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## EXISTENCE AND UNIQUENESS THEOREMS ON PERIODIC SOLUTIONS TO MULTIDIMENSIONAL LINEAR HYPERBOLIC EQUATIONS

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In  $\mathbb{R}^n$  consider the linear hyperbolic equations

$$u^{(\boldsymbol{m})} = \sum_{\boldsymbol{\alpha}\in\mathcal{E}^{\boldsymbol{m}}} p_{\boldsymbol{\alpha}}(\boldsymbol{x}_{\boldsymbol{\alpha}})u^{(\boldsymbol{\alpha})} + \sum_{\boldsymbol{\alpha}\in\mathcal{O}^{\boldsymbol{m}}} p_{\boldsymbol{\alpha}}(\boldsymbol{x}_{\boldsymbol{\alpha}})u^{(\boldsymbol{\alpha})} + q(\boldsymbol{x}),$$
(1)

and

$$u^{(\boldsymbol{m})} = p_{\boldsymbol{0}}(\boldsymbol{x})u + q(\boldsymbol{x}), \tag{2}$$

where  $n \geq 2$ ,  $\boldsymbol{x} = (x_1, \ldots, x_n) \in \mathbb{R}^n$ ,  $\boldsymbol{m} = (m_1, \ldots, m_n) \in \mathbb{Z}^n_+$  and  $\boldsymbol{\alpha} = (\alpha_1, \ldots, \alpha_n) \in \mathbb{Z}^n_+$  $\mathbb{Z}^n_+$  are multi–indeces , and

$$u^{(\boldsymbol{\alpha})} = \frac{\partial^{\alpha_1 + \dots + \alpha_n} u}{\partial x_1^{\alpha_1} \dots \partial x_n^{\alpha_n}}.$$

We make use of following notations and definitions.

 $\mathbb{Z}_+$  is the set of all nonnegative integers;  $\mathbb{Z}_+^n$  is the set of all multiindices  $\pmb{lpha}$  =  $(\alpha_1,\ldots,\alpha_n); \|\boldsymbol{\alpha}\| = \alpha_1 + \cdots + \alpha_n; \, \boldsymbol{0} = (0,\ldots,0) \in \mathbb{Z}_+^n.$ 

The inequalities between the multiindices  $\boldsymbol{\alpha} = (\alpha_1, \dots, \alpha_n)$  and  $\boldsymbol{\beta} = (\beta_1, \dots, \beta_n)$  are understood componentwise.

It will be assumed that m > 0.

If for some multiindex  $\boldsymbol{\alpha} = (\alpha_1, \ldots, \alpha_n)$  we have  $\alpha_{i_1} = \cdots = \alpha_{i_k} = 0$   $(i_1 < \cdots < i_k)$ , and  $\alpha_{j_1}, \ldots, \alpha_{j_{n-k}} > 0$   $(j_1 < \cdots < j_{n-k}), \{j_1, \ldots, j_{n-k}\} = \{1, \ldots, n\} \setminus \{i_1, \ldots, i_k\},\$ then by  $\boldsymbol{x}_{\boldsymbol{\alpha}}$  (by  $\boldsymbol{x}^{\boldsymbol{\alpha}}$ ) denote the vector  $(x_{i_1}, \ldots, x_{i_k}) \in \mathbb{R}^k$  (the vector  $(x_{j_1}, \ldots, x_{j_{n-k}}) \in \mathbb{R}^k$  $\mathbb{R}^{n-k}$ ). If  $\boldsymbol{\alpha} > \mathbf{0}$ , then in equation (1) by  $p_{\boldsymbol{\alpha}}(\boldsymbol{x}_{\boldsymbol{\alpha}})$  we understand a constant function.

A multiindex  $\boldsymbol{\alpha} \in \mathbb{Z}_{+}^{n}$  will be called *even*, if all its components are even. A multiindex  $\boldsymbol{\alpha} \in \mathbb{Z}_{+}^{n}$  will be called *odd*, if  $\|\boldsymbol{\alpha}\|$  is odd.

By  $\mathcal{E}^m$  and  $\mathcal{O}^m$ , respectively, denote the sets of all even and odd multiindices not exceeding  $\boldsymbol{m}$  and different from  $\boldsymbol{m}$ , i.e.,

$$\mathcal{E}^{\boldsymbol{m}} = \{ \boldsymbol{\alpha} \in \mathbb{Z}_{+}^{n} \setminus \{ \boldsymbol{m} \} : \boldsymbol{\alpha} \leq \boldsymbol{m}, \ \alpha_{1}, \dots, \alpha_{n} \text{ are even} \},$$

 $\mathcal{O}^{\boldsymbol{m}} = \big\{ \boldsymbol{\alpha} \in \mathbb{Z}_{+}^{n} \setminus \{ \boldsymbol{m} \} : \boldsymbol{\alpha} \leq \boldsymbol{m}, \ \alpha_{1} + \dots + \alpha_{n} \text{ is odd} \big\}.$ 

By  $S^{m}$  denote the set of nonzero multiindices  $\boldsymbol{\alpha} = (\alpha_1, \ldots, \alpha_n)$  whose components either equal to the corresponding components of  $\boldsymbol{m}$ , or equal to 0, i.e.,

 $\mathcal{S}^{\boldsymbol{m}} = \big\{ \boldsymbol{\alpha} \neq \boldsymbol{0} : \alpha_i \in \{0, m_i\} \ (i = 0, \dots, n) \big\}.$ 

Let  $\boldsymbol{\omega} = (\omega_1, \dots, \omega_n) \in \mathbb{R}^n$  b a vector with positive components. Then by  $\Omega$  denote the rectangular box  $[0, \omega_1] \times \cdots \times [0, \omega_n]$  in  $\mathbb{R}^n$ . Moreover, for an arbitrary multiindex  $\boldsymbol{\alpha}$ , similarly as we did above, introduce the vectors  $\boldsymbol{\omega}_{\boldsymbol{\alpha}} = (\omega_{i_1}, \ldots, \omega_{i_k}) \in \mathbb{R}^k$  and  $\boldsymbol{\omega}^{\boldsymbol{\alpha}} = (\omega_{j_1}, \ldots, \omega_{j_{n-k}}) \in \mathbb{R}^{n-k}$ , and the rectangular boxes  $\Omega_{\boldsymbol{\alpha}} = [0, \omega_{i_1}] \times \cdots \times [0, \omega_{i_k}]$  in  $\mathbb{R}^k$  and  $\Omega^{\boldsymbol{\alpha}} = [0, \omega_{j_1}] \times \cdots \times [0, \omega_{j_{n-k}}]$  in  $\mathbb{R}^{n-k}$ .

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We say that a function  $z: \mathbb{R}^n \to \mathbb{R}$  is  $\boldsymbol{\omega}$ -periodic, if

$$z(x_1,\ldots,x_j+\omega_j,\ldots,x_n)\equiv z(x_1,\ldots,x_n) \quad (j=1,\ldots,n).$$

It will be assumed that the functions  $p_{\alpha}$  ( $\alpha \in \mathcal{E}^m \cup \mathcal{O}^m$ ) and q, respectively, are  $\omega_{\alpha}$ -periodic and  $\omega$ -periodic continuous functions.

Let  $l = (l_1, \ldots, l_n) \in \mathbb{Z}_+^n$ . By  $C^l$  denote the space of continuous functions  $u : \mathbb{R}^n \to \mathbb{R}$ , having continuous partial derivatives  $u^{(\alpha)}$   $(\alpha \leq l)$ .

By a solution of equation (1) (equation (2)) we will understand a *classical solution*, i.e., a function  $u \in C^{\mathbf{m}}$  satisfying equation (1) (equation (2)) everywhere in  $\mathbb{R}^{n}$ .

In the case, where n = 2,  $m_1 = m_2 = 1$   $(n = 2, m_1 = m_2 = 2)$  sufficient conditions for existence and uniqueness of  $(\omega_1, \omega_2)$ -periodic solutions of equation (1) are given in [1–3, 6–8] (in [9, 10]). In the general case the problem on  $\boldsymbol{\omega}$ -periodic solutions to equations (1) and (2) are little investigated. In the present paper optimal sufficient conditions of existence and uniqueness of  $\boldsymbol{\omega}$ -periodic solutions to equation (1) (equation (2)) are given. Similar results for higher order nonlinear ordinary differential equations were obtained by I. Kiguradze and T. Kusano [5].

We consider equations (1) and (2) in two cases, where  $\boldsymbol{m}$  is either even, or odd. Also note that equations (1) and (2) do contain partial derivatives with even or odd (according to the above definitions) multiindices only (e.g., neither of  $\boldsymbol{m}$  and  $\boldsymbol{\alpha}$  can equal to (1, 1, 1, 1)).

Theorem 1. Let *m* be even, and let

. . . .

$$(-1)^{\frac{\|\boldsymbol{m}\|+\|\boldsymbol{\alpha}\|}{2}} p_{\boldsymbol{\alpha}}(\boldsymbol{x}_{\boldsymbol{\alpha}}) \leq 0 \quad for \quad \boldsymbol{x} \in \mathbb{R}^{n} \quad \boldsymbol{\alpha} \in \mathcal{E}^{\boldsymbol{m}},$$
(3)

$$\overline{\mathbb{R}^n \setminus I_{p_0}} = \mathbb{R}^n, \tag{4}$$

where  $I_{p_0} = \{ \boldsymbol{x} \in \mathbb{R}^n : p_0(\boldsymbol{x}) = 0 \}$ . Then equation (1) has at most one  $\boldsymbol{\omega}$ -periodic solution.

**Theorem 2.** Let m be odd, and let there exist  $j \in \{1, 2\}$  such that along with (4) the inequality

$$(-1)^{j+\frac{\|\boldsymbol{\alpha}\|}{2}}p_{\boldsymbol{\alpha}}(\boldsymbol{x}_{\boldsymbol{\alpha}}) \leq 0 \quad for \quad \boldsymbol{x} \in \mathbb{R}^n \quad \boldsymbol{\alpha} \in \mathcal{E}^{\boldsymbol{m}}$$
(5)

holds. Then equation (1) has at most one  $\boldsymbol{\omega}$ -periodic solution.

Theorems 1 and 2 almost immediately follow from the following lemma.

**Lemma 1.** Let  $u \in C^m$  be an  $\omega$ -periodic function. Then

$$\begin{split} \int_{\Omega^{\boldsymbol{\alpha}}} u^{(\boldsymbol{\alpha})}(\boldsymbol{x}) \, u(\boldsymbol{x}) \, d\boldsymbol{x}^{\boldsymbol{\alpha}} &= (-1)^{\frac{\|\boldsymbol{\alpha}\|}{2}} \int_{\Omega^{\boldsymbol{\alpha}}} \left| u^{\left(\frac{\boldsymbol{\alpha}}{2}\right)}(\boldsymbol{x}) \right|^{2} d\boldsymbol{x}^{\boldsymbol{\alpha}} \quad \text{for} \quad \boldsymbol{\alpha} \in \mathcal{E}^{\boldsymbol{m}}, \\ \int_{\Omega^{\boldsymbol{\alpha}}} u^{(\boldsymbol{\alpha})}(\boldsymbol{x}) \, u(\boldsymbol{x}) \, d\boldsymbol{x}^{\boldsymbol{\alpha}} &= 0 \quad \text{for} \quad \boldsymbol{\alpha} \in \mathcal{O}^{\boldsymbol{m}}. \end{split}$$

One can easily prove the lemma using integration by parts and taking into consideration  $\omega$ -periodicity of u.

Proof of Theorem 1. All we need to prove is that if  $q(\mathbf{x}) \equiv 0$ , then equation (1) has only a trivial  $\boldsymbol{\omega}$ -periodic solution. Indeed, let  $q(\mathbf{x}) \equiv 0$ , and let u be an arbitrary  $\boldsymbol{\omega}$ -periodic solution of equation (1). After multiplying equation (1) by u and integrating over the rectangular box  $\Omega$ , by Lemma 1 and condition (3), we get

$$\int_{\Omega} \left( \left| u^{\left(\frac{m}{2}\right)}(\boldsymbol{x}) \right|^{2} + \sum_{\boldsymbol{\alpha} \in \mathcal{E}^{\boldsymbol{m}}} \left| p_{\boldsymbol{\alpha}}(\boldsymbol{x}_{\boldsymbol{\alpha}}) \right| \left| u^{\left(\frac{\alpha}{2}\right)}(\boldsymbol{x}) \right|^{2} \right) d\boldsymbol{x} = 0.$$
(6)

(4) and (6) immediately imply that  $u(\boldsymbol{x}) \equiv 0$ .

We omit the proof of Theorem 2, since it is similar to the proof of Theorem 1.

**Theorem 3.** Let m be even, and let

$$0 \le (-1)^{\frac{\|\boldsymbol{m}\|}{2}} p_{\boldsymbol{0}}(\boldsymbol{x}) < \frac{(2\pi)^{\|\boldsymbol{m}\|}}{\omega_1^{m_1} \cdots \omega_n^{m_n}}, \quad \overline{\mathbb{R}^n \setminus I_{p_{\boldsymbol{0}}}} = \mathbb{R}^n.$$
(7)

Then equation (2) has at most one  $\boldsymbol{\omega}$ -periodic solution.

To prove the theorem along with Lemma 1 we need the following

**Lemma 2.** Let m be even, and let  $u \in C^m$  be an  $\omega$ -periodic function. Then

$$\int_{\Omega} \left| u^{\left(\frac{\boldsymbol{m}}{2}\right)}(\boldsymbol{x}) \right|^2 d\boldsymbol{x} \le \frac{\omega_1^{m_1} \cdots \omega_n^{m_n}}{(2\pi)^{\|\boldsymbol{m}\|}} \int_{\Omega} \left| u^{(\boldsymbol{m})}(\boldsymbol{x}) \right|^2 d\boldsymbol{x}.$$
(8)

This lemma immediately follows from Wirtinger's inequality ([4], Theorem 258).

Proof of Theorem 3. Assume the contrary: let  $q(\mathbf{x}) \equiv 0$  and equation (2) have a nontrivial  $\omega$ –periodic solution u. Then we have

$$u^{(\boldsymbol{m})}(\boldsymbol{x}) = p_{\boldsymbol{0}}(\boldsymbol{x})u(\boldsymbol{x}) \tag{9}$$

and

$$|u^{(m)}(\boldsymbol{x})|^2 = |p_0(\boldsymbol{x})u(\boldsymbol{x})|^2.$$
 (10)

ŀ Multiplying (9) by u, integrating over  $\Omega$ , by Lemma 1, we get

$$\int_{\Omega} |p_{\mathbf{0}}(\boldsymbol{x})| |u(\boldsymbol{x})|^2 \, d\boldsymbol{x} = \int_{\Omega} |u^{\left(\frac{\boldsymbol{m}}{2}\right)}(\boldsymbol{x})|^2 \, d\boldsymbol{x}. \tag{11}$$

Integrating (10) over  $\Omega$  and assuming that  $u(\boldsymbol{x}) \neq 0$ , by condition (8), we get

$$\int_{\Omega} \left| u^{(\boldsymbol{m})}(\boldsymbol{x}) \right|^2 d\boldsymbol{x} = \int_{\Omega} \left| p_{\boldsymbol{0}}(\boldsymbol{x}) u(\boldsymbol{x}) \right|^2 d\boldsymbol{x} < \frac{(2\pi)^{\|\boldsymbol{m}\|}}{\omega_1^{m_1} \cdots \omega_n^{m_n}} \int_{\Omega} \left| p_{\boldsymbol{0}}(\boldsymbol{x}) \right| \left| u(\boldsymbol{x}) \right|^2 d\boldsymbol{x}.$$
(12)

On the other hand, from (8) and (11) we get the inequality

$$\int_{\Omega} |p_{\mathbf{0}}(\boldsymbol{x})| |u(\boldsymbol{x})|^2 \, d\boldsymbol{x} \leq \frac{\omega_1^{m_1} \cdots \omega_n^{m_n}}{(2\pi)^{\|\boldsymbol{m}\|}} \int_{\Omega} |u^{(\boldsymbol{m})}(\boldsymbol{x})|^2 \, d\boldsymbol{x},$$

which contradicts to (12). The obtained contradiction completes the proof of the theorem. 

Remark 1. In Theorem 3 condition (7) is optimal and it cannot we weakened: strict inequality cannot be replaced by an unstrict one. Indeed, consider the equation

$$u^{(\boldsymbol{m})} = l \ u, \tag{13}$$

where l is a constant. If

$$0 < l < (-1)^m \frac{(2\pi)^{\|\boldsymbol{m}\|}}{\omega_1^{m_1} \cdots \omega_n^{m_n}}$$

then by Theorem 3 equation (13) has only a trivial solution. However, if

$$l = (-1)^m \frac{(2\pi)^{\|m\|}}{\omega_1^{m_1} \cdots \omega_n^{m_n}} \quad (l = 0),$$

then it is obvious that the function

$$u(\boldsymbol{x}) = \sin\left(\frac{2\pi}{\omega_1}x_1\right)\cdots\sin\left(\frac{2\pi}{\omega_n}x_n\right) \quad (u(\boldsymbol{x})=1)$$

is a nontrivial  $\omega$ -solution of equation (13).

Below we formulate existence theorems.

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**Theorem 4.** Let m be even, and let along with (3) the inequalities

$$(-1)^{\frac{\|\boldsymbol{m}\|+\|\boldsymbol{\alpha}\|}{2}} \int_{\Omega_{\boldsymbol{\alpha}}} p_{\boldsymbol{\alpha}}(\boldsymbol{x}_{\boldsymbol{\alpha}}) \, d\boldsymbol{x}_{\boldsymbol{\alpha}} < 0 \quad \text{for} \quad \boldsymbol{\alpha} \in \mathcal{S}^{\boldsymbol{m}}, \qquad (14)$$
$$\int_{\Omega} p_{\boldsymbol{0}}(\boldsymbol{x}) \, d\boldsymbol{x} \neq 0$$

hold. Then equation (1) has one and only one  $\omega$ -periodic solution.

**Theorem 5.** Let  $m_1$  be the only odd component of the the multiindex m, and let there exist  $j \in \{1, 2\}$  such that along with (5) the inequalities

$$(-1)^{j+\frac{\|\boldsymbol{\alpha}\|}{2}} \int_{\Omega_{\boldsymbol{\alpha}}} p_{\boldsymbol{\alpha}}(\boldsymbol{x}_{\boldsymbol{\alpha}}) \, d\boldsymbol{x}_{\boldsymbol{\alpha}} < 0 \quad \text{for} \quad \boldsymbol{\alpha} \in \mathcal{S}^{\boldsymbol{m}},$$

$$(-1)^{j} \int_{0}^{\omega_{2}} \dots \int_{0}^{\omega_{n}} p_{\boldsymbol{0}}(x_{1}, x_{2}, \dots, x_{n}) \, dx_{2} \dots dx_{n} < 0 \quad \text{for} \quad x_{1} \in \mathbb{R}$$

$$(15)$$

hold. Then equation (1) has one and only one  $\omega$ -periodic solution.

Remark 2. In Theorems 4 (Theorem 5) condition (14) (condition (15)) is essential and it cannot be weakened. If for at least one  $\alpha \in S^m p_\alpha(\mathbf{x}_\alpha) \equiv 0$ , then equation (1) may not have an  $\boldsymbol{\omega}$ -periodic solution. To verify this, consider the equation

$$u^{(2,2,2)} = u^{(2,2,0)} + u^{(2,0,2)} + u^{(0,2,2)} - u^{(0,2,0)} - u^{(0,0,2)} + \sin^2(x_1)u - 1.$$
(16)

In the case, where n = 3,  $m_1 = m_2 = m_3 = 2$  and  $\omega_1 = \omega_2 = \omega_3 = \pi$ , this equation satisfies all of the conditions of Theorem 4, except condition (14). For  $\boldsymbol{\alpha} = (2,0,0)$  we have  $p_{\boldsymbol{\alpha}}(x_2, x_3) \equiv 0$ . As a result equation (16) has no  $(\pi, \pi, \pi)$ -periodic solution. Assume the contrary: let equation (16) have a  $(\pi, \pi, \pi)$ -periodic solution u. By Theorem 1, it is unique, and therefore is independent of  $x_2$  and  $x_3$ . Hence u satisfies the equation

$$\sin^2(x_1) \, u - 1 = 0$$

But the latter equation has only a discontinuous solution. The obtained contradiction proves that equation (16) has no  $(\pi, \pi, \pi)$ -periodic solution.

**Theorem 6.** Let m be even, and let

$$0 < (-1)^{\frac{\|\boldsymbol{m}\|}{2}} p_{\mathbf{0}}(\boldsymbol{x}) < \frac{(2\pi)^{\|\boldsymbol{m}\|}}{\omega_{1}^{m_{1}} \cdots \omega_{n}^{m_{n}}}.$$
(17)

Moreover, let  $p_0$  and  $q \in C^m$ . Then equation (2) has one and only one  $\omega$ -periodic solution.

Theorem 7. Let *m* be even, and let

$$(-1)^{\frac{\|\boldsymbol{m}\|}{2}} p_{\mathbf{0}}(\boldsymbol{x}) < 0 \quad for \quad \boldsymbol{x} \in \mathbb{R}^{n}.$$

$$(18)$$

Moreover, let  $p_0$  and  $q \in C^m$ . Then equation (2) has one and only one  $\omega$ -periodic solution.

**Theorem 8.** Let m be odd, and let there exist a number  $j \in \{1, 2\}$  such that

$$(-1)^{j} p_{\mathbf{0}}(\boldsymbol{x}) < 0 \quad for \quad \boldsymbol{x} \in \mathbb{R}^{n}.$$

$$\tag{19}$$

Moreover, let  $p_0$  and  $q \in C^m$ . Then equation (2) has one and only one  $\omega$ -periodic solution.

Remark 3. In Theorems 6, 7 and 8 the requirement of additional regularity of functions  $p_0$  and q is sharp. If this condition is violated, then equation (2) may not have a  $\omega$ -periodic classical solution. Indeed, consider the equation

$$u^{(m)} = p_0(x_2, \dots, x_n) u - p_0^2(x_2, \dots, x_n),$$

where  $\boldsymbol{m}$  is even, and  $p_0(x_2, \ldots, x_n)$  is an arbitrary continuous  $(\omega_2, \ldots, \omega_n)$ -periodic function satisfying (18). By Theorem 3, this equation has at most one solution. Hence

$$u(\boldsymbol{x}) = p_{\boldsymbol{0}}(x_2, \dots, x_n).$$

But u is a classical solution if and only if  $p_0 \in C^m$ .

Remark 4. In Theorems 6, 7 and 8, respectively, the strict inequalities (17), (18) and (19) cannot be replaced by unstrict ones. To verify this, consider the equation

$$u^{(m)} = p_0(x_2, \dots, x_n) u - 1,$$

where m is odd and  $p_0(x_2, \ldots, x_n)$  is an smooth  $(\omega_2, \ldots, \omega_n)$ -periodic function such that  $p_0(x_2, \ldots, x_n) \ge 0$ ,  $p_0(x_2, \ldots, x_n) \ne 0$ . By Theorem 2, this equation has at most one solution. Therefore u is a solution of the equation

$$p_0(x_2,\ldots,x_n)\,u-1=0.$$

But the latter equation has a continuous solution if and only if

$$p_0(x_2,\ldots,x_n) > 0$$
 for  $(x_2,\ldots,x_n) \in \mathbb{R}^{n-1}$ 

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