Mem. Differential Equations Math. Phys. 19(2000), 154-158

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ON NONNEGATIVE BOUNDED SOLUTIONS OF SYSTEMS OF LINEAR FUNCTIONAL DIFFERENTIAL EQUATIONS

(Reported on July 19, 1999)

1. Statement of the Problem and Formulation of the Main Results

Let \mathbb{R} be the set of real numbers, $C_{\text{loc}}(\mathbb{R}, \mathbb{R})$ be the space of continuous functions $u : \mathbb{R} \to \mathbb{R}$ with the topology of uniform convergence on every compact interval, $C_{\text{loc}}(\mathbb{R}; \mathbb{R}_+) = \{u \in C_{\text{loc}}(\mathbb{R}; \mathbb{R}) : u(t) \geq 0 \text{ for } t \in \mathbb{R}\}, L_{\text{loc}}(\mathbb{R}, \mathbb{R}) \text{ be the space of locally summable functions } u : \mathbb{R} \to \mathbb{R} \text{ with the topology of convergence in the mean on every compact interval, and <math>L_{\text{loc}}(\mathbb{R}; \mathbb{R}_+) = \{u \in L_{\text{loc}}(\mathbb{R}; \mathbb{R}) : u(t) \geq 0 \text{ for almost all } t \in \mathbb{R}\}.$ Consider the system of differential equations

$$x'_{i}(t) = p_{i}(t)x_{i}(t) + \sum_{k=1}^{n} \ell_{ik}(x_{k})(t) + q_{i}(t) \qquad (i = 1, \dots, n),$$
(1)

where $\ell_{ik}: C_{\text{loc}}(\mathbb{R}, \mathbb{R}) \to L_{\text{loc}}(\mathbb{R}, \mathbb{R})$ (i, k = 1, ..., n) are linear continuous operators, \underline{p}_i and $q_i \in L_{\text{loc}}(\mathbb{R}, \mathbb{R})$ (i = 1, ..., n). Moreover, there exist linear positive operators $\overline{\ell}_{ik}: C_{\text{loc}}(\mathbb{R}, \mathbb{R}) \to L_{\text{loc}}(\mathbb{R}, \mathbb{R})$ (i, k = 1, ..., n) such that for any $u \in C_{\text{loc}}(\mathbb{R}, \mathbb{R})$ the inequalities

$$|\ell_{ik}(u)(t)| \le \overline{\ell}_{ik}(|u|)(t) \qquad (i,k=1,\ldots,n)$$

are fulfilled almost everywhere on \mathbb{R} .

The simple but important case of (1) is the system of differential equations with deviating arguments

$$x'_{i}(t) = \sum_{k=1}^{n} \sum_{j=1}^{m} p_{ikj}(t) x_{k}(\tau_{ikj}(t)) + q_{i}(t) \qquad (i = 1, \dots, n),$$
(1')

where q_i and $p_{ikj} \in L_{loc}(\mathbb{R};\mathbb{R}), \tau_{ikj}:\mathbb{R}\to\mathbb{R}$ are measurable functions, and $\tau_{ii1}(t) \equiv t$. A locally absolutely continuous vector function $(x_i)_{i=1}^n:\mathbb{R}\to\mathbb{R}$ is called a nonnegative

bounded solution of the system (1) if it satisfies this system almost everywhere on \mathbb{R} ,

$$\sup\left\{\sum_{i=1}^{n} |x_i(t)| : t \in \mathbb{R}\right\} < +\infty,$$

and

$$x_i(t) \ge 0$$
 for $t \in \mathbb{R}$ $(i = 1, \dots, n)$.

¹⁹⁹¹ Mathematics Subject Classification. 34K25.

Key words and phrases. Linear functional differential equation, nonnegative bounded solution, existence, uniqueness.

I. Kiguradze [3], [4] has established optimal in some sense sufficient conditions of the existence and uniqueness of nonnegative bounded solutions of the differential system

$$\frac{dx_i(t)}{dt} = \sum_{k=1}^n p_{ik}(t) x_k(t) + q_i(t) \qquad (i = 1, \dots, n).$$

In the present paper these results are generalized for the systems (1) and (1'). Before formulating the main results we want to introduce some notation.

 δ_{ik} is Kronecker's symbol, i.e., $\delta_{ii} = 1$ and $\delta_{ik} = 0$ for $i \neq k$. $A = (a_{ik})_{i,k=1}^n$ is a $n \times n$ matrix with components a_{ik} $(i, k = 1, \ldots, n)$. r(A) is the spectral radius of the matrix A. $\mathcal{P}_{\mathbb{R}}$ is the set of linear operators mapping $C_{\text{loc}}(\mathbb{R}; \mathbb{R}_+)$ into $L_{\text{loc}}(\mathbb{R}; \mathbb{R}_+)$. If $t_i \in \mathbb{R} \cup \{-\infty, +\infty\}$ $(i = 1, \ldots, n)$, then

$$\mathcal{N}_0(t_1,\ldots,t_n)=\{i:t_i\in\mathbb{R}\}.$$

If $u \in L_{loc}(\mathbb{R}, \mathbb{R})$, then

$$\eta(u)(t,s)=\int\limits_t^s u(\xi)\,d\xi ext{ for }t ext{ and }s\in\mathbb{R}.$$

For $t_i \in \mathbb{R} \cup \{-\infty, +\infty\}$ (i = 1, ..., n) put

$$\sigma_i(t) = \operatorname{sgn}(t - t_i) \quad \text{if } t_i \in \mathbb{R},$$

$$\sigma_i(t) \equiv 1 \quad \text{if } t_i = -\infty, \qquad \sigma_i(t) \equiv -1 \quad \text{if } t_i = +\infty.$$

Theorem 1. Let there exist $t_i \in \mathbb{R} \cup \{-\infty, +\infty\}$ (i = 1, ..., n), a matrix $A = (a_{ik})_{i,k=1}^n \in \mathbb{R}^{n \times n}_+$, and a nonnegative number a such that

$$r(A) < 1, \tag{2}$$

$$\left|\int_{t_i}^t \exp\left(\int_s^t p_i(\xi)d\xi\right)|\ell_{ik}(1)(s)|ds\right| \le a_{ik} \quad for \ t \in \mathbb{R} \quad (i,k=1,\ldots,n),$$
(3)

$$\sum_{i=1}^{n} \left| \int_{t_i}^{t} \exp\left(\int_{s}^{t} p_i(\xi) d\xi\right) |q_i(s)| ds \right| \le a \quad \text{for } t \in \mathbb{R}$$

$$\tag{4}$$

and

$$\sup\left\{\int_{t_i}^t p_i(\xi)d\xi: t \in \mathbb{R}\right\} < +\infty \quad for \ i \in \mathcal{N}_0(t_1, \dots, t_n).$$
(5)

Let, moreover, $\sigma_i \ell_{ik} \in \mathcal{P}_{\mathbb{R}}$, $\sigma_i q_i \in L_{loc}(\mathbb{R}; \mathbb{R}_+)$. Then for any $c_i \in \mathbb{R}_+$ $(i \in \mathcal{N}_0(t_1, \ldots, t_n))$ the system (1) has at least one nonnegative bounded solution satisfying

$$x_i(t_i) = c_i \qquad for \ i \in \mathcal{N}_0(t_1, \dots, t_n).$$
(6)

Theorem 2. Let all the assumptions of Theorem 1 be fulfilled and

$$\liminf_{t \to t_i} \int_t^0 p_i(\xi) d\xi = -\infty \qquad for \ i \in \{1, \dots, n\} \setminus \mathcal{N}_0(t_1, \dots, t_n).$$

Then for any $c_i \in \mathbb{R}_+$ $i \in \mathcal{N}_0(t_1, \ldots, t_n)$ the system (1) has a unique bounded solution satisfying (6), and this solution is nonnegative.

If $t_i \in \{-\infty, +\infty\}$ (i = 1, ..., n), then $\mathcal{N}_0(t_1, ..., t_n) = \emptyset$. In that case in Theorems 1 and 2 the conditions (5) and (6) become unnecessary. Consequently, these theorems are formulated as follows:

Corollary 1. Let there exist $t_i \in \{-\infty, +\infty\}$ (i = 1, ..., n), a matrix $A = (a_{ik})_{i,k=1}^n \in \mathbb{R}^{n \times n}_+$ and a nonnegative number a such that the conditions (2) - (4) are fulfilled. Let, moreover, $\sigma_i \ell_{ik} \in \mathcal{P}_I$, $\sigma_i q_i \in L_{loc}(\mathbb{R}; \mathbb{R}_+)$. Then the system (1) has at least one nonnegative bounded solution.

Corollary 2. Let all the assumptions of Corollary 1 be fulfilled and

$$\liminf_{t \to t_i} \int_t^0 p_i(\xi) d\xi = -\infty \qquad (i = 1, \dots, n).$$

Then the system (1) has a unique bounded solution, and this solution is nonnegative.

The above theorems yield the following statements for the system (5.1').

Corollary 1'. Let $t_i \in \mathbb{R} \cup \{-\infty, +\infty\}$ (i = 1, ..., n),

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$$(1 - \delta_{ik}\delta_{j1})\sigma_i p_{ikj} \in L_{\text{loc}}(\mathbb{R};\mathbb{R}_+), \qquad \sigma_i q_i \in L_{\text{loc}}(\mathbb{R};\mathbb{R}_+)$$
(7)
$$(i, k = 1, \dots, n; \quad m = 1, 2, \dots),$$

there exist a matrix $A = (a_{ik})_{i,k=1}^n \in \mathbb{R}^{n \times n}_+$ and a nonnegative number a such that r(A) < 1,

$$\sum_{j=1}^{m} \int_{t_i}^{t} \exp\left(\int_{s}^{t} p_{ii1}(\xi) d\xi\right) (1 - \delta_{ik} \delta_{j1}) p_{ikj}(s) ds \le a_{ik} \quad \text{for } t \in \mathbb{R}$$

$$(i, k = 1, \dots, n),$$

$$(8)$$

$$\sum_{i=1}^{n} \int_{t_{i}}^{t} \exp\left(\int_{s}^{t} p_{ii1}(\xi)d\xi\right) q_{i}(s)ds \le a \qquad for \ t \in \mathbb{R}$$

$$\tag{9}$$

and

$$\sup\left\{\int_{t_i}^t p_{ii1}(\xi)d\xi: t \in \mathbb{R}\right\} < +\infty \quad for \ i \in \mathcal{N}_0(t_1,\ldots,t_n).$$

Then for any $c_i \in \mathbb{R}_+$ $(i \in \mathcal{N}_0(t_1, \ldots, t_n))$ the system (5.1') has at least one nonnegative bounded solution satisfying the conditions (6).

Corollary 2'. Let all the assumptions of Corollary 1' be fulfilled and

$$\liminf_{t \to t_i} \int_t^0 p_{ii1}(\xi) d\xi = -\infty \qquad for \ i \in \{1, \dots, n\} \setminus \mathcal{N}_0(t_1, \dots, t_n).$$

Then for any $c_i \in \mathbb{R}_+$ $(i \in \mathcal{N}_0(t_1, \ldots, t_n))$ the system (5.1') has a unique bounded solution satisfying the conditions (6), and this solution is nonnegative.

Corollary 3'. Let there exist $t_i \in R \cup \{-\infty, +\infty\}$, $b_i \in [0, +\infty[$, $b_{ik} \in [0, +\infty[$ ($i, k = 1, \ldots, n$) such that the condition (7) is fulfilled, the real part of every eigenvalue of the matrix $(-\delta_{ik}b_i + b_{ik})_{i,k=1}^n$ is negative and the inequalities

$$\sigma_i(t)p_{ii1}(t) \le -b_i, \quad \sum_{j=1}^m (1 - \delta_{ik}\delta_{j1})\sigma_i(t)p_{ikj}(t) \le b_{ik} \quad (i,k=1,\ldots,n)$$

hold almost everywhere on \mathbb{R} . Moreover, let

$$\sup\left\{\int_{t}^{t+1} |q_i(s)| ds : t \in R\right\} < +\infty \quad (i = 1, \dots, n).$$

$$(10)$$

Then for any $c_i \in \mathbb{R}_+$ $(i \in \mathcal{N}_0(t_1, \ldots, t_n))$ the system (5.1') a unique bounded solution satisfying conditions (6), and this solution is nonnegative.

Corollary 4'. Let there exist $t_i \in \{-\infty, +\infty\}$ (i = 1, ..., n), a matrix $A = (a_{ik})_{i,k=1}^n \in \mathbb{R}^{n \times n}_+$ and a nonnegative number a such that r(A) < 1 and the conditions (7) – (9) be fulfilled. Then the system (5.1') has at least one nonnegative bounded solution.

Corollary 5'. Let all the assumptions of Corollary 4' be fulfilled and

$$\liminf_{t \to t_i} \int_t^0 p_{ii1}(s) \, ds = -\infty \quad (i = 1, \dots, n).$$

Then the system (5.1') has a unique bounded solution, and this solution is nonnegative.

Corollary 6'. Let there exist $\sigma_i \in \{-1,1\}$, $b_i \in [0,+\infty[$ $(i,k = 1,\ldots,n)$ such that the condition (7) is fulfilled, the real part of every eigenvalue of the matrix $(-\delta_{ik}b_i + b_{ik})_{i,k=1}^n$ is negative and the inequalities

$$\sigma_i p_{ii1}(t) \le -b_i, \qquad \sum_{j=1}^m (1 - \delta_{ik} \delta_{j1}) \sigma_i p_{ikj}(t) \le b_{ik} \qquad (i, k = 1, \dots, n)$$

hold almost everywhere on \mathbb{R} . Moreover, if the conditions (10) are fulfilled, then the system (5.1') has a unique bounded solution, and this solution is nonnegative.

2. Proof of the Main Results

Proof of Theorem 1. By Theorem 1.1 in [1] we obtain that under the assumptions of Theorem 1 there exists at least one bounded solution $(x_i)_{i=1}^n$ of the equation (1), which is a uniform limit of the sequence of functions

$$x_{im}(t) = e_{im}(y_{im})(t)$$
 $(i = 1, ..., n; m = 1, 2, ...)$

where $(y_{im})_{i=1}^n$ is the solution of the problem

$$y'_{i}(t) = p_{im}(t)y_{i}(t) + \sum_{k=1}^{n} \ell_{ikm}(y_{k})(t) + q_{im}(t),$$

$$y_i(t_{im}) = c_{im},$$

on the segment $[a_m, b_m]$, $\{a_m\}_{m=1}^{+\infty}$, $\{b_m\}_{m=1}^{+\infty}$ are sequences of real numbers such that $a_m < b_m$, $t_i \in [a_m, b_m]$ for $i \in \mathcal{N}_0(t_1, \ldots, t_n)$ $(m = 1, 2, \ldots)$,

$$\lim_{m \to +\infty} a_m = -\infty, \qquad \lim_{m \to +\infty} b_m = +\infty,$$

 p_{im} and q_{im} are the restrictions of the functions p_i and q_i on the segment $[a_m, b_m]$,

$$\ell_{ikm}(u)(t) \equiv \ell_{ik}(e_m(u))(t),$$

where

$$e_m(u)(t) \stackrel{def}{\equiv} \begin{cases} u(t) & \text{for } a_m \leq t \leq b_m \\ u(a_m) & \text{for } t < a_m \\ u(b_m) & \text{for } t > b_m \end{cases},$$

 $c_{im} = c_i \text{ if } i \in \mathcal{N}_0(t_1, \dots, t_n), c_{im} = 0 \text{ if } i \in \{1, \dots, n\} \setminus \mathcal{N}_0(t_1, \dots, t_n), t_{im} = t_i \text{ if } t_i \in \mathbb{R},$ $t_{im} = a_m$ if $t_i = -\infty$, $t_{im} = b_m$ if $t_i = +\infty$ (i, k = 1, ..., n; m = 1, 2, ...). On the other hand, we have

$$y_{im}(t) \ge 0$$
 for $t \in [a_m, b_m]$ $(i = 1, ..., n; m = 1, 2, ...).$

Consequently,

$$x_i(t) > 0$$
 for $t \in \mathbb{R}$ $(i = 1, \dots, n)$.

ACKNOWLEDGEMENT

This work was supported by the Ministry of Education of the Czech Republic under the Research Intention No. $\mathrm{J07}/98{:}143$ 100 001.

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