## G-H-KKM SELECTIONS WITH APPLICATIONS TO MINIMAX THEOREMS

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Based on the G-H-KKM selections, some nonempty intersection theorems and their applications to minimax inequalities are presented.

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## 1. Introduction

Minimax inequalities have numerous applications to variational inequalities, while variational inequalities turn out to be a powerful tool to the solvability of problems in elasticity and plasticity theory, heat conduction, diffusion theory, optimization theory, mathematical economics, and others.

Chang and Zhang [1] introduced the notion of the generalized quasiconcavity and obtained some nonempty intersection theorems and their applications to minimax inequalities in a linear topological space setting. Recently, Tan [4] extended this notion to the case of a G-convex space with applications to minimax theorems and saddle points. Our aim here is to present some G-H-KKM selection theorems and related applications to minimax inequalities in a G-H-space setting.

Let X be a topological space, P(X) denote the power set of X, and  $\langle X \rangle$ , a family of all nonempty finite subsets of X. Let  $\Delta^n$  denote a standard (n-1) simplex  $\{e_1, e_2, \ldots, e_n\}$  of  $\mathbb{R}^n$ .

**Definition 1.1:** A triple  $(X, H, \{p\})$  is called a *G*-*H*-space [6] if X is a topological space and  $H:(X) \rightarrow P(X) \setminus \{\emptyset\}$  is a mapping such that:

- (i) For each  $F, G \in \langle X \rangle$ , there exists  $F_1 \subset F$  such that  $F_1 \subset G$  implies  $H(F_1) \subset H(G)$ .
- (ii) For  $F = \{x_1, x_2, ..., x_n\} \in \langle X \rangle$ , there is a continuous mapping  $p: \Delta^n \to H(F)$  such that for  $\{i1, i2, ..., ik\} \subset \{1, 2, ..., n\}$ , we have  $p(\{e_{i1}, e_{i2}, ..., e_{ik}\}) \subset H(\{x_{i1}, x_{i2}, ..., x_{ik}\})$ , where  $\{x_{i1}, x_{i2}, ..., x_{ik}\} \subset F$ .

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A subset D of X is called finitely G-H-closed in X if for each  $A \in \langle X \rangle$ , there exists  $A \subset A$  such that D(-)H(A) is closed in H(A).

A subset K of X is said to be compactly closed in X if K(-)L is closed in L for all compact subsets L of X.

**Definition 1.2:** Let  $(X, H, \{p\})$  be a G-H-space and  $T: X \rightarrow P(X)$  a multivalued mapping. T is called a G-H-KKM mapping if for each  $\{x_1, x_2, \ldots, x_n\} \in \langle X \rangle$ , there exists  $\{x_{i1}, x_{i2}, \ldots, x_{ik}\} \subset \{x_1, x_2, \ldots, x_n\}$  such that

$$H(\{x_{i1}, x_{i2}, \dots, x_{ik}\}) \subset (\frac{k}{j-1})T(x_{ij}) \text{ for } \{i1, i2, \dots, ik\} \subset \{1, 2, \dots, n\}.$$

**Definition 1.3:** Let  $(X, H, \{p\})$  be a G-H-space and let  $M_1, M_2, \ldots, M_n$  be subsets of X. A subset  $\{x_1, x_2, \ldots, x_n\} \in \langle X \rangle$  is said to be a G-H-KKM selection for  $M_1, M_2, \ldots, M_n$  if for any  $\{x_{i1}, x_{i2}, \ldots, x_{ik}\} \subset \{x_1, x_2, \ldots, x_n\}$ , we have

$$H(\{x_{i1}, x_{i2}, \dots, x_{ik}\}) \subset (\frac{k}{j=1}) M_{ij} \text{ for } \{i1, i2, \dots, ik\} \subset \{1, 2, \dots, n\}.$$

This generalizes the notion of a KKM selection in a pseudoconvex space by Joo' and Kassay [2].

**Definition 1.4:** Let X be nonempty set and  $(Y, H, \{p\})$  a G-H-space. Let  $f: X \times Y \rightarrow R$ ,  $e: Y \rightarrow R$  and  $h: X \rightarrow R$  be functions. The function f is said to be 0-generalized G-H-quasiconcave (resp. 0-generalized G-H-quasiconvex) in its first variable x if for each  $\{x_1, x_2, \ldots, x_n\} \in \langle X \rangle$ , there exists  $\{v_1, v_2, \ldots, v_n\} \in \langle Y \rangle$  such that for each  $\{v_{i1}, v_{12}, \ldots, v_{ik}\} \subset \{v_1, v_2, \ldots, v_n\}$  and for any  $y_0 \in H(\{v_{i1}, v_{i2}, \ldots, v_{ik}\})$ , we have

$$\begin{split} \min_{\substack{1 \leq j \leq k}} & [f(x_{ij}, y_0) + e(y_0) - h(x_{ij})] \leq 0 \\ (\text{resp.} \quad \max_{\substack{1 \leq j \leq k}} [f(x_{ij}, y_0) + e(y_0) - h(x_{ij})] \geq 0), \end{split}$$

where  $\{i1, i2, ..., ik\} \subset \{1, 2, ..., n\}.$ 

This generalizes the notion of a 0-generalized quasiconcavity (0-generalized quasiconvexity) by Chang and Zhang [1].

## 2. G-H-KKM Theorems and Applications

In this section we first recall and obtain some auxiliary results and then establish some minimax theorems.

**Lemma 2.1:** [7] Let  $(X, H, \{p\})$  be a G-H-space and  $M_1, M_2, \ldots, M_n$  be finitely G-H-closed subsets of X. Suppose that  $M_1, M_2, \ldots, M_n$  have a G-KKM selection. Then  $(-)_{i=1}^n M_i \neq \emptyset$ .

**Proposition 2.1:** Let X be a nonempty set and  $(Y, H, \{p\})$  a G-H-space. Let  $f: X \times Y \rightarrow R$ ,  $e: Y \rightarrow R$  and  $h: X \rightarrow R$  be functions. Then the following statements are equivalent:

(a) A mapping  $T: X \rightarrow P(Y)$  defined by

$$T(x) = \{ y \in Y : f(x, y) + e(y) - h(x) \le 0 \}$$

$$(resp. T(x) = \{y \in Y: f(x, y) + e(y) - h(x) \ge 0\}),\$$

is a G-H-KKM mapping.

(b) f is 0-generalized G-H-quasiconcave (resp. 0-generalized G-H-quasiconvex) in its first variable x.

**Proof:**  $(a) \Rightarrow (b)$  Since T is G-H-KKM, it implies for each  $\{x_1, x_2, \ldots, x_n\} \in \langle X \rangle$  and corresponding  $\{v_1, v_2, \ldots, v_n\} \in \langle Y \rangle$  that there exist  $\{x_{i1}, x_{i2}, \ldots, x_{ik}\} \subset \{x_1, x_2, \ldots, x_n\}$ ,  $\{v_{i1}, v_{i2}, \ldots, v_{ik}\} \subset \{v_1, v_2, \ldots, v_k\}$  and any  $y_0 \in H(\{v_{i1}, v_{i2}, \ldots, v_{ik}\})$  such that

$$H(\{v_{i1}, v_{i2}, \dots, v_{ik}\}) \subset (\frac{k}{j-1})T(x_{ij}).$$

This implies  $y_0 \in (\frac{k}{j=1})T(x_{ij})$ , and as a result, there exists some index m  $(i \le m \le k)$  such that  $y_0 \in T(x_{im})$ . Hence,  $f(x_{im}, y_0) + e(y_0) - h(x_{im}) \le 0$  (resp.  $f(x_{im}, y_0) + e(y_0) - h(x_{im}) \ge 0$ ). It follows that

$$\begin{split} \min_{1 \le j \le k} & [f(x_{ij}, y_0) + e(y_0) - h(x_{ij})] \le 0\\ (\text{resp.} \quad \max_{1 \le j \le k} [f(x_{ij}, y_0) + e(y_0) - h(x_{ij})] \ge 0). \end{split}$$

 $\begin{array}{ll} (b) \Rightarrow (a) & \text{Since } f \text{ is 0-generalized G-H-quasiconcave (resp. 0-generalized G-H-quasiconvex) in } x, \text{ it implies for any } \{x_1, x_2, \ldots, x_n\} \in \langle X \rangle \text{ and } \{v_1, v_2, \ldots, v_n\} \in \langle Y \rangle, \text{ there exist } \{v_{i1}, v_{i2}, \ldots, v_{ik}\} \subset \{v_1, v_2, \ldots, v_n\}, \text{ and any } y_0 \in H(\{v_{i1}, v_{i2}, \ldots, v_{ik}\}) \text{ such that } \end{array}$ 

$$\min_{\substack{1 \le j \le k}} [f(x_{ij}, y_0) + e(y_0) - h(x_{ij})] \le 0$$
  
(resp. 
$$\max_{\substack{1 \le j \le k}} [f(x_{ij}, y_0) + e(y_0) - h(x) \ge 0).$$

It follows that there exists some index  $m \ (1 \le m \le k)$  such that  $y_0 \in T(x_m) \subset (\frac{k}{j=1})$  $T(x_{ij})$ . This completes the proof.

**Theorem 2.1:** Let X be a nonempty set and  $(Y, H, \{p\})$  a G-H-space such that H(F) is compact for all  $F \in \langle Y \rangle$ . Suppose that  $f: X \times Y \rightarrow R$ ,  $e: Y \rightarrow R$  and  $h: X \rightarrow R$  are functions satisfying the following assumptions:

- (i) f is lower semicontinuous in y on compact subsets of Y.
- (ii) e is lower semicontinuous on compact subsets of Y.
- (iii) f is 0-generalized G-H-quasiconcave in x.

(iv) There exists an element  $x_0 \in X$  such that the set

$$\{y \in Y {:}\, f(x_0,y) + e(y) - h(x_0) \leq 0\}$$

is a compact subset of Y.

Then there exists an element  $y \in Y$  such that

$$f(x, \underbrace{y}) + e(\underbrace{y}) - h(x) \le 0$$
 for all  $x \in X$ .

**Proof:** Let us define a mapping  $T: X \rightarrow P(Y)$  by

$$T(x) = \{y \in Y : f(x, y) + e(y) - h(x) \le 0\}$$
 for all  $x \in X$ .

Since f is 0-generalized G-H-quasiconcave, it implies that T(x) is nonempty. It follows from Proposition 2.1 that T is a G-H-KKM mapping. By (i) and (ii), each T(x) is finitely G-H-closed, that is, for each  $A \subset A \in \langle Y \rangle$ , we have

$$T(x)(-)H(A) = \{y \in H(A) : f(x,y) + e(y) - h(x) \le 0\}$$
  
=  $\{y \in H(A) : f(x,y) + e(y) \le h(x)\},$ 

is closed in  $H(\underline{A})$  by the lower semicontinuity of f and e, so the family  $\{T(x): x \in X\}$  has the finite intersection property by Lemma 2.1. Now applying (iv), we find that  $\{T(x)(-)T(x_0): x \in X\}$  is a family of compact subsets of Y. Hence,  $\binom{-}{x \in X}T(x) \neq \emptyset$ . That means, there exists an element  $\underbrace{y}_{\sim} \in Y$  such that

$$f(x, \underline{y}) + e(\underline{y}) - h(x) \le 0$$
 for all  $x \in X$ .

This completes the proof.

For Y compact, Theorem 2.1 reduces to:

**Theorem 2.2:** Let X be a nonempty set and  $(Y, H, \{p\})$  a compact G-H-space with H(F) compact for all  $F \in \langle Y \rangle$ . Suppose that  $f: X \times Y \rightarrow R$ ,  $e: Y \rightarrow R$  and  $h: X \rightarrow R$  are functions such that:

- (i) f is lower semicontinuous in second variable y.
- (ii) e is lower semicontinuous.

(iii) f is 0-generalized G-H-quasiconcave in first variable x.

Then there is an element  $y \in Y$  such that

$$f(x, y) + e(y) - h(x) \leq 0$$
 for all  $x \in X$ .

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