T-NEIGHBORHOOD GROUPS

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We generalize min-neighborhood groups to arbitrary T-neighborhood groups, where T is a continuous triangular norm. In particular, we point out that our results accommodate the previous theory on min-neighborhood groups due to T. M. G. Ahsanullah. We show that every T-neighborhood group is T-uniformizable, therefore, T-completely regular. We also present several results of T-neighborhood groups in conjunction with TI-groups due to J. N. Mordeson.

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1. Introduction. Menger in [19] introduces an important class of *T*-uniformities (*T* being a continuous *t*-norm) that is generated by a probabilistic metric [21]. Motivated by the Menger's *T*-uniformities, Höhle [13] brought into light in his celebrated article the idea of probabilistic metrization of fuzzy uniformities. While developing his theory, he showed that a fuzzy *T*-uniformity is probabilistic metrizable if and only if it is Hausdorff-separated and has a countable base. He also pointed out that when *T* = min is considered, his fuzzy *T*-uniformity reduces to min-fuzzy uniformity of R. Lowen—a fuzzy uniformity [16] is that it gives rise to a fuzzy neighborhood space [17]; an interesting and very well-behaved class of fuzzy topological spaces [15], used by many authors in a wide variety of ways. Among the prominent classes of so called fuzzy neighborhood spaces are, for instance, Katsaras linear fuzzy neighborhood spaces [14], fuzzy metric neighborhood spaces [18], fuzzy neighborhood groups, rings, modules, algebras, and commutative division rings [1, 2, 3, 4, 5].

Very recently, following the famous articles of Menger [19], Höhle [13], Frank [9], Hashem and Morsi [10, 11, 12] introduced a class of fuzzy topological spaces [15] as they put it: fuzzy *T*-neighborhood spaces herein called *T*-neighborhood spaces—a natural generalization of min-fuzzy neighborhood spaces of Lowen [17]. Our main target here in this article is to generalize the notion of min-fuzzy neighborhood groups introduced in [2]. We show that every *T*-neighborhood group is a *T*-uniform space, and therefore, a *T*-complete regular space in the sense of Hashem and Morsi [12]. We also generalize the two important characterization theorems, which give necessary and sufficient condition for a *T*-neighborhood system and a group structure to be compatible, and a prefilter to be a *T*-neighborhood prefilter.

As an application, we present some results on *T*-neighborhood groups in conjunction with Mordeson's *TI*-groups [7], which we believe will open the opportunities to look into further work on fuzzy algebraic structures in connection with the *T*-neighborhood groups.

2. Preliminaries. Let *T* be a continuous two-place function (known as continuous triangular norm or *t*-norm) mapping from the closed unit square to the closed unit interval satisfying certain conditions. In other words, $T : I \times I \to I$, $(\alpha, \beta) \mapsto \alpha T \beta$, satisfying the following conditions:

(Ta) 0T0 = 0, $\alpha T1 = \alpha$ for all $\alpha \in I$;

(Tb) $\alpha T \beta = \beta T \alpha$ for all $(\alpha, \beta) \in I \times I$;

(Tc) if $\alpha \leq \beta$ and $\gamma \leq \delta$, then $\alpha T \gamma \leq \beta T \delta$ for all $\alpha, \beta, \gamma, \delta \in I$;

(Td) $(\alpha T\beta)T\gamma = \alpha T(\beta T\gamma)$ for all $\alpha, \beta, \gamma \in I$.

DEFINITION 2.1 [6, 16]. A nonempty subset $\mathfrak{B} \subset I^G$ is called a prefilterbase if and only if the following conditions are true:

(PB1) 0 ∉ ℜ;

(PB2) for all $v_1, v_2 \in \mathfrak{B}$, there exists $v \in \mathfrak{B}$ such that $v \leq v_1 \wedge v_2$.

If \mathfrak{B} is a prefilterbase in I^G , then by its saturation we understand the following collection:

$$\mathfrak{B}^{\sim} = \{ \nu : G \longrightarrow I; \ \forall \epsilon > 0 \ \exists \nu_{\epsilon} \in \mathfrak{B} \ni \nu_{\epsilon} - \epsilon \le \nu \}.$$

$$(2.1)$$

DEFINITION 2.2 [10, 11, 12]. A *T*-neighborhood space is an *I*-topological space [15] $(G, \overline{})$ whose closure operator "-" is induced by some indexed family $\Omega = (\Omega(x))_{x \in G}$ of prefilterbases in I^G defined by

$$\bar{\xi}(x) = \inf_{\nu \in \Omega(x)} \sup_{z \in G} \xi(z) T \nu(z) \quad \forall \xi \in I^G, \ x \in G.$$
(2.2)

THEOREM 2.3 [10, 11, 12]. A family $\Omega = (\Omega(x))_{x \in G}$ of prefilterbases in I^G is a *T*-neighborhood base in *G* if and only if it satisfies the following two properties for all $x \in G$:

(TB1) for all $v \in \Omega(x)$, v(x) = 1;

(TB2) for all $v \in \Omega(x)$, there exists a family $(v_{y\epsilon} \in \Omega(y))_{(y,\epsilon)\in G\times I_0}$ which satisfies for all $(y,\epsilon) \in G \times I_0$,

$$\sup_{z \in G} \left[v_{x,\epsilon}(z) T v_{z,\epsilon}(y) \right] \le v(y) + \epsilon.$$
(2.3)

The family Ω is said to be a *T*-neighborhood basis for $(G, \overline{})$, and every $\nu \in \Omega(x)$ is called *T*-neighborhood at *x*. This *I*-topology is denoted by $t^{T}(\Omega)$. However, from now on we will be calling the triple $(G, \overline{}, t(\Omega))$ the *T*-neighborhood space with Ω a *T*-neighborhood base in *G*.

THEOREM 2.4 [10, 11, 12]. Let $(G_1, \bar{}, t(\Omega_1))$ and $(G_2, \bar{}, t(\Omega_2))$ be *T*-neighborhood spaces with *T*-neighborhood bases Ω_1 and Ω_2 , respectively. Then a function $f: G_1 \to G_2$ is continuous at $x \in G_1$

$$\Leftrightarrow \forall \mu \in \Omega_2(f(x)), \ f^{-1}(\mu) \in \Omega_1(x)^{\sim}, \Leftrightarrow \forall \mu_2 \in \Omega_2(f(x)) \quad \forall \epsilon > 0 \ \exists \mu_1 \in \Omega_1(x) \ni \mu_1 - \epsilon \le f^{-1}(\mu_2),$$
(2.4)

$$\Leftrightarrow \overline{[f^{-1}(\sigma)]}(x) \le [f^{-1}(\bar{\sigma})](x) \quad \forall \sigma \in I^{G_2}.$$

If $\Lambda, \Gamma \in I^{G \times G}$ and $\nu \in I^G$, then *T*-section of Λ over ν is given by

$$\Lambda \langle v \rangle_T(x) = \sup_{y \in G} v(y) T \Lambda(y, x) \quad \forall x \in G.$$
(2.5)

The *T*-composition of Λ and Γ is defined as

$$\Lambda \circ_T \Gamma(x, y) = \sup_{z \in G} \left[\Gamma(x, z) T \Lambda(z, y) \right] \quad \forall (x, y) \in G \times G.$$
(2.6)

Γ is called symmetric if $\Gamma^s = \Gamma$, that is, $\Gamma(\gamma, x) = \Gamma(x, \gamma)$, for all $(x, \gamma) \in G \times G$.

DEFINITION 2.5 [10, 11, 12]. A subset $\mathfrak{B} \subset I^{G \times G}$ is called a *T*-uniform base on a set *G* if and only if the following properties are fulfilled:

(TUB1) \mathfrak{B} is a prefilterbase;

(TUB2) for all $x \in G$, for all $v \in \mathcal{B}$, v(x, x) = 1;

(TUB3) for all $\beta \in \mathfrak{B}$, for all $\epsilon > 0$, there exists $\beta_{\epsilon} \in \mathfrak{B}$ such that $\beta_{\epsilon} \circ_T \beta_{\epsilon} - \epsilon \leq \beta$;

(TUB4) for all $\beta \in \mathfrak{B}$, for all $\epsilon > 0$, there exists $\beta_{\epsilon} \in \mathfrak{B}$ such that $\beta_{\epsilon} - \epsilon \leq \beta$.

The collection \mathfrak{B} of fuzzy subsets of $G \times G$ is called *T*-quasi-uniform base on a set *G* if and only if it fulfills the preceding conditions (TUB1), (TUB2), and (TUB3), while \mathfrak{U} is called *T*-quasi-uniformity if and only if $\widetilde{\mathfrak{B}} = \mathfrak{U}$. A *T*-uniformity \mathfrak{U} is a saturated *T*-uniform base \mathfrak{B} .

THEOREM 2.6 [10, 11, 12]. If \mathfrak{B} is a *T*-quasi-uniform base on a set *G*, then for all $x \in G$, the family

$$\Sigma(x) = \{\beta \langle 1_x \rangle \mid \beta \in \mathfrak{B}^{\sim}\} = \{\beta \langle 1_x \rangle \mid \beta \in \mathfrak{B}\}^{\sim}$$
(2.7)

is a T-neighborhood system on G.

PROPOSITION 2.7 [10, 11, 12]. Let (G, \mathfrak{A}) be a *T*-quasi-uniform space. Then the closure of the *T*-neighborhood space $(G, t(\mathfrak{A}))$ is given by

$$\bar{\mu} = \inf_{\sigma \in \mathcal{U}} \sigma \langle \mu \rangle_T \quad \forall \mu \in I^G.$$
(2.8)

THEOREM 2.8 [10, 11, 12]. If (G, τ) is a topological space and $\mathcal{V}_{\tau} = (\mathcal{V}_{\tau}(x))_{x \in G}$ is its associated neighborhood system in G, then $(G, \bar{\tau}, t(\Omega_{\tau}))$, a generated topological space, generated by τ , is a T-neighborhood space with a T-neighborhood basis $\Omega = (\Omega(x))_{x \in G}$, where for all $x \in G$,

$$\Omega_{1} := \Omega_{1}(x) = \{1_{M} : G \longrightarrow I; M \in \mathscr{V}_{\tau}(x)\} \subset I^{G};$$

$$\Omega_{2} := \Omega_{2}(x) = \{1_{M} : G \longrightarrow I; x \in M \in \tau\} \subset I^{G};$$

$$\Omega_{3} := \Omega_{3}(x) = \{\nu : G \longrightarrow I; \nu \text{ is l.s.c. in } x \text{ and } \nu(x) = 1\} \subset I^{G}.$$
(2.9)

Just for the sake of convenience, we provide the proof of the following proposition.

PROPOSITION 2.9. A function $f : (G, \mathcal{V}_{\tau}) \to (G', \mathcal{V}'_{\tau'})$ between two topological spaces is continuous at a point $x \in G$ if and only if $f : (G, t(\Omega_{\tau})) \to (G', t(\Omega'_{\tau'}))$ is continuous at $x \in G$ between two generated *T*-neighborhood spaces.

PROOF. Let $f : (G, \mathcal{V}_{\tau}) \to (G, \mathcal{V}_{\tau'})$ be continuous at $x \in G$ and $\mu' \in \Omega'_{\tau'}(f(x))$; in view of Theorem 2.4, we show that $f^{-1}(\mu') \in \widetilde{\Omega_{\tau}(x)}$.

Choose $M' \in \mathcal{V}'_{\tau}(f(x))$ such that $\mu' = 1_{M'}$. This implies that there exists an $M \in \mathcal{V}_{\tau}(x)$ such that $f(M) \subset M'$, and hence for all $\epsilon > 0$,

$$1_M(x) - \epsilon = 1 - \epsilon \le 1_{f^{-1}(M')}(x) = f^{-1}(\mu').$$
(2.10)

With $\mu = 1_M$, one obtains $\mu - \epsilon \le f^{-1}(\mu')$ implying that $f^{-1}(\mu') \in \Omega_{\tau}(x)$.

Conversely, we show that the function $f: (G, \mathcal{V}_{\tau}) \to (G', \mathcal{V}'_{\tau'})$ is continuous at $x \in G$. If $U \in \mathcal{V}'_{\tau'}(f(x))$, then $1_U \in \Omega'_{\tau'}(f(x))$ implies $f^{-1}(1_U) \in \widetilde{\Omega_{\tau}(x)}$ by continuity of f between the generated spaces.

Thus, for all $\epsilon > 0$, there is a $\mu = \mu_{\epsilon} \in \Omega_{\tau}(x)$ such that

$$\mu - \epsilon \le f^{-1}(1_U). \tag{2.11}$$

This implies that for all $\epsilon > 0$, there exists a $V_{\epsilon} \in \mathcal{V}_{\tau}(x)$ such that $1_{V_{\epsilon}} = \mu = \mu_{\epsilon}$ and

$$1_{V_{\epsilon}} - \epsilon \le 1_{f^{-1}(U)}.\tag{2.12}$$

Now $V_{\epsilon} \in \mathcal{V}_{\tau}(x)$ implies $x \in V_{\epsilon}$ if and only if $1_{V_{\epsilon}}(x) = 1$. Therefore,

$$0 < 1 - \epsilon = 1_{V_{\epsilon}}(x) - \epsilon \le 1_{f^{-1}(U)}(x) \Longrightarrow 1_{f^{-1}(U)}(x) > 0 \Longrightarrow 1_{f^{-1}(U)}(x)$$
$$= 1 \Longleftrightarrow x \in f^{-1}(U).$$
(2.13)

This means that $V_{\epsilon} \subseteq f^{-1}(U)$ implies $f^{-1}(U) \in \mathcal{V}_{\tau}(x)$. That is, f is continuous at $x \in G$.

THEOREM 2.10 [11]. Let $(G, \overline{})$ be an *I*-topological space. Then $(G, \overline{})$ is a *T*-neighborhood space if and only if $\overline{\alpha T \mu} = \alpha T \overline{\mu}$ for all $\mu \in I^G$ and for all $\alpha \in I$.

DEFINITION 2.11 [12]. An *I*-topological space (X, τ) is called *T*-completely regular if τ is the initial *I*-topology for the family of all continuous functions from (X, τ) to $(\mathfrak{D}^+, t^T(\mathcal{F}_{\mathcal{H}}))$.

Here, \mathfrak{D}^+ stands for the collection of all distance distribution functions from \mathfrak{R}^+ to the unit interval *I*, and the pair $(\mathfrak{D}^+, t^T(\mathcal{F}_{\mathcal{H}}))$ is the *T*-neighborhood space induced by the well-known Höhle's probabilistic *T*-metric $\mathcal{F}_{\mathcal{H}}$. For details, we refer to [12, 13].

THEOREM 2.12 [12]. *T*-complete regularity is equivalent to *T*-uniformizability.

3. Some results on *T*-neighborhood spaces

THEOREM 3.1. Let $(G_1, -, t(\Omega_1))$ and $(G_2, -, t(\Omega_2))$ be two *T*-neighborhood spaces with bases $\Omega_1 = (\Omega_1(x))_{x \in G_1}$ and $\Omega_2 = (\Omega_2(x))_{x \in G_2}$ in G_1 and G_2 , respectively. Then their *T*-product $(G_1 \times G_2, -^{\otimes_T}, t(\Omega_1) \otimes_T t(\Omega_2))$ is the *T*-neighborhood space with base $\Omega = \Omega_1 \otimes_T \Omega_2$ defined by

$$\Omega(\boldsymbol{x},\boldsymbol{y}) = \{ \boldsymbol{v}_1 \otimes_T \boldsymbol{v}_2 \mid \boldsymbol{v}_1 \in \Omega_1(\boldsymbol{x}), \ \boldsymbol{v}_2 \in \Omega_2(\boldsymbol{y}) \},$$
(3.1)

where $v_1 \otimes_T v_2$ is given as

$$\nu_1 \otimes_T \nu_2(x, y) = \nu_1(x) T \nu_2(y) \quad \forall (x, y) \in G_1 \times G_2.$$

$$(3.2)$$

Moreover,

$$\overline{\nu_1 \otimes_T \nu_2} = \overline{\nu_1} \otimes_T \overline{\nu_2} \quad \forall \nu_1 \in I^{G_1}, \ \nu_2 \in I^{G_2}.$$
(3.3)

Conversely, if

$$\overline{\nu_1 \otimes_T \nu_2} = \overline{\nu_1} \otimes_T \overline{\nu_2} \quad \forall \nu_1 \in I^{G_1}, \ \nu_2 \in I^{G_2},$$
(3.4)

then both the I-topological spaces $(G_1, -)$ and $(G_2, -)$ are T-neighborhood spaces.

PROOF. First we show that for all $(x, y) \in G_1 \times G_2$, $\Omega(x, y)$ is a prefilterbase. (PB1) Obviously, $\Omega \neq \emptyset$ and $0 \notin \Omega$.

(PB2) Let $\xi_1, \xi_2 \in \Omega(x, y)$, then there are $v_1, v_2 \in \Omega_1(x)$ and $\mu_1, \mu_2 \in \Omega_2(y)$ such that $\xi_1 = v_1 \otimes_T \mu_1$ and $\xi_2 = v_2 \otimes_T \mu_2$.

Now, $\xi_1 \wedge \xi_2 = (\nu_1 \otimes_T \mu_1) \wedge (\nu_2 \otimes_T \mu_2)$. For any $(x, y) \in G_1 \times G_2$,

$$\xi_{1}(x, y) \wedge \xi_{2}(x, y) = (v_{1} \otimes_{T} \mu_{1})(x, y) \wedge (v_{2} \otimes_{T} \mu_{2})(x, y)$$

$$= (v_{1}(x)T\mu_{1}(y)) \wedge (v_{2}(x)T\mu_{2}(y))$$

$$\geq (v_{1}(x) \wedge v_{2}(x))T(v_{1}(y) \wedge \mu_{2}(y))$$

$$= (v_{1} \wedge v_{2})(x)T(\mu_{1} \wedge \mu_{2})(y).$$

(3.5)

Therefore, $\xi_1 \wedge \xi_2(x, y) \ge v(x) \wedge \mu(y)$ for some $v \in \Omega_1(x)$ and $\mu \in \Omega_2(y)$, since both $\Omega_1(x)$ and $\Omega_2(y)$ are prefilterbases in G_1 and G_2 , respectively.

This implies that $\xi_1 \wedge \xi_2(x, y) \ge v \otimes_T \mu(x, y) = \xi(x, y)$ and $\xi \in \Omega(x, y)$, and hence $\xi \le \xi_1 \wedge \xi_2$, proving that $\Omega(x, y)$ is a prefilterbase in $G_1 \times G_2$.

Now we prove the conditions of Theorem 2.3.

- (TB1) If $x \in G$ and $\xi \in \Omega(x, x)$, then for some $v \in \Omega_1(x)$ and $\mu \in \Omega_2(x)$, we have $\xi(x, x) = v \otimes_T \mu(x, x), v(x)T\mu(x) = 1T1 = 1.$
- (TB2) Let $(x, y) \in G_1 \times G_2$, $\xi \in \Omega(x, y)$, and $\epsilon \in I_0$. Then there exists $\nu \in \Omega_1(x)$ and $\mu \in \Omega_2(y)$ such that $\xi = \nu \otimes_T \mu$.

Consequently, there is a family $(v_{y_1\epsilon} \in \Omega_1(y_1))_{(y_1,\epsilon)\in G_1\times I_0}$, a *T*-kernel for ν which satisfies for all $(y_1,\epsilon)\in G_1\times I_0$,

$$\sup_{z_1\in G_1} \left[\nu_{x,\epsilon}(z_1)T\nu_{z_1,\epsilon}(y_1) \right] \le \nu(y_1) + \epsilon.$$
(3.6)

Also, there is a family $(\mu_{\gamma_2\epsilon} \in \Omega_2(\gamma_2))_{(\gamma_2,\epsilon)\in G_2\times I_0}$, a *T*-kernel for μ which satisfies for all $(\gamma_2,\epsilon)\in G_2\times I_0$,

$$\sup_{z_2\in G_2} \left[\mu_{\mathcal{Y},\epsilon}(z_2)T\mu_{z_2,\epsilon}(\mathcal{Y}_2)\right] \le \mu(\mathcal{Y}_2) + \epsilon.$$
(3.7)

Now for all $(y_1, y_2) \in G_1 \times G_2$,

$$(v \otimes_T \mu)(y_1, y_2) + \delta = [v(y_1)T\mu(y_2)] + \delta \ge (v(y_1) + \epsilon)T(\mu(y_2) + \epsilon)$$
(3.8)

with $\epsilon = \epsilon_{T,\delta} > 0$.

This yields that

$$(v \otimes_{T} \mu) (y_{1}, y_{2}) + \delta \geq \sup_{z_{1} \in G_{1}} [v_{x,\epsilon}(z_{1}) T v_{z_{1},\epsilon}(y_{1})] T \sup_{z_{2} \in G_{2}} [\mu_{y,\epsilon}(z_{2}) T \mu_{z_{2},\epsilon}(y_{2})] = \sup_{(z_{1}, z_{2}) \in G_{1} \times G_{2}} [(v_{x,\epsilon}(z_{1}) T \mu_{y,\epsilon}(z_{2})) T (v_{z_{1},\epsilon}(y_{1}) T \mu_{z_{2},\epsilon}(y_{2}))] = \sup_{(z_{1}, z_{2}) \in G_{1} \times G_{2}} [((v_{x,\epsilon} \otimes_{T} \mu_{y,\epsilon})(z_{1}, z_{2})) T ((v_{z_{1},\epsilon} \otimes_{T} \mu_{z_{2},\epsilon})(y_{1}, y_{2}))] \Rightarrow \sup_{(z_{1}, z_{2}) \in G_{1} \times G_{2}} [v_{x,\epsilon} \otimes_{T} \mu_{y,\epsilon}(z_{1}, z_{2}) T v_{z_{1},\epsilon} \otimes_{T} \mu_{z_{2},\epsilon}(y_{1}, y_{2})] \leq v \otimes_{T} \mu(y_{1}, y_{2}) + \delta.$$

In order to prove the final part, we proceed as follows. Let $v_1 \in I^{G_1}$, $v_2 \in I^{G_2}$, and $(x, y) \in G_1 \times G_2$.

Then in view of **Definition 2.2**, we have

$$\overline{\nu_{1} \otimes_{T} \nu_{2}}(x, y) = \inf_{\substack{\xi_{1} \in \Omega_{1}(x) \\ \xi_{2} \in \Omega_{2}(y) \\ \xi_{2} \in \Omega_{2}(y) \\ z_{1} \in G_{1}} \sup_{z_{2} \in G_{2}} \sup_{z_{1} \in G_{1}} \sup_{z_{2} \in G_{2}} \{\nu_{1}(z_{1})T\nu_{2}(z_{2})\}T\{\xi_{1}(z_{1})T\xi_{2}(z_{2})\} \\
= \inf_{\substack{\xi_{1} \in \Omega_{1}(x) \\ \xi_{2} \in \Omega_{2}(y) \\ \xi_{1} \in G_{1}} \sup_{z_{2} \in G_{2}} \sup_{z_{1} \in G_{1}} \sup_{z_{2} \in G_{2}} \nu_{1}(z_{1})T\xi_{1}(z_{1})T\nu_{2}(z_{2})T\xi_{2}(z_{2}) \\
= \inf_{\substack{\xi_{1} \in \Omega_{1}(x) \\ \xi_{1} \in G_{1}}} \sup_{z_{1} \in G_{1}} \nu_{1}(z_{1})T\xi_{1}(z_{2})T \inf_{\substack{\xi_{2} \in \Omega_{2}(y) \\ \xi_{2} \in G_{2}(y)}} \sup_{z_{2} \in G_{2}} \nu_{2}(z_{2})T\xi_{2}(z_{2}) \\
= \overline{\nu_{1}}(x)T\overline{\nu_{2}}(y) = \overline{\nu_{1}} \otimes_{T} \overline{\nu_{2}}(x, y).$$
(3.10)

To prove the converse part, we proceed as follows. Since

$$\overline{\nu_1 \otimes_T \nu_2} = \overline{\nu_1} \otimes_T \overline{\nu_2} \quad \forall \nu_1 \in I^{G_1}, \ \nu_2 \in I^{G_2}, \tag{3.11}$$

in view of Theorem 2.10, we have

$$\overline{(\alpha T \nu_1 \otimes_T \nu_2)}(x) = (\alpha T \overline{\nu_1 \otimes_T \nu_2})(x)$$
$$= \alpha(x) T (\overline{\nu_1} \otimes_T \overline{\nu_2})(x)$$
$$= \alpha(x) T (\overline{\nu_1}(x) T \overline{\nu_2}(x)).$$
(3.12)

Since this holds for all *x* and for all v_1 and v_2 , with $v_2 = 1$, we have

$$\overline{(\alpha T \nu_1 \otimes_T \nu_2)}(x) = (\alpha T \overline{\nu_1 \otimes_T \nu_2})(x) = \alpha(x) T(\overline{\nu_1}(x)T1)$$

= $\alpha(x) T \overline{\nu_1}(x) = (\alpha T \overline{\nu_1})(x) = \overline{(\alpha T \nu_1)}(x),$ (3.13)

so $(G_1, -)$ is a *T*-neighborhood space. Similarly, with $v_1 = 1$, we see that $(G_2, -)$ is a *T*-neighborhood space. This completes the proof.

PROPOSITION 3.2. Let $(G_1, -, t(\Omega_1))$ and $(G_2, -, t(\Omega_2))$ be *T*-neighborhood spaces. Then the projections

$$pr_1: (G_1 \times G_2, -^{\otimes_T}, t(\Omega_1) \otimes_T t(\Omega_2)) \longrightarrow (G_1, -, t(\Omega_1)), \qquad (x_1, x_2) \longmapsto x_1, pr_2: (G_1 \times G_2, -^{\otimes_T}, t(\Omega_1) \otimes_T t(\Omega_2)) \longrightarrow (G_2, -, t(\Omega_2)), \qquad (x_1, x_2) \longmapsto x_2,$$

$$(3.14)$$

are continuous.

PROOF. Let $v \in \Omega_1(x_1)$ and $\epsilon > 0$. Then

$$pr_{1}^{-1}(v_{1})(x_{1},x_{2}) = v_{1}(pr_{1}(x_{1},x_{2})) = v_{1}(x_{1})T1 \ge v_{1}(x_{1})Tv_{2}(x_{2}) \ge v_{1} \otimes_{T} v_{2}(x_{1},x_{2}) - \epsilon$$

$$\Rightarrow v_{1} \otimes_{T} v_{2} - \epsilon \le pr_{1}^{-1}(v_{1}) \Rightarrow pr_{1}^{-1}(v_{1}) \in \Omega(x_{1},x_{2})^{\sim}.$$

(3.15)

This implies that $\operatorname{pr}_1 : (G_1 \times G_2, -^{\otimes_T}, t(\Omega_1) \otimes_T t(\Omega_2)) \to (G_1, -, t(\Omega_1)), (x_1, x_2) \mapsto x_1$, is continuous, and similarly, one can prove that $\operatorname{pr}_2 : (G_1 \times G_2, -^{\otimes_T}, t(\Omega_1) \otimes_T t(\Omega_2)) \to (G_2, -, t(\Omega_2)), (x_1, x_2) \mapsto x_2$, is continuous.

DEFINITION 3.3. A *T*-neighborhood space $(G, -, t(\Omega))$ is said to be a *TN*-regular space if and only if for all $z \in G$, for all $\mu \in \Omega(z)$, and for all $\epsilon > 0$, there exists a $\nu \in \Omega(z)$ closed such that

$$\epsilon + \mu(z) \ge \inf_{\rho \in \Omega(z)} \sup_{t \in G} \nu(t) T \rho(t) (= \bar{\nu}(z)).$$
(3.16)

THEOREM 3.4. Every *T*-quasi-uniform space (G, Ψ) is *TN*-regular.

PROOF. Suppose that $z \in G$, $\psi \in \Psi$, and $\epsilon > 0$, and choose $\psi_{\epsilon} \in \Psi$ such that

$$\psi_{\epsilon} \circ_T \psi_{\epsilon} \le \psi + \epsilon. \tag{3.17}$$

If $t \in G$, then by using Proposition 2.7,

$$\overline{\psi_{\epsilon}\langle z \rangle}^{T}(t) = \inf_{\substack{\psi_{\epsilon}' \in \Psi \\ y \in G}} \sup_{y \in G} \psi_{\epsilon}\langle z \rangle\langle y \rangle T \psi_{\epsilon}'(y,t) \leq \sup_{y \in G} \psi_{\epsilon}(z,y) T \psi_{\epsilon}(y,t)
= \psi_{\epsilon} \circ_{T} \psi_{\epsilon}(z,t) \leq \psi(z,t) + \epsilon
= \psi\langle z \rangle(t) + \epsilon.$$
(3.18)

Hence the result follows.

4. *T***-neighborhood groups.** In what follows, we consider (G, \cdot) as a multiplicative group with *e* as the identity element. If $\mu : G \to I$, then $\mu^{-1}(x)$ is defined as $\mu^{-1}(x) = \mu(-x)$, and μ is said to be symmetric if and only if $\mu = \mu^{-1}$.

DEFINITION 4.1. Let (G, \cdot) be a group and $(G, -, t(\Omega))$ a *T*-neighborhood space with *T*-neighborhood base Ω on *G*. Then the quadruple $(G, \cdot, -, t(\Omega))$ is called a *T*-neighborhood group if and only if the following properties are satisfied:

- (TG1) the mapping $m : (G \times G, -^{\otimes_T}, t(\Omega) \otimes_T t(\Omega)) \to (G, -, t(\Omega)), (x, y) \mapsto xy$, is continuous;
- (TG2) the inversion mapping $r: (G, \bar{}, t(\Omega)) \to (G, \bar{}, t(\Omega)), x \mapsto x^{-1}$, is continuous.

A group structure and a *T*-neighborhood system is said to be compatible if and only if (TG1) and (TG2) are fulfilled.

REMARKS 4.2. A *T*-neighborhood group may not be a fuzzy topological group in the sense of Foster [8] since we have used *T*-neighborhood topology, which differ from the product fuzzy topology.

PROPOSITION 4.3. Let (G, \cdot) be a group and $(G, -, t(\Omega))$ a *T*-neighborhood space with a *T*-neighborhood base Ω . Then the quadruple $(G, \cdot, -, t(\Omega))$ is a *T*-neighborhood group if and only if the mapping

$$h: (G \times G, -^{\otimes_T}, t(\Omega) \otimes_T t(\Omega)) \longrightarrow (G, -, t(\Omega)), \quad (x, y) \longmapsto x y^{-1}, \tag{4.1}$$

is continuous.

PROOF. Observe that the conditions (TG1) and (TG2) are equivalent to the following single condition:

(TG3) the mapping $h: (G \times G, -^{\otimes_T}, t(\Omega) \otimes_T t(\Omega)) \to (G, -, t(\Omega)), (x, y) \mapsto xy^{-1}$, is continuous.

In fact, if we let $f(x, y) = (x, y^{-1})$, then by (TG2), f is continuous and hence in conjunction with (TG1), one obtains the continuity of h. On the other hand, (TG3) \Rightarrow (TG2) for $x \rightarrow ex^{-1} = x^{-1}$ is then continuous; while (TG1) follows from (TG3) and (TG2), because $(x, y) \rightarrow x(y^{-1})^{-1} = xy$ is then continuous.

PROPOSITION 4.4. Let (G, \cdot) be a group and $(G, -, t(\Omega))$ a *T*-neighborhood space with Ω a *T*-neighborhood base in *G*. Then

(a) the mapping $m : (G \times G, \cdot, -^{\otimes_T}, t(\Omega) \otimes_T t(\Omega)) \to (G, \cdot, -, t(\Omega)), (x, y) \mapsto xy$, is continuous at $(e, e) \in G \times G$ if and only if for all $\mu \in \Omega(e)$, for all $\epsilon > 0$, there exists $\nu \in \Omega(e)$ such that

$$\nu \odot_T \nu \le \mu + \epsilon; \tag{4.2}$$

(b) the inversion mapping $r: (G, \cdot, \bar{}, t(\Omega)) \to (G, \cdot, \bar{}, t(\Omega)), x \mapsto x^{-1}$, is continuous at $e \in G$ if and only if for all $\mu \in \Omega(e)$, for all $\epsilon > 0$, there exists $v \in \Omega(e)$ such that

$$\nu \le \mu^{-1} + \epsilon. \tag{4.3}$$

PROOF. (a) In view of Theorem 2.4, continuity at $(e, e) \in G \times G$ is equivalent to

$$\forall \mu \in \Omega(e) \Longrightarrow m^{-1}(\mu) \in (\Omega(e) \otimes_T \Omega(e))^{\sim} \iff \forall \mu \in \Omega(e), \quad \forall \epsilon > 0, \ \exists \nu = \nu_{\epsilon} \in \Omega(e) \ni \nu \otimes_T \nu \le m^{-1}(\mu) + \epsilon.$$

$$(4.4)$$

But $m(v \otimes_T v)(z) = \sup_{(x,y) \in m^{-1}(z)} v(x) Tv(y) = \sup_{xy=z} v(x) Tv(y) = v \odot_T v(z)$. Thus, in this case, continuity at $(e, e) \in G \times G$ is in fact equivalent to

$$\nu \odot_T \nu \le \mu + \epsilon. \tag{4.5}$$

(b) This follows almost in the same way as in (a).

COROLLARY 4.5. *If* $(G, \cdot, -, t(\Omega))$ *is a T*-neighborhood group, then the mapping (4.1) *is continuous at* $(e, e) \in G \times G$ *if and only if for all* $\mu \in \Omega(e)$ *and for all* $\epsilon > 0$, *there exists a* $\nu \in \Omega(e)$ *such that*

$$\nu \odot_T \nu^{-1} \le \mu + \epsilon. \tag{4.6}$$

PROOF. This follows at once from the composition of (a) and (b) in Proposition 4.4.

PROPOSITION 4.6. Let $(G, \bar{}, t(\Omega))$ be a *T*-neighborhood space and $A \subset G$. Then $(A, \bar{}, t(\Omega_{|A}))$ is a *T*-neighborhood space, a subspace of the *T*-neighborhood space $(G, \bar{}, t(\Omega))$.

PROOF. The proof follows by easy verification.

THEOREM 4.7. The triple (G, \cdot, τ) is a topological group if and only if the quadruple $(G, \cdot, \bar{t}, t(\Omega_{\tau}))$, where Ω is the generated *T*-neighborhood basis, is a *T*-neighborhood group.

PROOF. With the help of Proposition 2.9, it follows that the mapping

$$h: (G \times G, \mathscr{V}_{\tau} \times \mathscr{V}_{\tau}) \longrightarrow (G, \mathscr{V}_{\tau}), \quad (x, y) \longmapsto x y^{-1}, \tag{4.7}$$

is continuous if and only if

$$h: (G \times G, t(\Omega_{\tau}) \otimes_T t(\Omega_{\tau})) \longrightarrow (G, t(\Omega_{\tau})), \quad (x, y) \longmapsto x y^{-1}, \tag{4.8}$$

is continuous, where Ω is the basis for the generated *T*-neighborhood spaces.

LEMMA 4.8. Let $(G, \cdot, \bar{}, t(\Omega))$ be a *T*-neighborhood group and $a \in G$. Then

- (1) the left translation $\mathcal{L}_a: (G, \cdot, \bar{}, t(\Omega)) \to (G, \cdot, \bar{}, t(\Omega)), x \mapsto ax$, and the right translation $\mathcal{R}_a: (G, \cdot, \bar{}, t(\Omega)) \to (G, \cdot, \bar{}, t(\Omega)), x \mapsto ax$, are homeomorphisms;
- (2) the inner automorphism 𝔅_a: (G, ·, ⁻, t(Ω)) → (G, ·, ⁻, t(Ω)), z ↦ aza⁻¹, is an isomorphism;
- (3) v ∈ Ω(e)[~] if and only if L_a(v) ∈ Ω(a)[~] if and only if R_a(v) ∈ Ω(a)[~]. In other words, if Ω is saturated, then v ∈ Ω(e) if and only if 1_{a} ⊙_T v = a ⊙_T v ∈ Ω(a) if and only if v ⊙_T a ∈ Ω(a);
- (4) $v \in \Omega(a)^{\sim}$ if and only if $\mathscr{L}_{-a}(v) \in \Omega(e)^{\sim}$ if and only if $\mathscr{R}_{-a}(v) \in \Omega(e)^{\sim}$. In other words, if Ω is saturated, then $v \in \Omega(a)$ if and only if $1_{\{a^{-1}\}} \odot_T v = a^{-1} \odot v \in \Omega(e)$ if and only if $v \odot_T a^{-1} \in \Omega(e)$;
- (5) if $v \in \Omega(e)$, then $v^{-1} \in \Omega(e)$;
- (6) $v \odot_T v^{-1}$ is symmetric.

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PROOF. (1) follows at once from the definitions while (2) follows from the fact that $\mathcal{I}_a = \mathcal{L}_a \circ \mathcal{R}_{-a} = \mathcal{R}_{-a} \circ \mathcal{L}_a$ for all $a \in G$.

(3) Let $v \in \Omega(e)^{\sim} \subset \Omega(e)$, that is, $v \in \Omega(a^{-1}a) = \Omega(\mathscr{L}_a^{-1}(a))$. Since \mathscr{L}_a^{-1} is continuous, then in view of Theorem 2.4, $\mathscr{L}_a(v) = (\mathscr{L}_a^{-1})^{-1}(v) \in \Omega(a)^{\sim}$ implies $\mathscr{L}_a(v) \in \Omega(a)^{\sim}$. Conversely, let $\mathscr{L}_a(v) \in \Omega(a)^{\sim} \subset \Omega(a)$ implies $\mathscr{L}_a(v) \in \Omega(a) = \Omega(ae) = \Omega(\mathscr{L}_a(e))$, and since $\mathscr{L}_a : G \to G$ is continuous injection again by Theorem 2.4, $v = \mathscr{L}_a^{-1}(\mathscr{L}_a(v)) \in \Omega(e)^{\sim}$. For the calculations of the other part, see [7, Theorem 5.1.1]. (4) follows from (3) while (5) follows from the fact that the inversion mapping $r : G \to C$

 $G, x \mapsto x^{-1}$ is a homeomorphism.

(6) We have $v \odot_T v^{-1} = (v \odot_T v^{-1})^{-1}$. If $x \in G$, then

$$(v \odot_T v^{-1})^{-1}(x) = (v \odot_T v^{-1})(x^{-1}) = \sup_{ab=x^{-1}} v(a)Tv(b^{-1})$$

= $\sup_{st^{-1}=x^{-1}} v(s)Tv(t) = \sup_{ts^{-1}=x} v(t)Tv(s)$
= $\sup_{ts^{-1}=x} v(t)Tv((s^{-1})^{-1})$
= $\sup_{ts^{-1}=x} v(t)Tv^{-1}(s^{-1})$
= $v \odot_T v^{-1}(x).$ (4.9)

This completes the proof.

DEFINITION 4.9. A *T*-neighborhood space $(G, -, t(\Omega))$ is called homogeneous space if and only if for all $(a, b) \in G \times G$, there exists a homeomorphism $f : (G, -, t(\Omega)) \rightarrow (G, -, t(\Omega))$ such that f(a) = b.

THEOREM 4.10. Every *T*-neighborhood group is a homogeneous space.

PROOF. This follows from the fact that for all $a, b \in G \times G$, the function

$$\mathfrak{R}_{a^{-1}b}: G \longrightarrow G, \quad x \longmapsto xa^{-1}b, \tag{4.10}$$

is a homeomorphism.

LEMMA 4.11. Let (G, \cdot) be a group, and let, for all $\mu \in I^G$, $\mu_L : G \times G \to I$, $(x, y) \mapsto \mu_L(x, y) = \mu(x^{-1}y)$ (resp., $\mu_R : G \times G \to I$, $(x, y) \mapsto \mu_R(x, y) = \mu(yx^{-1})$) be the vicinities *L*-associated (resp., *R*-associated) with μ .

Then for all μ , θ , $\nu \in I^G$, $(x, y) \in G \times G$, and triangular norm $T : I \times I \rightarrow I$, the following hold:

- (1) $\mu_L \langle \theta \rangle_T = \theta \odot_T \mu$ (resp., $\mu_R \langle \theta \rangle_T = \mu \odot_T \theta$);
- (2) $\mu_L T \nu_L = (\mu T \nu)_L$ (resp., $\mu_R T \nu_R = (\mu T \nu)_R$);
- (3) $(\mu_L^s) = (\mu_L)^s;$
- (4) $\mu_L \odot_T \nu_L = (\nu \odot_T \mu)_L$ (resp., $\mu_R \odot_T \nu_R = (\nu \odot_T \mu)_R$).

PROOF. (1) For all $(x, \theta, \mu) \in G \times I^G \times I^G$,

$$\mu_L \langle \theta \rangle_T(x) = \sup_{y \in G} \left[\theta(y) T \mu_L(y, x) \right] = \sup_{y \in G} \left[\theta(y) T \mu(y^{-1}x) \right]$$

= $\theta \odot_T \mu(x)$ (by [7, Theorem 5.1.1]). (4.11)

(2) and (3) are obvious.

(4) For all $(x, y) \in G \times G$,

$$\mu_{L} \odot_{T} \nu_{L}(x, y) = \sup_{z \in G} \left[\nu_{L}(x, z) T \mu_{L}(z, y) \right] = \sup_{z \in G} \left[\nu(x^{-1}z) T \mu(z^{-1}y) \right]$$
$$= \sup_{st = x^{-1}zz^{-1}y = x^{-1}y} \left[\nu(s) T \mu(t) \right] = (\nu \odot_{T} \mu) (x^{-1}y)$$
(4.12)

$$= (v \odot_T \mu)_I(x, y). \qquad \Box$$

THEOREM 4.12. Every *T*-neighborhood group is a *T*-uniform space.

PROOF. If $(G, \cdot, \bar{}, t(\Omega))$ is a *T*-neighborhood group, then $(G, \bar{}, t(\Omega))$ is a *T*-neighborhood space with the *T*-neighborhood basis Ω .

We consider the following collection:

$$\Omega = \{ \mu_L \mid \mu \in \Omega(e) \} \subset I^{G \times G}.$$
(4.13)

We claim that Ω is a *T*-uniform basis.

(TUB1) Clearly Ω is a prefilterbasis.

(TUB2) If $\psi \in \Omega$, then there exists a $\mu \in \Omega(e)$ such that $\psi = \mu_L$, and for all $x \in G$,

$$\psi(x,x) = \mu_L(x,x) = \mu(e) = 1. \tag{4.14}$$

(TUB3) If $\psi \in \Omega$, then there exists a $\mu \in \Omega(e)$ such that $\psi = \mu_L$. Thus, by virtue of Proposition 4.4(a), for all $\epsilon > 0$, we can find $\nu^{\epsilon} \in \Omega(e)$ such that

$$\nu^{\epsilon} \odot_T \nu^{\epsilon} - \epsilon \le \mu. \tag{4.15}$$

If we let $v_L^{\epsilon} = \psi_{\epsilon}$, then one obtains

$$\begin{aligned} \psi_{\epsilon} \odot_T \psi_{\epsilon} - \epsilon &= \nu_L^{\epsilon} \odot_T \nu_L^{\epsilon} - \epsilon = \left(\nu^{\epsilon} \odot_T \nu^{\epsilon} \right)_L - \epsilon \le \mu_L \\ &\implies \psi_{\epsilon} \odot_T \psi_{\epsilon} - \epsilon \le \psi. \end{aligned}$$

$$(4.16)$$

(TUB4) If $\psi \in \Omega$, then there is a $\mu \in \Omega(e)$ such that $\psi = \mu_L$. Consequently, by Proposition 4.4(b), for all $\epsilon > 0$, there exists a $\nu^{\epsilon} \in \Omega(e)$ such that

$$\nu^{\epsilon} - \epsilon \le \mu^{-1}. \tag{4.17}$$

Therefore, $v_L^{\epsilon} - \epsilon \le (\mu^{-1})_L = (\mu_L)^{-1}$ implies $\psi_{\epsilon} - \epsilon \le \psi_s$.

This shows in accordance with Definition 2.5 that Ω is a *T*-uniform basis, which in turn gives rise to a left *T*-uniformity $\mathfrak{U}_L = \Omega^{\sim}$.

In fact, we have for all $x \in G$,

$$\mathfrak{U}_{L}(x) = \left\{ \mu_{L} \langle 1_{x} \rangle \mid \mu \in \Omega(e) \right\}^{\sim} = \left\{ \mathfrak{L}_{x}(\mu) \mid \mu \in \Omega(e)^{\sim} \right\} = \Omega(x)^{\sim}, \tag{4.18}$$

which is a *T*-neighborhood system on *G* and that $(G, t(\Omega) = t(\mathfrak{A}_L))$ is a *T*-uniform space. Similarly, one can obtain right *T*-uniformity.

THEOREM 4.13. Every *T*-neighborhood group is *T*-completely regular.

PROOF. This follows from the preceding theorem in conjunction with Theorem 2.12 because every *T*-neighborhood group is *T*-uniformizable and every *T*-uniformizable space is *T*-completely regular.

THEOREM 4.14. Let (G, \cdot) be a group, $(G, -, t(\Omega))$ a *T*-neighborhood space with *T*-neighborhood base Ω in *G*. Then the quadruple $(G, \cdot, -, t(\Omega))$ is a *T*-neighborhood group if and only if the following are true:

- (1) for all $a \in G, \Omega(a)^{\sim} = \{\mathscr{L}_a(\mu) \mid \mu \in \Omega(e)\}^{\sim}$ (resp., for all $a \in G, \Omega(a)^{\sim} = \{\mathscr{R}_a(\mu) \mid \mu \in \Omega(e)\}^{\sim}$);
- (2) for all $\mu \in \Omega(e)$, for all $\epsilon > 0$, there exists a $\nu \in \Omega(e)$ such that

$$\nu \odot_T \nu \le \mu + \epsilon, \tag{4.19}$$

that is, the mapping $m : (x, y) \mapsto xy$ is continuous at $(e, e) \in G \times G$; (3) for all $\mu \in \Omega(e)$, for all $\epsilon > 0$, there exists a $\nu \in \Omega(e)$ such that

$$\nu \le \mu^{-1} + \epsilon, \tag{4.20}$$

that is, the mapping $r : x \mapsto x^{-1}$ is continuous at $e \in G$;

(4) for all $\mu \in \Omega(e)$, for all $\epsilon > 0$, and for all $a \in G$ such that

$$a \odot_T \nu \odot_T a^{-1} \le \mu + \epsilon, \tag{4.21}$$

that is, the mapping $\mathfrak{I}_a: x \mapsto axa^{-1}$ is continuous at $e \in G$.

PROOF. Let $(G, \cdot, \bar{}, t(\Omega))$ be a *T*-neighborhood group. Then the conditions (1), (2), (3), and (4) are clearly true.

To prove the converse part, we remark that from Corollary 4.5, it follows that the mapping $h: G \times G \to G$; $(x, y) \mapsto xy^{-1}$ is continuous at (e, e), and since the translations \mathcal{L}_a and \mathcal{R}_a are continuous at a and e, respectively, the continuity of m follows from the following chain:

$$G \times G \xrightarrow{\mathscr{L}_{a^{-1}} \times \mathscr{L}_{b^{-1}}} G \times G \xrightarrow{m} G \xrightarrow{\mathscr{I}_b} G \xrightarrow{\mathscr{L}_{ab^{-1}}} G, \tag{4.22}$$

where $(a,b) \rightarrow (e,e) \rightarrow e \rightarrow e \rightarrow ab^{-1}$.

THEOREM 4.15. Let (G, \cdot) be a group and \mathcal{F} a collection of nonempty subsets of I^G , that is, $\emptyset \neq \mathcal{F} \subset I^G$ such that

- (1) \mathcal{F} is a prefilterbasis and $\mu(e) = 1$ for all $\mu \in \mathcal{F}$;
- (2) for all $\mu \in \mathcal{F}$, for all $\epsilon > 0$, there exists a $\nu \in \mathcal{F}$ such that $\nu \epsilon \le \mu^{-1}$;
- (3) for all $\mu \in \mathcal{F}$, for all $\epsilon > 0$, there exists a $\nu \in \mathcal{F}$ such that $\nu \odot_T \nu \epsilon \le \mu$;
- (4) for all $\mu \in \mathcal{F}$, for all $a \in G$, for all $\epsilon > 0$, there exists $\nu \in \mathcal{F}$ such that $a \odot_T \nu \odot_T a^{-1} \epsilon \leq \mu$.

Then there exists a unique *T*-neighborhood system compatible with the group structure of *G* such that \mathcal{F} is a *T*-neighborhood basis at $e \in G$.

PROOF. For all $\mu \in \mathcal{F}$, let $\mu_L : G \times G \to I$ be the vicinities *L*-associated with μ . Evidently, $\mu_L(a, a) = \mu(a^{-1}a) = \mu(e) = 1$.

We let

$$\mathfrak{B} = \{\mu_L \mid \mu \in \mathfrak{F}\} \subset I^{G \times G}.$$
(4.23)

We show that \mathfrak{B} is a *T*-quasi-uniform basis for a *T*-quasi-uniformity. We verify Definition 2.5 upto (TUB3).

- (TUB1) \mathfrak{B} is a prefilterbasis; for $0 \notin \mathfrak{B}$ which is clearly true, since \mathfrak{F} is a prefilterbasis. Next, let $\lambda, \xi \in \mathfrak{B}$, then $\lambda = \mu_L$ for some $\mu \in \mathfrak{F}$ and $\xi = \eta_L$ for some $\eta \in \mathfrak{F}$. Since \mathfrak{F} is a prefilterbasis, there exists a $\theta \in \mathfrak{F}$ such that $\theta \leq \mu \wedge \eta$ and $\theta_L \leq \mu_L \wedge \eta_L = \lambda \wedge \xi$, proving that \mathfrak{B} is indeed a prefilterbasis.
- (TUB2) For all $x \in G$, and $\psi \in \mathfrak{B}$, we have $\psi = \mu_L$ for some $\mu \in \mathfrak{F}$ and $\psi(x, x) = \mu_L(x, x) = \mu(e) = 1$ by (1).
- (TUB3) Let $\psi \in \mathfrak{B}$. Then there exists a $\mu \in \mathfrak{F}$ such that $\psi = \mu_L$. Now by (3), for all $\epsilon > 0$, we can find a $\nu \in \mathfrak{F}$ such that

$$v \odot_T v - \epsilon \le \mu. \tag{4.24}$$

But then by virtue of Lemma 4.11(4), we get $v_L \odot_T v_L - \epsilon \leq \mu_L$. So, if we put $\psi_{\epsilon} = v_L$, then

$$\psi_{\epsilon} \odot_T \psi_{\epsilon} - \epsilon \le \psi. \tag{4.25}$$

This completes the proof that \mathfrak{B} is a *T*-quasi-uniform basis which in turn gives rise to a *T*-quasi-uniformity and hence a *T*-quasi-uniform space. Then in view of the Theorem 2.6, since every *T*-quasi-uniform space is a *T*-neighborhood space, in this case, we have the *T*-neighborhood system as given by the family

$$\{ \mu_L \langle 1_x \rangle_T \mid \mu_L \in \mathfrak{B}^{\sim} \} = \{ \mu_L \langle 1_x \rangle_T \mid \mu_L \in \mathfrak{B} \}^{\sim}$$

$$= \{ 1_x \odot_T \mu \mid \mu \in \mathfrak{F} \}^{\sim}$$

$$= \{ 1_x \odot \mu \mid \mu \in \mathfrak{F} \}^{\sim}.$$

$$(4.26)$$

Thus one obtains the *T*-neighborhood system with the following family: $\Omega(x) = \{1_x \odot_T \mu \mid \mu \in \mathcal{F}\}\)$, a basis for the system in question.

THEOREM 4.16. Let $(G, \cdot, \bar{}, t(\Omega))$ be a *T*-neighborhood group. Then for all $\mu : G \to I$,

$$\bar{\mu} = \inf \left\{ \mu \odot_T \nu \mid \nu \in \Omega(e)^{\sim} \right\} = \inf \left\{ \mu \odot_T \nu \mid \nu \in \Omega(e) \right\}^{\sim}.$$
(4.27)

PROOF. Observe that every *T*-neighborhood group is a *T*-quasi-uniform space. Therefore, by virtue of Theorem 2.6, we can write, in particular, that

$$\bar{\mu} = \inf \{ \nu_L \langle \mu \rangle_T \mid \nu \in \Omega(e)^{\sim} \}.$$
(4.28)

Then by using Lemma 4.11(1), we have the following:

$$\bar{\mu} = \inf \left\{ \mu \odot_T \nu \mid \nu \in \Omega(e)^{\sim} \right\} = \inf \left\{ \mu \odot_T \nu \mid \nu \in \Omega(e) \right\}^{\sim}.$$
(4.29)

COROLLARY 4.17. In a *T*-neighborhood group $(G, \cdot, \bar{}, t(\Omega))$, the following property holds:

$$\bar{\mu} = \inf \left\{ \nu \odot_T \mu \mid \nu \in \Omega(e)^{\sim} \right\} = \inf \left\{ \nu \odot_T \mu \mid \mu \in \Omega(e) \right\}^{\sim}.$$
(4.30)

PROOF. This follows at once from the preceding results.

THEOREM 4.18. If $(G, \cdot, -, t(\Omega))$ is a T-neighborhood group, then $(G, -, t(\Omega))$ is T-regular.

PROOF. Let $\mu \in \Omega(e)$ and $\epsilon > 0$. Since the map $(x, y) \mapsto xy^{-1}$ is continuous at $(e, e) \in G \times G$, in view of Corollary 4.5, we can find a $v \in \Omega(e)$ such that

$$\nu \odot_T \nu^{-1} \le \mu + \epsilon. \tag{4.31}$$

Then using Theorem 4.16, we obtain

$$\bar{\mu}(x) = \inf_{\omega \in \Omega(e)} v \odot_T \omega^{-1} \le v \odot_T v^{-1} \le \mu(x) + \epsilon, \tag{4.32}$$

which ends the proof.

PROPOSITION 4.19. If $(G, \cdot, \bar{}, t(\Omega))$ is a *T*-neighborhood group, then for all $\mu, \nu \in I^G$, we have the following:

- (i) $\bar{\mu} \odot_T \bar{\nu} \leq \overline{\mu \odot_T \nu}$;
- (ii) $\overline{\mu^{-1}} = \overline{\mu}^{-1};$
- (iii) $\overline{x \odot_T \mu \odot_T y} = x \odot_T \overline{\mu} \odot_T y$ for all $x, y \in G$.

PROOF. (i) If $z \in G$, then we have

$$\begin{split} \bar{\mu} \odot_T \bar{\nu}(z) &= \sup_{xy=z} \bar{\mu}(x) T \bar{\nu} y = \sup_{(x,y)\in m^{-1}(z)} \left[\bar{\mu} \otimes_T \bar{\nu} \right](x,y) \\ &= m \left[\bar{\mu} \otimes_T \bar{\nu} \right](z) = m \left[\overline{\mu} \otimes_T \overline{\nu} \right](z) \\ &\leq \overline{m \left[\mu \otimes_T \nu \right]}(z) = \overline{\mu} \odot_T \overline{\nu}(z). \end{split}$$
(4.33)

(ii) and (iii) follow immediately.

LEMMA 4.20. If (G, \cdot) and (G', \cdot) are groups and $f : G \to G'$ is a group homomorphism, then

$$f(x \odot_T a^{-1} \odot_T \mu) = f(x) \odot_T f(a)^{-1} \odot_T f(\mu).$$

$$(4.34)$$

PROOF. This follows the same way as in [2, Lemma 2.15]; see also [7].

THEOREM 4.21. Let $(G, \cdot, -, t(\Omega))$ and $(H, \cdot, -, t(\Xi))$ be *T*-neighborhood groups with bases Ω and Ξ in *G* and *H*, respectively. If $f : G \to H$ is a group homomorphism, then *f* is continuous if and only if it is continuous at one point.

PROOF. Let $f : G \to H$ be continuous at the point $a \in G$. We need to show that f is continuous at each $x \in G$. Let $\xi \in \Xi(f(x))$ and $\epsilon > 0$. Then we have $f(x)^{-1} \odot_T \xi \in \Xi(e)$ and hence $f(a) \odot_T f(x)^{-1} \odot_T \xi \in \Xi(f(a))$. Then by Theorem 2.4, the continuity at one

point $a \in G$ yields that $f^{-1}(f(a) \odot_T f(x)^{-1} \odot_T \xi) \in \Omega(a)^{\sim}$, which in turn implies that there exists a $\sigma = \sigma_{\epsilon} \in \Omega(a)$ such that

$$\sigma - \epsilon \le f^{-1}(f(a) \odot_T f(x)^{-1} \odot_T \xi).$$
(4.35)

Now we have $\mu := x \odot_T a^{-1} \odot_T \sigma \in \Omega(x)$.

Thus, one obtains

$$\mu(z) - \epsilon = x \odot_T a^{-1} \odot_T \sigma(z) - \epsilon = \sigma(ax^{-1}z) - \epsilon$$

$$\leq f(a) \odot_T f(x)^{-1} \odot_T \xi(f(ax^{-1}z))$$

$$= f(ax^{-1}) \odot_T \xi(f(ax^{-1})f(z))$$

$$= \xi(f(z)) = f^{-1}(\xi)(z),$$
(4.36)

that is, $\mu - \epsilon \le f^{-1}(\xi)$, which implies that $f^{-1}(\xi) \in \Omega(x)^{\sim}$.

Now we present some results on *T*-neighborhood groups in conjunction with Mordeson's *TI*-group.

5. Application of *T*-neighborhood groups in *TI*-groups

DEFINITION 5.1 [7, 20]. An *I*-subset μ of *G* is called a *TI*-subgroup of *G* if it fulfills the following conditions:

(G1) $\mu(e) = 1$;

(G2) $\mu(x^{-1}) \ge \mu(x)$, for all $x \in G$;

(G3) $\mu(xy) \ge \mu(x)T\mu(y)$, for all $x, y \in G$.

We denote the set of all *TI*-subgroups of *G* by TI(G) and that of the set of all normal *TI*-subgroups by *NTI*-subgroups, while by *NI*-subgroup we mean normal *I*-subgroups, the one introduced by Rosenfeld [20] in which case $T = \min$ is used.

PROPOSITION 5.2. Let $(G, \cdot, \bar{}, t(\Omega))$ be a *T*-neighborhood group and $\mu \in TI(G)$. Then $\bar{\mu}^{t(\Omega)} \in TI(G)$.

PROOF. In view of [7, Theorem 5.1.4], it suffices to prove that

$$\bar{\mu}^{t(\Omega)} \odot_T \left(\bar{\nu}^{t(\Omega)} \right)^{-1} \le \bar{\mu}^{t(\Omega)}.$$
(5.1)

Since $\mu \in TI(G)$, we have $\mu \odot_T \mu^{-1} \le \mu$. Then by an easy calculation, one obtains

$$\mu \odot_T \mu^{-1} = h(\mu \otimes_T \mu^{-1}), \tag{5.2}$$

which in conjunction with Theorem 3.1, yields the following:

$$\left(\bar{\mu}^{t(\Omega)}\right) \odot_T \left(\bar{\mu}^{t(\Omega)}\right)^{-1} = h\left[\left(\bar{\mu}^{t(\Omega)}\right) \otimes_T \left(\bar{\mu}^{t(\Omega)}\right)^{-1}\right] \le \bar{\mu}^{t(\Omega)},\tag{5.3}$$

which proves that $\bar{\mu}^{t(\Omega)} \in TI(G)$.

PROPOSITION 5.3. If $(G, \cdot, \bar{}, t(\Omega))$ is a *T*-neighborhood group and $\mu \in NTI(G)$, then $\bar{\mu}^{t(\Omega)} \in NTI(G)$.

PROOF. Since $\mu \in NI(G)$, we have $I_x(\mu) = x \odot_T \mu \odot_T x^{-1} = \mu$, where $I_x : G \to G$, $z \mapsto xzx^{-1}$ is an inner automorphism. But then using Proposition 4.19(iii), we obtain

$$x \odot_T \bar{\mu} \odot_T x^{-1} = \overline{x \odot_T \mu \odot x^{-1}} = \bar{\mu}.$$
(5.4)

Hence the result follows from [7, Theorem 5.2.1(N5)].

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