{\beta(k)} \in S \Rightarrow f(t_k) = t_{\beta(k)} \quad (k = 0,1,\ldots,m).
\]

**Proof.** Sufficiency is obvious. Conversely, suppose \( f \) is a general solution. Define a map \( \varphi_0:S \rightarrow T \) by choosing, for each element \( t \in S \), an element \( \varphi_0(t) \) such that \( t = f(\varphi_0(t)) \). Then \( \varphi_0 \) is obviously injective and it follows immediately that \( \varphi_0 \) can be extended to a bijection \( \varphi:T \rightarrow T \). The defining property of \( \varphi_0 \) implies that \( t_h = f(\varphi(t_h)) \) for all \( t_h \in S \). The latter property can be written in the form (10) for the permutation \( \beta \) of \( \{0,1,\ldots,m\} \) defined by \( \beta(k) = h \Leftrightarrow \varphi(t_h) = t_k \).

**Lemma 2.** The implication (10) in Lemma 1 can be written in the form

\[
f(t_k) = t_{\beta(k)}a_{\beta(k)}^0 + f(t_k)a_{\beta(k)}^1 \quad (k = 0,1,\ldots,m).
\]

**Proof.** It follows from (11) that

\[
a_{\beta(k)} = 0 \Rightarrow f(t_k) = t_{\beta(k)} \quad (k = 0,1,\ldots,m);\]
but (12) is equivalent to (10) by (8). Conversely, suppose (10) holds. Then (11) is checked immediately by considering the cases \( a_{\beta(k)} = 1 \) and \( a_{(k)} = 0 \) and by using again (8).

**Theorem 1.** A function \( f: T \to T \) is a general solution of equation (7) if and only if it is of the form

\[
f(x) = \sum_{k=0}^{m} (t_{\beta(k)} a_{\beta(k)}^0 + c_k a_{\beta(k)}^1) x^j_k \quad (\forall x \in T)
\]

where \( \beta \) is a permutation of \( \{0, 1, \ldots, m\} \) and

\[
c_k \in S \quad (k = 0, 1, \ldots, m)
\]

**Proof.** Suppose (13) and (14) hold. Consider an arbitrary but fixed \( k \in \{0, 1, \ldots, m\} \). Taking into account Proposition 1, it follows that if \( a_{\beta(k)} = 1 \); then \( f(t_k) = c_k \in S \), while \( t_{\beta(k)} \in S \Leftrightarrow a_{\beta(k)} = 0 \Rightarrow f(t_k) = t_{\beta(k)} \). Therefore \( f \) is a general solution by Lemma 1. Conversely, necessity follows from Proposition 1 and Lemmas 1 and 2.

**Theorem 2.** A function \( f: T \to T \) is a reproductive solution of equation (7) if and only if it is of the form

\[
f(x) = \sum_{k=0}^{m} (t_k a_k^0 + c_k a_k^1) x^j_k \quad (\forall x \in T)
\]

where

\[
c_k \in S \quad (k = 0, 1, \ldots, m).
\]

**Proof.** It follows from Theorem 1 and Proposition 1 that any function satisfying (15) and (14) is a general solution and

\[
f(t_k) = t_k a_k^0 + c_k a_k^1 \quad (k = 0, 1, \ldots, m),
\]

therefore if \( t_k \in S \) then \( f(t_k) = t_k \) because \( a_k = 0 \). Conversely, suppose \( f \) is a reproductive solution of equation (7). Then \( f \) satisfies conditions (i) and (ii) in Lemma 1 with the identity in the role of \( \beta \). Taking also into account Lemma 2 we see that relations (14) and (16) hold for \( c_k = f(t_k) \). The proof is completed by Proposition 1.

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