

κ -Deformations and Extended κ -Minkowski Spacetimes*

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Abstract. We extend our previous study of Hopf-algebraic κ -deformations of all inhomogeneous orthogonal Lie algebras $\text{iso}(g)$ as written in a tensorial and unified form. Such deformations are determined by a vector τ which for Lorentzian signature can be taken time-, light- or space-like. We focus on some mathematical aspects related to this subject. Firstly, we describe real forms with connection to the metric's signatures and their compatibility with the reality condition for the corresponding κ -Minkowski (Hopf) module algebras. Secondly, h -adic vs q -analog (polynomial) versions of deformed algebras including specialization of the formal deformation parameter κ to some numerical value are considered. In the latter the general covariance is lost and one deals with an orthogonal decomposition. The last topic treated in this paper concerns twisted extensions of κ -deformations as well as the description of resulting noncommutative spacetime algebras in terms of solvable Lie algebras. We found that if the type of the algebra does not depend on deformation parameters then specialization is possible.

Key words: quantum deformations; quantum groups; quantum spaces; reality condition for Hopf module algebras; q -analog and specialization versions; κ -Minkowski spacetime; extended κ -deformations; twist-deformations; classification of solvable Lie algebras

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1 Introduction

Recently we have proposed a unified description for Drinfel'd type quantization of inhomogeneous orthogonal algebras $\text{iso}(g)$ [26] corresponding to the noncommutative spacetime of the form: $[x^\mu, x^\nu] = \frac{i}{\kappa}(\tau^\mu x^\nu - \tau^\nu x^\mu)$ [51, 56] (we shall call it $\kappa(\tau)$ -Minkowski spacetime). In this paper we want to discuss related problems with this generalized $\kappa(\tau)$ -deformation. Historically, the κ -Minkowski spacetime [64, 87] was the first example of a noncommutative spacetime of the Lie-algebraic type, where the time coordinate does not commute with the space coordinates. It is the time-like ($\tau^0 \neq 0$) version of above, more general noncommutative spacetime. The κ -Minkowski spacetime was inspired by the introduction of the deformed Poincaré Hopf algebra in 1991 [57, 58] with the deformation parameter 'kappa' of mass dimension (which is usually interpreted as Planck mass or quantum gravity scale). Lie algebraic noncommutativity, including κ -Minkowski, have been further investigated by many authors in the wide range of applications, among others in deformation of special relativity framework [27, 53], noncommutative field theories [4, 7, 32, 34, 35, 37, 41, 43, 67, 69, 80], deformed statistics [33, 42, 44, 85],

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Planck scale physics [17, 45] and quantum gravity phenomenology [1, 2, 3, 46]. Moreover due to the fact that in the context of $(2 + 1)$ -dimensional quantum gravity noncommutative spacetime geometry and deformations of Poincaré symmetry arise naturally, recently the κ -deformation in $(2 + 1)$ dimensions has attracted quite some attention as well, see e.g. [10, 11, 12, 65, 71]. In [26] the deformation of the symmetry algebra (i.e. generalized for any τ the κ -deformed inhomogeneous orthogonal Hopf algebra $U_{\kappa,\tau}(\text{iso}(g))$) was determined by a metric tensor g of any dimension and arbitrary signature. Such formulation allows for many applications within the deformed general relativity and Planck scale physics, including $(2 + 1)$ -dimensional case allowing for relation with quantum gravity models. The deformation of inhomogeneous orthogonal algebras corresponding to $\kappa(\tau)$ -Minkowski spacetime explicitly depends on the choice of an additional vector field τ which at the same time parameterizes classical r -matrices and distinguishes between nonequivalent deformations¹.

In this paper we want to focus on mathematical issues connected with this generalized $\kappa(\tau)$ -deformation and discuss related problems. The framework of Drinfel'd type of deformations [38, 39] requires the so-called h -adic topology [29, 50], i.e. dealing with formal power series therefore one usually uses in fact topological completion $U(\text{iso}(g))[[\frac{1}{h}]]$. The version of κ -Poincaré algebra used by many authors [57, 58, 59, 64] in a traditional approach is (implicitly) of such ' h -adic' type. In this approach the deformation parameter κ cannot take a numerical value and must stay formal which makes it difficult to undergo some physical interpretation, e.g., as Planck mass or quantum gravity scale. Nevertheless there exists a method which in some cases allows deformation parameter to take a constant (numerical) value. In this sense the κ -Poincaré quantum group with h -adic topology as described before [51, 56, 57, 58, 59, 64, 87], is not the only possible version. In this paper we will reformulate this traditional Hopf algebra to hide the infinite series on the abstract level. This is known to be always possible in the framework of Drinfel'd–Jimbo standard quantization of semi-simple Lie algebras. As a first step, one distinguishes certain sub-Hopf algebra which can be treated as a Hopf algebra over polynomial ring $\mathbb{C}[q, q^{-1}]$ (the so called ' q -analog' version), in this way, getting rid off h -adic topology. Next we create new Hopf algebra by setting up (specializing) the formal parameter q to some numerical (complex in general) value. As a result, one obtains a one-parameter family of new Hopf algebras labeled by the numerical parameter which (when real) could be interpreted as some physical quantity. Usually, the value of the parameter matters and may lead to non-isomorphic Hopf algebras (e.g., for roots of unity) or influence representation theory. In our case a real value for this parameter is dictated by real forms of (complex) Hopf algebras under consideration which can be extended to module algebras as well. These issues are studied with more care.

In the following we shall introduce the ' q -analog' version of $\kappa(\tau)$ -deformation of non-semi-simple inhomogeneous orthogonal algebras $\text{iso}(g)$, for all values of the vector τ with a fixed deformation parameter, i.e. $\kappa \in \mathbb{C}$. It appears that in this case one can re-scale all the formulas to get rid off the deformation parameter altogether. Firstly we recall the case of the orthogonal $D = 1 + (D - 1)$ decomposition for time-like τ and introduce its q -analog version (analogous arguments will hold for space-like case as well). Later we consider the null-plane deformation and $D = 2 + (D - 2)$ decomposition. One should underline that the q -analog version has been common for the standard deformations (i.e. for which r -matrix satisfies modified Yang–Baxter equation (MYBE), as in the time-like case). On the contrary it is rather unexpected for non-standard deformations (i.e. for which r -matrix satisfies classical YBE and when the twist exists, like in the light-like case). As a by-product we show that specialization procedure can be also applied to the extended Jordanian twist deformations. Also the underlying covariant quantum

¹For the Lorentzian signature we can distinguish three (nonequivalent) Hopf-algebraic deformations: time-like, space-like (a.k.a. tachyonic) and light-like (a.k.a. light-cone) quantizations of the Poincaré algebra, represented by different choices of vector τ , i.e. $(1, 0, 0, 0)$, $(1, 0, 0, 1)$ and $(0, 0, 0, 1)$ respectively, provided that the metric is in diagonal form: $g_{\mu\nu} = (-, +, +, +)$.

space, together with its real form, is introduced in the q -analog as well as specialized version. Such $\kappa(\tau)$ -Minkowski spacetime with fixed value of parameter κ is an universal envelope of solvable Lie algebra without h -adic topology. This version has been already considered by some authors, e.g. in the context of spectral triples [30, 40, 47, 48, 70] and group field theory [75].

As a final issue related with $\kappa(\tau)$ -deformation, we shall deal in this paper, is the possibility of extending the κ -deformations via twisting. Quantum deformations for Lorentz and Poincaré symmetries have been classified in terms of classical r -matrices [88]. For example the original κ -deformation of Poincaré algebra corresponds to $r = M_{0i} \wedge P^i$. It is a particular case of more general family $r_\tau = \tau^\alpha M_{\alpha\mu} \wedge P^\mu$ found for any non-zero vector τ by Zakrzewski [88]. It has been shown in the same paper that r_τ admits extensions $r_\tau + \xi r'$ with an additional parameter ξ , where r' corresponds to some specific triangular deformations. The passage from a classical r -matrix to the corresponding deformation is, in general, non trivial task even in a triangular case: as an intermediate step one needs to construct a twisting element before quantizing. Twisting two-tensors corresponding to Zakrzewski's scheme have been already found in [83, 84] (see also [19, 20, 21, 22, 55, 61]). Here we use such twists (corresponding to the extended classical r -matrices) in order to deform $\kappa(\tau)$ -Minkowski spacetime algebra and describe resulting algebras in terms of solvable Lie algebras. To this aim we use classification scheme of low-dimensional solvable Lie algebras proposed in [36]. As a final task in this paper we calculate the deformed coproducts for some selected twistings of the κ -deformations. It turns out that the possibility of their specialization is related with the type of twisted κ -Minkowski spacetime algebras.

2 $\kappa(\tau)$ -deformations for (inhomogeneous) orthogonal Lie algebras

Here we recall the form of κ -deformations recently written in an unified way [26]. Let V be a D -dimensional (real) vector space equipped with a metric tensor g of arbitrary signature (p, q) , $p + q = D$. For an arbitrary basis $\{e_\mu\}_{\mu=0}^{D-1}$ one can introduce its components $g_{\mu\nu} = g(e_\mu, e_\nu)$. Making use of the dual basis $\{e^\mu\}_{\mu=0}^{D-1}$ in the dual vector space $V^\#$ one can write $g = g_{\alpha\beta} e^\alpha \otimes e^\beta$. It is well-known that Lie algebra of inhomogeneous orthogonal group $\text{ISO}(g)$ consists of $\frac{1}{2}D(D+1)$ generators $(M_{\mu\nu}, P_\alpha)$ adapted to a choice of the basis and satisfying the standard commutation relations

$$[M_{\mu\nu}, M_{\rho\lambda}] = i(g_{\mu\lambda}M_{\nu\rho} - g_{\nu\lambda}M_{\mu\rho} + g_{\nu\rho}M_{\mu\lambda} - g_{\mu\rho}M_{\nu\lambda}), \quad (2.1)$$

$$[M_{\mu\nu}, P_\rho] = i(g_{\nu\rho}P_\mu - g_{\mu\rho}P_\nu), \quad [P_\mu, P_\lambda] = 0. \quad (2.2)$$

The relation with the basis $\{e_\mu\}_{\mu=0}^{D-1}$ of V is throughout the complexify vector representation²

$$M_{\mu\nu} \mapsto -i(g_{\mu\alpha}e_\nu - g_{\nu\alpha}e_\mu) \otimes e^\alpha \in \text{End } V \otimes \mathbb{C} \quad (2.3)$$

acting in the complexified vector space $V \otimes \mathbb{C}$. In fact, the generators $(M_{\mu\nu}, P_\alpha)$ belong to the complexified Lie algebra $\text{iso}(g)$. However, for the purpose of this paper we shall treat the relations (2.1), (2.2) as generating ones for a complex universal enveloping algebra $U(\text{iso}(g))$ of $\text{iso}(g)$ understood as a free (complex) unital associative algebra generated by the symbols $(M_{\mu\nu}, P_\alpha)$ and factorized further by a two-sided ideal generated by the relations (2.1), (2.2). It is also customary to consider real algebras as complex ones equipped additionally with the structure of involutive anti-linear anti-automorphism, the so-called $*$ -conjugation: $X \mapsto X^*$, i.e. having the same formal properties as a Hermitean conjugation. In our case the choice of

²Throughout this paper we shall use the standard covariant Einstein's convention under which the repeated covariant and contravariant indices indicate summation, as well as the possibility of lowering and rising indices by the metric $g_{\alpha\beta}$ and its inverse $g^{\alpha\beta}$.

real structure is completely determined by the requirement that the generators (2.1), (2.2) are self-conjugated (formally Hermitean or self-adjoint), i.e.

$$X = X^* \quad \text{for } X \in (M_{\mu\nu}, P_\alpha) \quad (2.4)$$

since the relations (2.1), (2.2) are invariant with respect to such conjugation³. It is well-known that real structures defined in this way are in one-to-one correspondence with the metric signatures (p, q) , however complexified algebra is signature independent.

It has been found in [88] that for any (non-zero) vector $\tau = \tau^\mu e_\mu \in V$ (and any metric tensor $g_{\mu\nu}$ as above) one can introduce the corresponding classical r -matrix

$$r_{(\tau, g)} = \tau^\alpha M_{\alpha\mu} \wedge P^\mu \equiv \tau^\alpha g^{\beta\sigma} M_{\alpha\beta} \wedge P_\sigma \equiv \frac{1}{2} \tau_\perp \Omega_g \in \wedge^2 \text{iso}(g), \quad (2.5)$$

where $\Omega_g = M_{\mu\nu} \wedge P^\mu \wedge P^\nu$ is known to be the only invariant element in $\wedge^3 \text{iso}(g)$ and τ_\perp is used for contraction with the vector τ . The Schouten bracket reads

$$[[r_{(\tau, g)}, r_{(\tau, g)}]] = -\tau_g^2 \Omega_g, \quad (2.6)$$

where $\tau_g^2 \equiv \tau^\mu \tau_\mu \equiv g_{\mu\nu} \tau^\mu \tau^\nu$ denotes the scalar square of τ with respect to the metric g . One should notice that the case $\tau_g^2 = 0$, which is only possible for non-Euclidean signature, provides a solution of the classical (non-modified) Yang–Baxter equation. Further on we shall simplify the notation and drop off the sub-index referring to the metric g .

We are now in position to introduce the corresponding quantized Hopf algebra structure. According to [88] non-equivalent quantizations are classified by the conjugation classes of the stability subgroups G_τ of the vector τ ⁴. For a non-Euclidean metric it provides three non-isomorphic cases, which for the Lorentzian signature are the very well-known ones: vector τ can be time-, space- or light-like. In the Euclidean case there is only one κ -deformation⁵. In the complex (signature independent) case one distinguishes two subcases instead: $\tau^2 = 0$ and $\tau^2 \neq 0$.

In the Drinfel'd quantization scheme one requires the so-called h -adic topology: extension of $U(\text{iso}(g))$ by formal power series $U(\text{iso}(g))[[\frac{1}{\kappa}]]$ in order to arrange the deformation. It enables, e.g., existence of invertible twist, etc. (see, e.g., [29, 38, 39] for more details). Hereafter for shortening the notation one introduces the following objects

$$\Pi_\tau = \frac{1}{\kappa} P_\tau + \sqrt{1 + \frac{\tau^2}{\kappa^2}} C, \quad \Pi_\tau^{-1} = \frac{\sqrt{1 + \frac{\tau^2}{\kappa^2}} C - \frac{1}{\kappa} P_\tau}{1 + \frac{1}{\kappa^2} (\tau^2 C - P_\tau^2)}, \quad (2.7)$$

$$\tau^2 C_\tau = \kappa^2 \left(\Pi_\tau + \Pi_\tau^{-1} - 2 + \frac{1}{\kappa^2} (\tau^2 C - P_\tau^2) \Pi_\tau^{-1} \right) = 2\kappa^2 \left(\sqrt{1 + \frac{\tau^2}{\kappa^2}} C - 1 \right) \quad (2.8)$$

as formal power series in $\frac{1}{\kappa}$, where $P_\tau = \tau^\mu P_\mu$. Moreover $C \equiv P^\alpha P_\alpha = g^{\alpha\beta} P_\alpha P_\beta$ denotes the well-known quadratic Casimir element (a.k.a. Casimir of mass in $D = 4$ Lorentzian case). The element C_τ is also central and plays a role of deformed Casimir describing deformed dispersion relations (see, e.g., [17, 45] and references therein). For the case $\tau^2 = 0$ one should take $C_\tau = C$. With this notation $\kappa(\tau)$ -deformed (inhomogeneous) orthogonal Lie algebra, besides the standard

³If one wishes to have a real instead pure imaginary structure constants in (2.1), (2.2) then it is necessary to re-scale the generators $X \mapsto \tilde{X} = -iX$. In such a case $\tilde{X}^* = -\tilde{X}$ are real.

⁴In fact, Zakrzewski has provided a classification of the classical r -matrices in which the modified Yang–Baxter case is not completed. Therefore κ -deformation can be further quantized. We shall return to this point in the last two sections.

⁵Euclidean case has been also studied before in [37, 66].

orthogonal Lie algebra structure (2.1), (2.2), has deformed coalgebraic sector [26] (cf. realization dependent form in [37, 52, 66])

$$\Delta_\tau(P_\mu) = P_\mu \otimes \Pi_\tau + 1 \otimes P_\mu - \frac{\tau_\mu}{\kappa} P^\alpha \Pi_\tau^{-1} \otimes P_\alpha - \frac{\tau_\mu}{2\kappa^2} C_\tau \Pi_\tau^{-1} \otimes P_\tau, \quad (2.9)$$

$$\begin{aligned} \Delta_\tau(M_{\mu\nu}) &= M_{\mu\nu} \otimes 1 + 1 \otimes M_{\mu\nu} + \frac{1}{\kappa} P^\alpha \Pi_\tau^{-1} \otimes (\tau_\nu M_{\alpha\mu} - \tau_\mu M_{\alpha\nu}) \\ &\quad - \frac{1}{2\kappa^2} C_\tau \Pi_\tau^{-1} \otimes (\tau_\mu M_{\tau\nu} - \tau_\nu M_{\tau\mu}), \end{aligned} \quad (2.10)$$

where $M_{\tau\lambda} = \tau^\alpha M_{\alpha\lambda}$ and $\tau_\mu = g_{\alpha\mu} \tau^\alpha$ denote covariant components of τ^μ with respect to the metric $g_{\mu\nu}$. In order to complete the Hopf algebra structure one defines counits: $\epsilon(1) = 1$, $\epsilon(P_\mu) = -P_\mu$, $\epsilon(M_{\mu\nu}) = -M_{\mu\nu}$ and antipodes

$$S_\tau(P_\mu) = - \left(P_\mu + \frac{\tau_\mu}{\kappa} \left(C + \frac{1}{2\kappa} P_\tau C_\tau \right) \right) \Pi_\tau^{-1}, \quad S_\kappa(\Pi_\tau) = \Pi_\tau^{-1}, \quad (2.11)$$

$$S_\tau(M_{\mu\nu}) = -M_{\mu\nu} + \frac{1}{\kappa} P^\alpha (\tau_\nu M_{\alpha\mu} - \tau_\mu M_{\alpha\nu}) + \frac{1}{2\kappa^2} C_\tau (\tau_\nu M_{\tau\mu} - \tau_\mu M_{\tau\nu}). \quad (2.12)$$

So defined Hopf algebra structure will be denoted as $U_{\kappa,\tau}(\text{iso}(g))$, i.e., in particular, $U_{\kappa,\tau}(\text{iso}(g)) \cong U(\text{iso}(g))[[\frac{1}{\kappa}]]$ as an algebra. It preserves the reality condition (2.4) induced by the metric signature in the following well-known Hopf algebra reality condition form (see e.g. [63])

$$\Delta_\tau(X^*) = \Delta_\tau(X)^{* \otimes *} \quad \text{and} \quad S_\tau(S_\tau(X^*)^*) = X \quad (2.13)$$

for arbitrary $X \in U_{\kappa,\tau}(\text{iso}(g))$ provided that the vector τ^μ and the formal parameter $\frac{1}{\kappa}$ are real. Above conditions are enough to be checked on self-adjoint generators (2.1), (2.2). In particular, the identity: $S_\tau(S_\tau(X)) = \Pi_\tau^{D-1} X \Pi_\tau^{1-D}$ found in [52] can be very helpful.

It is important to notice that simultaneous re-scaling of τ and κ by the same factor does not change formulas (2.9)–(2.12) involving these symbols, so it can be treated as an isomorphism of the corresponding Hopf algebras, i.e. $U_{\kappa,\tau}(\text{iso}(g)) \cong U_{\lambda\kappa,\lambda\tau}(\text{iso}(g))$. As a practical application one finds that the vector τ can be normalized to the values $\tau^2 = \pm 1, 0$.

This unified description has the advantage of general covariance manifested via tensorial character of all defining formulas (2.1)–(2.12). Consider a change of basis in the space V : $e_\mu \mapsto \tilde{e}_\mu = A_\mu^\alpha e_\alpha$ by a non-degenerate matrix $A_\alpha^\beta \in \text{GL}(D, \mathbb{R})$. Thus one can introduce the new generators

$$\tilde{P}_\alpha = A_\alpha^\mu P_\mu, \quad \tilde{M}_{\alpha\beta} = A_\alpha^\mu A_\beta^\nu M_{\mu\nu} \quad (2.14)$$

together with $\tilde{g}_{\alpha\beta} = A_\alpha^\mu A_\beta^\nu g_{\mu\nu}$, $\tilde{\tau}_\alpha = A_\alpha^\mu \tau_\mu$ (but $\tilde{\tau}^\alpha = (A^{-1})^\alpha_\mu \tau^\mu$, $\tilde{C} = C$ and therefore $P_{\tilde{\tau}} = P_\tau$). Then all formulas of this section remain valid if we replace all objects without tilde sign by the corresponding ones with the tilde. Moreover the real structure (2.4) is preserved. It means that $U_{\kappa,\tau}(\text{iso}(g)) \cong U_{\kappa,\tilde{\tau}}(\text{iso}(\tilde{g}))$ as real Hopf algebras. In particular, if $A_\alpha^\beta \in O(g)$ then $g_{\alpha\beta} = \tilde{g}_{\alpha\beta}$ (internal automorphism). This fact is important for possible physical applications and interpretations (see last section in [26]). It is to be observed that the transformation (2.14) does not change the metric signature.

3 Specialization of the $\kappa(\tau)$ -inhomogeneous orthogonal Hopf algebras

It is known that quantized enveloping Lie algebras have many (non-isomorphic) incarnations, with the deformation parameter being both a formal variable (algebraic generator) or a numerical

factor. The passage from the topological h -adic (Drinfel'd) version, we have used till now, to the q -analog (Drinfel'd–Jimbo) form and final specialization of the formal deformation parameter to some numerical value is well understood and described for standard deformations of semi-simple Lie algebras (see, e.g., [29, Chapter 9] and [50, Chapters 3, 7]). More deeper mathematical study of this problem can be found in [15, 16]. The specialization problem for time-like κ -Poincaré case has been also treated in a bicrossproduct basis in the context of possible C^* -algebra reformulation [30, 47, 48, 82].

In the present section we recall our earlier result concerning specialization problem for a time-like version of κ -type deformation [25]. Then we extend the analysis to the non-standard (light-cone) case as well as to twisted κ -deformations. Surprisingly, to our best knowledge, the specialization problem for non-standard (i.e. invoked by a two-cocycle twist) deformation has not been studied in the literature yet. Our results show that (extended) Jordanian twist, in contrast to the Abelian one, enables (after suitable change of variables) to solve specialization problem.

3.1 The $D = 1 + (D - 1)$ orthogonal decomposition: $\tau^2 \neq 0$

In order to introduce the q -analog version of $\kappa(\tau)$ -quantized inhomogeneous orthogonal Hopf algebra from the previous section we start with reminding the orthogonal $D = 1 + (D - 1)$ decomposition which relays on suitable change⁶ of generators in $U(\text{iso}(g))$, provided that $\tau^2 \neq 0$.

In the corresponding Lie algebra basis $\{P_\tau, P_i, M_{\tau i}, M_{ij}\}$ the algebraic relations read as

$$[M_{ij}, M_{kl}] = i(g_{il}M_{jk} - g_{jl}M_{ik} + g_{jk}M_{il} - g_{ik}M_{jl}), \quad (3.1)$$

$$[M_{\tau j}, M_{kl}] = i(g_{jk}M_{\tau l} - g_{jl}M_{\tau k}), \quad [M_{\tau j}, M_{\tau l}] = 0, \quad (3.2)$$

$$[P_\tau, P_k] = [P_i, P_j] = [P_\tau, P_\tau] = 0, \quad (3.3)$$

$$[M_{ij}, P_k] = i(g_{jk}P_i - g_{ik}P_j), \quad [M_{ij}, P_\tau] = 0, \quad (3.4)$$

$$[M_{\tau j}, P_k] = ig_{jk}P_\tau, \quad [M_{\tau j}, P_\tau] = -i\tau^2 P_j, \quad (3.5)$$

while the coproducts take the form (notice that now $\tau^\mu = (1, 0, \dots, 0)$)

$$\begin{aligned} \Delta_\tau(P_\tau) &= P_\tau \otimes \left(\frac{1}{\kappa} P_\tau + \sqrt{1 + \frac{\tau^2}{\kappa^2} C} \right) + \left(\frac{\sqrt{1 + \frac{\tau^2}{\kappa^2} C} - \frac{1}{\kappa} P_\tau}{1 + \frac{\tau^2}{\kappa^2} P^m P_m} \right) \otimes P_\tau \\ &\quad - \frac{\tau^2}{\kappa} \left(\frac{\sqrt{1 + \frac{\tau^2}{\kappa^2} C} - \frac{1}{\kappa} P_\tau}{1 + \frac{\tau^2}{\kappa^2} P^m P_m} \right) P^j \otimes P_j, \end{aligned} \quad (3.6)$$

$$\Delta_\tau(P_i) = P_i \otimes \left(\frac{1}{\kappa} P_\tau + \sqrt{1 + \frac{\tau^2}{\kappa^2} C} \right) + 1 \otimes P_i, \quad (3.7)$$

$$\Delta_\tau(M_{ij}) = M_{ij} \otimes 1 + 1 \otimes M_{ij}, \quad i, j = 1, \dots, D - 1, \quad (3.8)$$

$$\begin{aligned} \Delta_\tau(M_{\tau i}) &= M_{\tau i} \otimes 1 + \left(\frac{\sqrt{1 + \frac{\tau^2}{\kappa^2} C} - \frac{1}{\kappa} P_\tau}{1 + \frac{\tau^2}{\kappa^2} P^m P_m} \right) \otimes M_{\tau i} \\ &\quad + \frac{\tau^2}{\kappa} \left(\frac{\sqrt{1 + \frac{\tau^2}{\kappa^2} C} - \frac{1}{\kappa} P_\tau}{1 + \frac{\tau^2}{\kappa^2} P^m P_m} \right) P^j \otimes M_{ij}, \end{aligned} \quad (3.9)$$

⁶It can be done by certain choice of the basis $\{e_\mu\}_{\mu=0}^{D-1}$ in V , where $e_0 = \tau$ and $\{e_i\}_{i=1}^{D-1}$ are orthogonal to τ : $g_{00} = \tau^2$, $g_{0i} = g(e_0, e_i) = 0$. This can be reached by an analog of the so-called Gram–Schmidt orthogonalization procedure which provides the orthogonal decomposition $(V, g_{\mu\nu}) \cong (\mathbb{R}, g_{00}) \times (V^{D-1}, g_{ij})$. One can note that the $(D - 1)$ -dimensional metric g_{ij} does not need to be in the diagonal form.

where $\tau^2 = g_{00}$ and after normalization it can be reduced to ± 1 and $C = P^\mu P_\mu = (\tau^2)^{-1} P_\tau^2 + g^{ij} P_i P_j$, $\mu, \nu = \tau, i$. For this system of generators one has

$$\Pi_\tau = \frac{1}{\kappa} P_\tau + \sqrt{1 + \frac{\tau^2}{\kappa^2} C}, \quad \Pi_\tau^{-1} = \frac{\sqrt{1 + \frac{\tau^2}{\kappa^2} C} - \frac{1}{\kappa} P_\tau}{1 + \frac{\tau^2}{\kappa^2} P^m P_m}, \quad (3.10)$$

$$C_\tau = \frac{\kappa^2}{\tau^2} \left(\Pi_\tau + \Pi_\tau^{-1} - 2 + \frac{\tau^2}{\kappa^2} P^m P_m \Pi_\tau^{-1} \right) = \frac{2\kappa^2}{\tau^2} \left(\sqrt{1 + \frac{\tau^2}{\kappa^2} C} - 1 \right), \quad (3.11)$$

as well as the following antipodes

$$S_\tau(P_\tau) = - \left(P_\tau + \frac{\tau^2}{\kappa} \left(C + \frac{1}{2\kappa} P_\tau C_\tau \right) \right) \Pi_\tau^{-1}, \quad (3.12)$$

$$S_\tau(P_i) = -P_i \Pi_\tau^{-1}, \quad S_\tau(\Pi_\tau) = \Pi_\tau^{-1}, \quad (3.13)$$

$$S_\tau(M_{ij}) = -M_{ij}, \quad S_\tau(M_{\tau i}) = -M_{\tau i} - \frac{\tau^2}{\kappa} P^\alpha M_{\alpha i} - \frac{\tau^2}{2\kappa^2} C_\tau M_{\tau i}. \quad (3.14)$$

The relations (3.1)–(3.14) constitute the same Hopf algebra although written in another presentation (system of generators). The importance of such presentation has been shown in [26] by the relation to Majid–Ruegg formulation [64]. Again, above coproducts and antipodes are formal power series in $\frac{1}{\kappa}$ as well. It is to be observed that the elements $(P_\tau, \Pi_\tau, \Pi_\tau^{-1})$ are not algebraically independent, since

$$P_\tau = \frac{\kappa}{2} \left(\Pi_\tau - \Pi_\tau^{-1} \left(1 + \frac{\tau^2}{\kappa^2} P^m P_m \right) \right). \quad (3.15)$$

In the next section we show how to use this fact and by taking advantage of two (mutually inverse) group-like elements $(\Pi_\tau, \Pi_\tau^{-1})$ one can eliminate infinite power series from the formulas (3.6)–(3.14).

q -analog version of $U_{\kappa, \tau}(\text{iso}(g))$: $\tau^2 \neq 0$. As a first step, inside the Hopf algebra from the previous section⁷, one can consider sub-Hopf algebra generated by elements $(M_{ij}, P_i, M_{\tau i}, \Pi_\tau, \Pi_\tau^{-1})$ and call it $U_{q, \tau}(\text{iso}(g))$. Its generators satisfy the following relations⁸

$$\Pi_\tau \Pi_\tau^{-1} = 1 = \Pi_\tau \Pi_\tau^{-1}, \quad (3.16)$$

$$[P_i, \Pi_\tau] = [M_{ij}, \Pi_\tau] = 0, \quad [M_{\tau i}, \Pi_\tau] = -\frac{i}{\kappa} P_i, \quad (3.17)$$

$$[M_{\tau i}, P_j] = i g_{ij} \frac{\kappa}{2} \left(\Pi_\tau - \Pi_\tau^{-1} \left(1 + \frac{\tau^2}{\kappa^2} P^m P_m \right) \right). \quad (3.18)$$

Commutators with Π_τ^{-1} can be easily calculated from the above (e.g. $[M_{\tau i}, \Pi_\tau^{-1}] = \frac{i}{\kappa} P_i \Pi_\tau^{-2}$).

Alternatively, one can abstractly define the algebraic structure of $U_{q, \tau}(\text{iso}(g))$, in a way similar to the universal enveloping algebra, i.e. as a universal associative algebra generated by elements $(M_{ij}, P_i, M_{\tau i}, \Pi_\tau, \Pi_\tau^{-1})$ factorized by a suitable (two-sided) ideal of relations (3.16)–(3.18). Coalgebraic structure

$$\Delta_\tau(\Pi_\tau) = \Pi_\tau \otimes \Pi_\tau, \quad \Delta_\tau(\Pi_\tau^{-1}) = \Pi_\tau^{-1} \otimes \Pi_\tau^{-1}, \quad (3.19)$$

$$\Delta_\tau(P_i) = P_i \otimes \Pi_\tau + 1 \otimes P_i, \quad i, j = 1, \dots, D-1, \quad (3.20)$$

$$\Delta_\tau(M_{ij}) = M_{ij} \otimes 1 + 1 \otimes M_{ij}, \quad (3.21)$$

⁷More generally, one can take, in fact, any basis with $e_0 = \tau$. In such cases one has $\tau^2 = g_{00}$ and $\tau_\mu = g_{0\mu}$.

⁸The sector (M_{ij}, P_i) remains standard, cf. formulas (2.1), (2.2).

$$\Delta_\tau(M_{\tau i}) = M_{\tau i} \otimes 1 + \Pi_\tau^{-1} \otimes M_{\tau i} + \frac{\tau^2}{\kappa} P^j \Pi_\tau^{-1} \otimes M_{ij}, \quad (3.22)$$

as well as antipodes

$$S_\tau(P_i) = -P_i \Pi_\tau^{-1}, \quad S_\tau(\Pi_\tau^{\pm 1}) = \Pi_\tau^{\mp 1}, \quad S_\tau(M_{ij}) = -M_{ij}, \quad (3.23)$$

$$S_\tau(M_{\tau i}) = -M_{\tau i} - \frac{\tau^2}{\kappa} P^k M_{ki} - \frac{\tau^2}{2} \left(\Pi_\tau - \Pi_\tau^{-1} \left(1 + \frac{1}{\kappa^2} P^m P_m \right) \right) M_{\tau i} - \frac{\tau^2}{2\kappa^2} C_\tau M_{\tau i} \quad (3.24)$$

can be calculated from (3.6)–(3.14).

In order to complete the definition one leaves counit undeformed, i.e., $\epsilon(X) = 0$ for $X = (M_{ij}, M_{\tau i}, P_i)$ and $\epsilon(\Pi_\tau) = 1 = \epsilon(\Pi_\tau^{-1})$. Deformed and undeformed central elements can now be expressed as

$$C_\tau = \frac{\kappa^2}{\tau^2} \left(\Pi_\tau + \Pi_\tau^{-1} - 2 + \frac{\tau^2}{\kappa^2} P^m P_m \Pi_\tau^{-1} \right), \quad C = C_\tau \left(1 + \frac{\tau^2}{4\kappa^2} C_\tau \right). \quad (3.25)$$

It is important to note that the Hopf algebra $U_{q,\tau}(\text{iso}(g))$ can be considered as an algebra over polynomial ring $\mathbb{C}[\frac{1}{\kappa}]$ (instead of h -adic ring $\mathbb{C}[[\frac{1}{\kappa}]]$), since it contains only polynomial expressions in the formal variable $\frac{1}{\kappa}$. Because of this we are entitled to introduce a new (non-isomorphic) Hopf algebra over \mathbb{C} by assigning some numerical (complex in general) value to the parameter κ in the formulas (3.16)–(3.25). A real value of κ is necessary if one wants to preserve the real form (2.4) of the Hopf algebra. This solves the so-called specialization problem for $U_{q,\tau}(\text{iso}(g))$ in the case $\tau^2 \neq 0$. First of all one can prove that different values of κ give rise to the same (isomorphic) Hopf algebras. It can be seen if one changes the generators by the re-scaling $P_i \mapsto \frac{1}{\kappa} P_i$ which is equivalent to setting $\kappa = 1$ ⁹.

One can argue that this new Hopf algebra has some advantages with respect to the previous ones. For example, in the (semi-)simple case there is a duality between Drinfel'd–Jimbo quantized enveloping algebras and some matrix (or coordinate) Hopf algebras. The same is expected for the case above [77, 78].

Moreover, one can also introduce an element P_τ expressed in terms of q -analog algebra generators by the formula (3.15). This means that $U_{q,\tau}(\text{iso}(g))$ contains as a subalgebra the universal enveloping algebra $U(\text{iso}(g))$. However it is not a sub-Hopf algebra. This fact is meaningful for the representation theory of $U_{q,\tau}(\text{iso}(g))$: any representation of $U_{q,\tau}(\text{iso}(g))$ becomes automatically a representation of the corresponding Lie algebra $\text{iso}(g)$. The inverse statement is in general not true. Instead one gets the following selection rule: a representation of an orthogonal Lie algebra $\text{iso}(g)$ becomes at the same time a representation of its quantum version provided the elements Π_τ, Π_τ^{-1} as given by the formula (3.10) are well defined (self-adjoint) operators in the representation space and are mutually inverse of each other. From one hand, these might be complicated issues involving numerical value of the parameter κ , domain of P_τ , etc. From the other hand representations with a constant value for the mass Casimir operator C , e.g. irreducible ones, are very welcome.

From the point of view of applications in physical theories, specialization of the deformation parameter allows to interpret it as some physical constant of Nature, e.g. quantum gravity scale M_{QG} . However the value of it depends on a system of units one is using. For example, one should be able to use natural (Planck) system of units, $\hbar = c = 1$. This fits very well with the re-scaling property mentioned above.

3.2 The $D = 2 + (D - 2)$ orthogonal decomposition: $\tau^2 = 0$

In the previous subsection we were dealing with the q -analog version of the standard κ -deformation (i.e. time-like case which includes the κ -Poincaré algebra). For $\tau^2 \neq 0$ the corresponding

⁹Some authors are used to use similar formulation in the bicrossproduct basis, see e.g. [40].

r -matrix satisfies MYBE. It should be stressed that such q -analog version has not been considered for non-standard deformations (i.e. for which r -matrix satisfies CYBE and the cocycle twist exists¹⁰). In this section we will show that, in fact, it is possible to construct the q -analog for the case of $\tau^2 = 0$, which includes the null-plane quantum Poincaré Hopf algebra [9, 13, 14] (also known as the light-like deformation). Throughout this section we assume non-Euclidean signature.

We remind the $D = 2 + (D - 2)$ orthogonal decomposition for inhomogeneous orthogonal Hopf algebra of non-Euclidean signature which relies on a suitable choice of basis in the vector space V . This in turn invokes change of the generators of $U(\text{iso}(g))$ which are now related with the so-called “null-plane” basis in $\text{iso}(g)$

$$P_\mu = (P_+, P_-, P_a), \quad M_{\mu\nu} = (M_{+-}, M_{+a}, M_{-a}, M_{ab}), \quad a, b = 1, 2, \dots, D - 2. \quad (3.26)$$

Here we took two (non-orthogonal) null vectors $\tau^\mu \equiv \tau_+^\mu = (1, 0, \dots, 0)$, $\tilde{\tau}^\mu \equiv \tau_-^\mu = (0, 1, 0, \dots, 0)$: $\tau_+ \tau_- = 1$ (as spanning of 2-dimensional Lorentzian subspace)¹¹ in order to obtain the convenient null-plane (a.k.a. light-cone) basis in the space of the Lie algebra generators (3.26). This algebra consists of the following (non-vanishing) commutators

$$[M_{+a}, M_{-b}] = -i(M_{ab} + g_{ab}M_{+-}), \quad [M_{\pm a}, M_{\pm b}] = 0, \quad (3.27)$$

$$[M_{\pm a}, M_{bc}] = i(g_{ab}M_{\pm c} - g_{ac}M_{\pm b}), \quad [M_{+-}, M_{\pm a}] = \pm iM_{\pm a}, \quad (3.28)$$

$$[M_{+-}, P_\pm] = \pm iP_\pm, \quad [M_{\pm a}, P_b] = ig_{ab}P_\pm, \quad (3.29)$$

$$[M_{\pm a}, P_\pm] = [M_{+-}, P_a] = 0, \quad [M_{\pm a}, P_\mp] = -iP_a \quad (3.30)$$

together with the standard commutation relations within the $(D - 2)$ -dimensional sector (M_{ab}, P_a, g_{ab}) , cf. (2.1), (2.2).

The universal formula for the coalgebra structure, in this case reduces to

$$\Delta_\tau(P) = P \otimes \left(1 + \frac{1}{\kappa}P_+\right) + 1 \otimes P \quad \text{for } P \in \{P_+, P_a\}, \quad (3.31)$$

$$\begin{aligned} \Delta_\tau(P_-) &= P_- \otimes \left(1 + \frac{1}{\kappa}P_+\right) + \left(1 + \frac{1}{\kappa}P_+\right)^{-1} \otimes P_- \\ &\quad - \frac{1}{\kappa} \left(P_- + \frac{1}{2\kappa}C_+\right) \left(1 + \frac{1}{\kappa}P_+\right)^{-1} \otimes P_+ - \frac{1}{\kappa}P^a \left(1 + \frac{1}{\kappa}P_+\right)^{-1} \otimes P_a, \end{aligned} \quad (3.32)$$

$$\Delta_\tau(M_{+-}) = M_{+-} \otimes 1 + \left(1 + \frac{1}{\kappa}P_+\right)^{-1} \otimes M_{+-} - \frac{1}{\kappa}P^a \left(1 + \frac{1}{\kappa}P_+\right)^{-1} \otimes M_{+a}, \quad (3.33)$$

$$\begin{aligned} \Delta_\tau(M_{-a}) &= M_{-a} \otimes 1 + \left(1 + \frac{1}{\kappa}P_+\right)^{-1} \otimes M_{-a} \\ &\quad - \frac{1}{\kappa} \left(P_- + \frac{1}{2\kappa}C_+\right) \left(1 + \frac{1}{\kappa}P_+\right)^{-1} \otimes M_{+a} - \frac{1}{\kappa}P^b \left(1 + \frac{1}{\kappa}P_+\right)^{-1} \otimes M_{ba}, \end{aligned} \quad (3.34)$$

$$\Delta_\tau(M) = M \otimes 1 + 1 \otimes M \quad \text{for } M \in \{M_{+a}, M_{ab}\} \quad (3.35)$$

¹⁰It is known that for standard deformations of semi-simple Lie algebra there exist a cochain twist which determines a weaker quasi-Hopf algebra structure on the corresponding enveloping algebra instead. In the case of non-semi-simple Poincaré Lie algebra the existence of such cochain twist has been proved in [86]. However our formulas for the coproduct (3.6)–(3.9) do not admit a cochain twist for $\tau^2 \neq 0$ as noticed in [18].

¹¹Starting from non-zero vector $\tau : \tau^2 = 0$, one can decompose the space $V^D = V^2 \times V^{D-2}$, by an appropriate choice of basis vectors, into the orthogonal product of 2-dimensional Lorentzian space $\{V^2, g_{AB}\}$ with a $(D - 2)$ -dimensional one $\{V^{D-2}, g_{ab}\}$: $(A, B = +, -)$, $(a, b = 1, 2, \dots, D - 2)$. Moreover, the total metric $g_{\mu\nu} = g_{AB} \times g_{ab}$ becomes a product metric. We choose $g_{AB} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ in its anti-diagonal (null-plane) form.

and can be obtained by twisting of undeformed (primitive) coproducts by the extended Jordanian twist [26]

$$\begin{aligned}\mathcal{F} &= \exp(-iM_{+-} \otimes \ln \Pi_+) \exp\left(-\frac{i}{\kappa}M_{+a} \otimes P^a \Pi_+^{-1}\right) \\ &= \exp\left(-\frac{i}{\kappa}M_{+a} \otimes P^a\right) \exp(-iM_{+-} \otimes \ln \Pi_+),\end{aligned}\quad (3.36)$$

which satisfies the two-cocycle condition, see also [54, 73]. Moreover, the twist is unitary, i.e. the resulting deformation preserves the real form (cf. (2.13)). For this system of generators we have $\Pi_+ \doteq 1 + \frac{1}{\kappa}P_+$ and $C = 2P_+P_- + P^aP_a$. The antipodes are as follows

$$S_\tau(P) = -P\Pi_+^{-1} \quad \text{for } P \in \{P_+, P_a\}, \quad (3.37)$$

$$S_\tau(P_-) = -P_- \Pi_+ - \frac{1}{\kappa} \left(1 + \frac{1}{2\kappa}P_+\right) P_a P^a \Pi_+^{-1}, \quad (3.38)$$

$$S_\tau(M_{+-}) = -\Pi_+ M_{+-} - \frac{1}{\kappa} P^a M_{+a}, \quad (3.39)$$

$$S_\tau(M_{-a}) = -\Pi_+ M_{-a} - \frac{1}{\kappa} \left(P_- + \frac{1}{2\kappa}C\right) M_{+a} - \frac{1}{\kappa} P^b M_{ba}, \quad (3.40)$$

$$S_\tau(M) = -M \quad \text{for } M \in \{M_{+a}, M_{ab}\}. \quad (3.41)$$

Due to the presence of Π_+^{-1} some of the above expressions are infinite (formal) power series in $\frac{1}{\kappa}$. The Lie sub-algebra corresponding to the stability group of τ_+ consists of $\text{iso}(p-1, q-1) = \text{gen}\{M_{ab}, M_{+b}\}$, i.e. the generators with the primitive coproducts. One can notice that P_+ and Π_+ are not algebraically independent and one can express one through another: $P_+ = \kappa(\Pi_+ - 1)$ which will be helpful in introducing the q -analog version of the above Hopf algebra.

q -analog version of $U_{\kappa, \tau}(\text{iso}(\mathfrak{g}))$: $\tau^2 = 0$. Similarly to the previous section we start from considering the Hopf sub-algebra generated by the following elements ($M_{+-}, M_{+a}, M_{-a}, M_{ab}, P_a, P_-, \Pi_+, \Pi_+^{-1}$) and we denote it as before as $U_{q, \tau}(\text{iso}(\mathfrak{g}))$. The only difference is that now $\tau^2 = 0$ and one deals with non-standard (triangular) deformation. It is generated by the following relations

$$[M_{+a}, M_{-b}] = -i(M_{ab} + g_{ab}M_{+-}), \quad [M_{\pm a}, M_{\pm b}] = 0, \quad (3.42)$$

$$[M_{\pm a}, M_{bc}] = i(g_{ab}M_{\pm c} - g_{ac}M_{\pm b}), \quad [M_{+-}, M_{\pm a}] = \pm iM_{\pm a}, \quad (3.43)$$

$$[M_{+-}, \Pi_+] = i(\Pi_+ - 1), \quad [M_{+-}, P_-] = -iP_-, \quad [M_{+a}, P_b] = i\kappa g_{ab}(\Pi_+ - 1), \quad (3.44)$$

$$[M_{-a}, P_-] = 0, \quad [M_{-a}, P_+] = -iP_a, \quad [M_{-a}, \Pi_+] = -\frac{i}{\kappa}P_a, \quad (3.45)$$

$$[M_{-a}, P_b] = ig_{ab}P_-, \quad [M_{+a}, \Pi_+] = [M_{+a}, P_+] = [M_{+-}, P_a] = 0. \quad (3.46)$$

The commutation relations within the $(D-2)$ -dimensional sector (M_{ab}, P_a, g_{ab}) stay standard, cf. (2.1), (2.2). Another way would be, to abstractly define the algebraic structure as universal unital and associative algebra over the complex numbers generated by the elements $(M_{+-}, M_{+a}, M_{-a}, M_{ab}, P_a, P_-, \Pi_+, \Pi_+^{-1})$ and factorized by the corresponding (two-sided) ideal of above relations.

Then a coalgebra for the q -analog version in this case takes the form

$$\Delta_\tau(P_a) = P_a \otimes \Pi_+ + 1 \otimes P_a, \quad (3.47)$$

$$\Delta_\tau(\Pi_+) = \Pi_+ \otimes \Pi_+, \quad \Delta_\tau(\Pi_+^{-1}) = \Pi_+^{-1} \otimes \Pi_+^{-1}, \quad (3.48)$$

$$\Delta_\tau(P_-) = P_- \otimes \Pi_+ + \Pi_+^{-1} \otimes P_- - \left(P_- + \frac{1}{2\kappa}C\right) \Pi_+^{-1} \otimes (\Pi_+ - 1) - \frac{1}{\kappa}P^a \Pi_+^{-1} \otimes P_a, \quad (3.49)$$

$$\Delta_\tau(M_{+-}) = M_{+-} \otimes 1 + \Pi_+^{-1} \otimes M_{+-} - \frac{1}{\kappa} P^a \Pi_+^{-1} \otimes M_{+a}, \quad (3.50)$$

$$\Delta_\tau(M_{-a}) = M_{-a} \otimes 1 + \Pi_+^{-1} \otimes M_{-a} - \frac{1}{\kappa} \left(P_- + \frac{1}{2\kappa} C \right) \Pi_+^{-1} \otimes M_{+a} - \frac{1}{\kappa} P^b \Pi_+^{-1} \otimes M_{ba}, \quad (3.51)$$

$$\Delta_\tau(M) = M \otimes 1 + 1 \otimes M \quad \text{for } M \in \{M_{+a}, M_{ab}\}, \quad (3.52)$$

where now $C = 2\kappa(\Pi_+ - 1)P_- + P^a P_a$. Including the following antipodes

$$S_\tau(P_a) = -P_a \Pi_+^{-1}, \quad S_\tau(\Pi_+) = \Pi_+^{-1}, \quad (3.53)$$

$$S_\tau(P_-) = -P_- \Pi_+ - \frac{1}{2\kappa} (1 + \Pi_+) P_a P^a \Pi_+^{-1}, \quad (3.54)$$

$$S_\tau(M_{+-}) = -\Pi_+ M_{+-} - \frac{1}{\kappa} P^a M_{+a}, \quad (3.55)$$

$$S_\tau(M_{-a}) = -\Pi_+ M_{-a} - \frac{1}{\kappa} \left(P_- + \frac{1}{2\kappa} C \right) M_{+a} - \frac{1}{\kappa} P^b M_{ba}, \quad (3.56)$$

$$S_\tau(M) = -M \quad \text{for } M \in \{M_{+a}, M_{ab}\} \quad (3.57)$$

one completes the Hopf algebra structure provided the counits remain undeformed, i.e. $\epsilon(X) = 0$ for $X = (M_{+-}, M_{+a}, M_{-a}, M_{ab}, P_a, P_-, \Pi_+, \Pi_+^{-1})$ and $\epsilon(\Pi_+) = 1 = \epsilon(\Pi_+^{-1})$.

One can notice that analogously to the previous case the algebra $U_{q,\tau}(\text{iso}(g))$ can be seen as an algebra over polynomial ring $\mathbb{C}[\frac{1}{\kappa}]$. By assigning the numerical value to κ in formulas (3.42)–(3.57) we are introducing new (non-isomorphic) Hopf algebra over \mathbb{C} , which constitutes the so-called specialized (q -analog) version $U_{q,\tau}(\text{iso}(g))$ for the case of $\tau^2 = 0$. Again, one can easily rescale the momenta P^a, P_- by $\frac{1}{\kappa}$, so in fact, one can prove that different values of the parameter κ give rise to isomorphic Hopf-algebras. Additionally, more general version of this construction is possible provided that one starts up from any basis in the associate vector space with $e_0 = \tau$.

From the considerations presented in this section one can deduce that any universal enveloping algebra twisted by an (extended) Jordanian twist admits specialization of the deformation parameter to a numerical value.

3.3 $\kappa(\tau)$ -Minkowski spacetime

Quantum κ -Minkowski spacetime $\mathcal{M}_{\kappa,\tau}^D$ is usually defined as an algebra (complex, universal, unital and associative) generated by the following relations [51, 56]

$$[x^\mu, x^\nu] = \frac{i}{\kappa} (\tau^\mu x^\nu - \tau^\nu x^\mu) \quad (3.58)$$

of Lie algebra type¹², where τ^μ are (real numerical) contravariant components of the vector $\tau \in V$ with respect to some basis $\{e_\mu\}_{\mu=0}^{D-1}$.

On one hand the algebra (3.58) is well adopted to the following action of the quantum $U_{\kappa,\tau}(\text{iso}(g))$

$$P_\mu \triangleright x^\nu = -i\delta_\mu^\nu, \quad M_{\mu\nu} \triangleright x^\rho = i (g_{\mu\alpha} \delta_\nu^\rho - g_{\nu\alpha} \delta_\mu^\rho) x^\alpha. \quad (3.59)$$

This implies $\Pi_\tau^{\pm 1} \triangleright x^\mu = x^\mu \mp \frac{i}{\kappa} \tau^\mu$. On the linear subspace spanned by the generators $\text{lin}_{\mathbb{C}}\{x^1, \dots, x^D\}$ this action is equivalent to the (complexified) vector representation (2.3). The way it extends to the polynomial expressions $x^{\mu_1} \dots x^{\mu_k}$ is controlled by the coproduct. Under the action the algebra (3.58) becomes a covariant quantum space (\equiv Hopf module algebra) in a sense of the compatibility condition (a.k.a. generalized Leibniz rule)

$$L \triangleright (x \cdot y) = (L_{(1)} \triangleright x) \cdot (L_{(2)} \triangleright y) \quad (3.60)$$

¹²At the moment we consider $\frac{1}{\kappa}$ as a formal variable.

as well as

$$(L \cdot M) \triangleright x = L \triangleright (M \triangleright x) \quad (3.61)$$

for any $x, y \in \mathcal{M}_{\kappa, \tau}^D$, $L, M \in U_{\kappa, \tau}(\text{iso}(g))$, where, for simplicity, we have used Sweedler type notation for the coproduct: $\Delta_{\tau}(L) = L_{(1)} \otimes L_{(2)}$. On the other hand, the presentation of the algebra (3.58) provides its natural real form by the requirement that the generators $(x^{\mu})^{\dagger} = x^{\mu}$ are self-adjoint in analogy to (2.4). The compatibility condition between two real structures can be expressed (see e.g. [81]) as a reality condition

$$L^* \triangleright x^{\dagger} = (S_{\tau}(L^*)^* \triangleright x)^{\dagger} \quad (3.62)$$

for the corresponding representation (module structure). This property is enough to be checked on Hermitean generators: $L \in (M_{\mu\nu}, P_{\rho})$, $x \in (x^{\mu})$ since formula (3.62) is consistent with both multiplications, i.e. (3.60) and (3.61).

It should be observed that the metric components are not involved in the definition of (3.58), so the algebra is independent of the metric itself and the metric signature in particular. One can see it also by making use of a general covariance in order to change the system of generators in (3.58) (cf. (2.14)). Indeed, introducing new generators $\tilde{x}^{\alpha} = (A^{-1})_{\mu}^{\alpha} x^{\mu}$ and new components $\tilde{\tau}^{\alpha} = (A^{-1})_{\mu}^{\alpha} \tau^{\mu}$ ($\tilde{e}_{\alpha} = A_{\alpha}^{\mu} e_{\mu}$, $A_{\alpha}^{\mu} \in \text{GL}(D, \mathbb{R})$) one preserves the form of (3.58) as well as the reality condition. It shows that the real algebra (3.58) is, in fact, independent of the components of the vector $\tau \neq 0$ (for $\tau = 0$ one obtains undeformed Abelian algebra). In particular, one can always reach the well-known standard form of the κ -Minkowski spacetime algebra¹³

$$[x^0, x^i] = \frac{i}{\kappa} x^i, \quad [x^i, x^j] = 0, \quad i, j = 1, \dots, D-1. \quad (3.63)$$

One can conclude that up to the isomorphism mentioned above, for any dimension there is only one real κ -Minkowski spacetime algebra $\mathcal{M}_{\kappa, \tau}^D$, which is covariant as a Hopf module algebra with respect to the action (3.59) of different, in general, Hopf algebras equipped with different reality structures. In fact, to be more precise, we have to distinguish three non-isomorphic options (incarnations): each one is adopted to the corresponding form of quantum $U(\text{iso}(g))$:

- i) $\mathcal{M}_{\kappa, \tau}^D$ is closed in h -adic topology (see [24]);
- ii) $\mathcal{M}_{q, \tau}^D$ is considered as an algebra over polynomial ring $\mathbb{C}[\frac{1}{\kappa}]$ admitting only polynomial expressions in the formal variable $\frac{1}{\kappa}$ (q -analog version);
- iii) we assign to κ numerical value. In this case a value of κ becomes irrelevant since it can be removed by re-scaling: $\tau^{\mu} \mapsto \frac{1}{\kappa} \tau^{\mu}$ in (3.58) (or alternatively $x^0 \mapsto \kappa x^0$ in (3.63)). Such algebra \mathcal{M}_{τ}^D is isomorphic to the enveloping algebra of the solvable Lie algebra denoted usually¹⁴ as \mathfrak{an}^D . This version has found numerous applications, e.g. from the point of view of the spectral triples [30, 47, 48, 70] or in the group field theories [75] which are connected with loop quantum gravity and spin foams approach.

3.4 Crossed product – unified description for DSR algebras

The property (3.60) allows us to introduce a larger algebra which unifies $\text{iso}(g)$ generators with that of $\mathcal{M}_{\kappa, \tau}^D$ by making use of a crossed product construction (see e.g. [24]). This is the so-called DSR (deformed special relativity) algebra and it is based on the multiplication formula

$$(f \otimes L) \rtimes (g \otimes M) = f(L_{(1)} \triangleright g) \otimes L_{(2)} M$$

¹³To this aim we take any basis with $e_0 = \tau$.

¹⁴According to a classification scheme [36] for all 4-dimensional solvable Lie algebras (see Appendix), we shall be using later, it is denoted as M^2 .

providing the following crossed commutations

$$[1 \otimes L, f \otimes 1]_{\times} = (L_{(1)} \triangleright f) \otimes L_{(2)} - f \otimes L$$

between elements of two ingredient algebras: $\mathcal{M}_{\kappa, \tau}^D$ and $\mathcal{U}_{\kappa, \tau}(\text{iso}(g))$ with the action induced by (3.59).

Therefore the covariant form of DSR algebra, generalized now to any metric g , any vector τ and living in arbitrary dimensions, obeys the algebraic relations (2.1), (2.2), (3.58) supplemented by the following cross-commutation relations

$$\begin{aligned} [P_{\mu}, x^{\rho}]_{\times} &= -i\delta_{\mu}^{\rho}\Pi_{\tau} + i\frac{\tau_{\mu}}{\kappa}P^{\rho}, \\ [M_{\mu\nu}, x^{\rho}]_{\times} &= i(g_{\mu\alpha}\delta_{\nu}^{\rho} - g_{\nu\alpha}\delta_{\mu}^{\rho})x^{\alpha} + \frac{i}{\kappa}g^{\rho\alpha}(\tau_{\mu}M_{\alpha\nu} - \tau_{\nu}M_{\alpha\mu}). \end{aligned}$$

The obvious real form of this algebra (with Hermitean generators in the formulas above) is induced from (2.4), (2.13) and (3.62). It has been shown in [24] that deformed and undeformed (with commuting spacetime variables and primitive coproducts, i.e. for $\kappa \mapsto \infty$) DSR algebras are isomorphic each other (in general, such statement holds true provided that one deals with twisted deformation [24]).

4 Twist deformations of κ -Minkowski spacetime

As it is known, one can distinguish two types of quantum deformations of the corresponding universal enveloping algebras: non-standard (triangular) provided by two-cocycle twist and standard, quasi-triangular one. In the first case the corresponding classical r -matrix satisfies Yang–Baxter equation with vanishing Schouten brackets. In the latter one deals with modified Yang–Baxter equation with invariant (non-trivial) Schouten brackets. One of the advantages of the twist deformation is that it provides straightforwardly the universal R -matrix and the explicit formula for star-product, which is consistent with Hopf-algebraic actions. Twisted deformations are especially useful, e.g. in gravity [4, 5, 7, 8, 74], field [32, 34, 35, 41, 43, 67, 69, 80] and gauge [6, 49, 62] theories on noncommutative spaces and other applications requiring a star-product formalism [68]. However it is known that κ -Minkowski spacetime with κ -Poincaré Hopf algebra as a symmetry cannot be obtained by twisting. Nevertheless, both objects can be further quantized by twist. Also some extensions of Poincaré algebra are amenable to twist formulation [23, 28, 68]. That is why the last part of this paper we devote to (further) twisting of $\kappa(\tau)$ -deformed noncommutative spacetimes.

We recall that twisting two-tensors F are invertible elements fulfilling 2-cocycle and normalization conditions [29, 38, 39]. Let us also remind that in the process of twisted deformation of the underlying spacetime algebra (H -module algebra) the current ‘kappa’ $*$ -multiplication is replaced by a new twist-deformed one

$$x \star_F y = m \circ F^{-1} \triangleright (x \otimes y) = (\bar{f}^{\alpha} \triangleright x) \star (\bar{f}_{\alpha} \triangleright y), \tag{4.1}$$

where \triangleright denotes the classical action (e.g. like the one in (3.59)). 2-cocycle condition guarantees associativity of the corresponding twisted star-product (4.1). Twisted deformations lead to noncommutative spacetimes which, in general form, involve dimensionfull parameters

$$[x^{\mu} x^{\nu}]_{\star} = \Xi^{\mu\nu}(x) = i\theta^{\mu\nu} + i\theta_{\rho}^{\mu\nu} x^{\rho} + i\theta_{\lambda\rho}^{\mu\nu} x^{\lambda} x^{\rho} + \dots,$$

with a constant, Lie-algebraic, quadratic, etc. contributions. Such deformation of spacetime algebra however, requires suitable modification of its relativistic symmetries as well. According to

the Leibniz rule (3.60) the coalgebra sector (of the Hopf algebra) would change correspondingly. In the case under consideration this can be done by twisting

$$\Delta_\tau^F(X) = F\Delta_\tau(X)F^{-1}. \quad (4.2)$$

In this section we will focus on Lie algebra type quantized noncommutative 4-dimensional space-times obtained from twisting of $\kappa(\tau)$ -Minkowski spacetime (3.58)¹⁵. After such twisting, it will become a Hopf module algebra over the twisted κ -Poincaré Hopf algebra $U_{\kappa,\tau}^F(\text{iso}(g))$. It is a way to obtain new quantum algebras from the $\kappa(\tau)$ -Minkowski one.

For this purpose we shall consider certain extensions of the classical r -matrices corresponding to κ -deformations. Then using techniques proposed in [83, 84] and [61] one is able to write the corresponding twists. Zakrzewski [88] has already proposed a list of Abelian extensions of r_τ which we shall use in the time-, light- and space- like cases of the vector τ

$$r_{\tau,\text{ext}} = r_\tau + \xi P_\tau \wedge X, \quad [P_\tau, X] = 0,$$

where X belongs to a Lie algebra for the stability subgroup G_τ of τ (remembering that for time-like case, $G_\tau = \text{SO}(3)$; for light-like case $G_\tau = E(2) = \text{ISO}(2)$; for space-like case $G_\tau = \text{SO}(2,1)$ [26]). Here ξ is a new deformation parameter¹⁶. Later on Lyakhovsky [61] has found more sophisticated extensions of a time-like κ -Poincaré case (11 subcases) showing at the same time that the list presented in [88] is incomplete (as already mentioned by Zakrzewski himself). According to our best knowledge the problem of final classification is still open. We deform the multiplication in algebra (3.58) according to (4.1) with the ‘classical’ (undeformed) action (3.59). Our aim in this section is to describe new emerging spacetime algebras in terms of 4-dimensional Lie algebras. Therefore one limits oneself to the case of Lie-algebraic deformations which for any value of the deformation parameter turns out to be solvable. Then we apply classification scheme for 4-dimensional solvable Lie algebras as introduced in [36]. (For reader’s convenience we recall basic facts of de Graaf’s approach in the Appendix.) In three cases we present also the corresponding deformed κ -Poincaré coproducts. Main results of this section are presented in the following Table 1.

The last two cases come from Lyakhovsky findings. In his notation $\tilde{P}_\pm = P_1 \pm iP_2$, $\tilde{M}_\pm = M_1 \pm iM_2$ and $\sigma_\pm = \ln(1 + \xi\tilde{P}_\pm)$. This implies that these twists are not unitary and the corresponding spacetime algebras are complex. Another fact is that the case S3 with a special values $\xi = \pm\frac{1}{\kappa}$, $\pm\frac{2}{\kappa}$ provide nonequivalent deformations [88]. The same is true for T1 with $\xi = \pm\frac{1}{2\kappa}$, $\pm\frac{1}{\kappa}$, $\pm\frac{2}{\kappa}$ [61].

Twisting light-cone deformation. For convenience we choose a light-cone basis (see footnote 9). Two Abelian twists corresponding to the cases denoted as L1 and L2 have the form¹⁷

$$F_{L1} = e^{i\xi\kappa(M_{+1} \wedge \ln \Pi_+)}, \quad F_{L2} = e^{i\xi\kappa(M_3 \wedge \ln \Pi_+)}.$$

For these two examples, we shall demonstrate how by a chain of consecutive linear transformations of generators one can reach a canonical form from [36].

L1. From twist one obtains the \star -commutators as defining relations for the algebra under consideration¹⁸

$$[x^+, x^1]_\star = \frac{i}{\kappa}x^1 + 2i\xi x^-, \quad [x^+, x^2]_\star = \frac{i}{\kappa}x^2, \quad [x^+, x^-]_\star = \frac{i}{\kappa}x^-.$$

¹⁵Lie-algebraic deformations of undeformed Minkowski spacetime algebra by Abelian twists from the Zakrzewski list [88] have been considered for the first time in [60], see also [31].

¹⁶Some further multi-parameter extensions are also possible (see [83, 84, 88] for details).

¹⁷Notice that both commuting elements M_{+1} , $\ln \Pi_+$ have primitive coproducts in the light-cone deformed κ -Poincaré algebra. The same is true for M_3 , $\ln \Pi_+$.

¹⁸We shall always write only non-vanishing commutators.

Table 1.

type	r -matrix	twist	algebra type
light-like case with $\tau^+ = (1, 0, 0, 0)$ and metric in $2 + 2$ decomposition			
L1	$\xi P_+ \wedge M_{+1}$	$e^{i\xi\kappa(M_{+1} \wedge \ln \Pi_+)}$	$M_{a=1}^3$
L2	$\xi P_+ \wedge M_3$	$e^{i\xi\kappa(M_3 \wedge \ln \Pi_+)}$	$M_{a,b}^6$ with $a = -\frac{(3+(2\kappa\xi)^2)}{9}$, $b = \frac{(1+(2\kappa\xi)^2)}{27}$
space-like case with $\tau^\mu = (0, 1, 0, 0)$ and $\eta_{\mu\nu} = (+, -, -, -)$			
S1	$\xi P_1 \wedge M_1$	$e^{i\xi P_1 \otimes M_1}$	$M_{a,b}^6$ with $a = -\frac{(3+(\kappa\xi)^2)}{9}$, $b = \frac{(1+(\kappa\xi)^2)}{27}$
S2	$\xi P_1 \wedge (M_1 + N_3)$	$e^{i\xi P_1 \otimes (M_1 + N_3)}$	the same as S1
S3	$\xi P_1 \wedge N_3$	$e^{i\xi P_1 \otimes N_3}$	the same as S1
time-like case with $\tau = (1, 0, 0, 0)$ and $\eta_{\mu\nu} = (-, +, +, +)$			
T1	$\xi M_3 \wedge P_0$	$e^{i\xi\kappa \ln \Pi_0 \wedge M_3}$	$M_{a,b}^6$ with $a = -\frac{(3+4(\alpha\kappa)^2)}{9}$, $b = \frac{(1+4(\alpha\kappa)^2)}{27}$
T3	$\pm \frac{1}{2\kappa} M_3 \wedge P_0 + \xi \tilde{M}_\pm \wedge \tilde{P}_\pm$	$e^{\xi \tilde{P}_\pm \Pi_0^{\frac{1}{2}} \otimes \tilde{M}_\pm} e^{\pm \frac{i}{2} \ln \Pi_0 \otimes M_3}$	$M_{b=-\frac{2}{9}}^{13}$ (as complex algebra)
T4	$\pm \frac{1}{\kappa} M_3 \wedge P_0$ $\pm \xi (P_3 \wedge \tilde{M}_\pm + M_3 \wedge \tilde{P}_\pm)$	$e^{\pm \xi \tilde{M}_\pm} e^{-\sigma_\pm \pm \ln \Pi_0} \otimes P_3 e^{\sigma_\pm \otimes M_3} e^{\pm i \ln \Pi_0 \otimes M_3}$	M_8 (as complex algebra)

One can check that for any fixed (real) value of the parameters κ, ξ this is a solvable Lie algebra. Firstly we notice that the coordinates (x^1, x^2, x^-) make a L^1 Abelian 3-dimensional subalgebra. Thus 4-dimensional algebra can be classified as $M_{a=1}^3$ in the following way:

1. Firstly we rescale x^+ as $\frac{\kappa}{i}x^+ = \tilde{x}^0$ to obtain $[\tilde{x}^0, x^1] = x^1 + 2\kappa\xi x^-$, $[\tilde{x}^0, x^2] = x^2$, $[\tilde{x}^0, x^-] = x^-$.
2. Then change the generators as $\tilde{x}^1 = x^1 + \beta x^-$ and $\tilde{x}^- = x^- + \gamma x^1$ to get $[\tilde{x}^0, \tilde{x}^1] = \tilde{x}^-$ with $\gamma = (2\kappa\xi + \beta)$ and $[\tilde{x}^0, x^2] = x^2$, together with $[\tilde{x}^0, \tilde{x}^-] = -\tilde{x}^1 + 2\tilde{x}^-$.

And this algebra can be classified as (cf. Appendix)

$$M_{a=1}^3 : [x^0, x^1] = x^3, \quad [x^0, x^2] = x^2, \quad [x^0, x^3] = -ax^1 + (1+a)x^3 \quad \text{for } a = 1.$$

One can observe that the final form does not depend on the numerical values of the deformation parameters in this case.

L2. The algebra obtained from the second twist is defined by the following relations

$$[x^+, x^1]_\star = \frac{i}{\kappa}x^1 - 2i\xi x^2, \quad [x^+, x^2]_\star = \frac{i}{\kappa}x^2 + 2i\xi x^1, \quad [x^+, x^-]_\star = \frac{i}{\kappa}x^-.$$

Firstly we recognize its 3-dimensional subalgebra (x^-, x^1, x^2) as L^1 -Abelian Lie algebra. The whole 4-dimensional one undergoes the following changes:

1. x^+ goes into $\frac{\kappa}{i}x^+ = x^0$, we also denote x^- by x^3 and put $\alpha = 2\kappa\xi$. This way we get

$$\begin{aligned} [x^0, x^1]_\star &= x^1 - \alpha x^2, & [x^0, x^2]_\star &= x^2 + \alpha x^1, & [x^0, x^3]_\star &= x^3, \\ [x^3, x^1]_\star &= 0, & [x^3, x^2]_\star &= 0, & [x^1, x^2]_\star &= 0. \end{aligned}$$

2. We rename the generators as $x^1 \rightarrow x^2 + \alpha x^1 = \tilde{x}^1$, $\alpha \neq 0$ and we get

$$[x^0, \tilde{x}^1]_\star = 2\tilde{x}^1 - (1 + \alpha^2)x^2, \quad [x^0, x^2]_\star = \tilde{x}^1, \quad [x^0, x^3]_\star = x^3.$$

3. Subsequently we take $\tilde{x}^1 \rightarrow \tilde{x}^1 + x^3 = \bar{x}^1$, $x^2 \rightarrow x^2 + x^3 = \bar{x}^2$,

$$[x^0, \bar{x}^1]_\star = 2\bar{x}^1 + \alpha^2 x^3 - (1 + \alpha^2)\bar{x}^2, \quad [x^0, \bar{x}^2]_\star = \bar{x}^1, \quad [x^0, x^3]_\star = x^3.$$

4. Once more introducing new generators: $x^3 \rightarrow 2\bar{x}^1 + \alpha^2 x^3 - (1 + \alpha^2)\bar{x}^2 = \bar{x}^3$ one obtains

$$[x^0, \bar{x}^1]_* = \bar{x}^3, \quad [x^0, \bar{x}^2]_* = \bar{x}^1, \quad [x^0, \bar{x}^3]_* = 3\bar{x}^3 + (1 + \alpha^2)\bar{x}^2 - (3 + \alpha^2)\bar{x}^1.$$

5. After final change $x^0 \rightarrow \frac{x^0}{3} = x^0$, $\bar{x}^1 \rightarrow 3\bar{x}^1 = x^1$, $\bar{x}^2 \rightarrow 9\bar{x}^2 = x^2$, $\bar{x}^3 = x^3$ which leads to

$$[x^0, x^1]_* = x^3, \quad [x^0, x^2]_* = x^1, \quad [x^0, x^3]_* = x^3 + \frac{(1 + \alpha^2)}{27}x^2 - \frac{(3 + \alpha^2)}{9}x^1$$

with $\alpha = 2\kappa\xi$. The resulting algebra can be recognized as

$$M_{a,b}^6 : [x^0, x^1] = x^3, \quad [x^0, x^2] = x^1, \quad [x^0, x^3] = ax^1 + bx^2 + x^3$$

with $a = -\frac{(3+(2\kappa\xi)^2)}{9}$, $b = \frac{(1+(2\kappa\xi)^2)}{27}$. This time isomorphism class of the resulting algebra does depend on the numerical value of the product $\kappa\xi$.

Twisting of the symmetries. As we mentioned in the previous part one should also perform a twisting of the coalgebra sector of κ -Poincaré Hopf algebra via (4.2). In this section we will focus on 4-dimensional quantized Poincaré Hopf algebra $U_{\kappa,\tau}(\text{iso}(1,3))$. Firstly we will use the light-like twists F_{L1} and F_{L2} and subsequently one of the time-like twist F_{T1} .

Twisting of null-plane Poincaré. Let us focus now on the quantum null-plane Poincaré algebra case [9, 13, 14]. As reminded in the previous sections such algebra is a result of twist deformation. The classical r -matrix corresponding to the vector τ_+ reads

$$r_{LC} = M_{+-} \wedge P_+ + M_{+a} \wedge P^a$$

and $\tau_+^2 = 0$ so it satisfies CYBE (2.6). The coproducts $\Delta_{LC}(X)$ obtained directly from the twist (3.36) via (4.2) $\Delta_{LC}(X) = \mathcal{F}\Delta_0(X)\mathcal{F}^{-1}$ are related with the universal ones (3.31)–(3.35) via $\mathcal{R}\Delta_{LC}(X)\mathcal{R}^{-1} = \Delta_{LC}^{\text{op}}(X) = \Delta_\tau(X)$, where $\mathcal{R} = \mathcal{F}_{21}\mathcal{F}^{-1}$ is a triangular quantum R -matrix.

The algebra relations are (3.27)–(3.30).

Twist F_{L1} . The twisted deformation (4.2) of the coproducts $\Delta_{LC}(X)$ with the twist F_{L1} (see the table) results in the following coalgebra

$$\begin{aligned} \Delta_{L1}(P_+) &= P_+ \otimes 1 + \Pi_+ \otimes P_+, \\ \Delta_{L1}(P_a) &= P_a \otimes 1 + \Pi_+ \otimes P_a - \xi(g_{1a}P_+ \otimes \kappa \ln \Pi_+ - \Pi_+ \kappa \ln \Pi_+ \otimes g_{1a}P_+), \\ \Delta_{L1}(P_-) &= P_- \otimes \Pi_+^{-1} + \Pi_+ \otimes P_- - \frac{1}{\kappa}P_+ \otimes \left(P_- + \frac{1}{2\kappa}C_+\right) \Pi_+^{-1} - \frac{1}{\kappa}P_a \otimes P^a \Pi_+^{-1} \\ &\quad + \xi(P_1 \otimes \Pi_+^{-1}(\kappa \ln \Pi_+) - \Pi_+(\kappa \ln \Pi_+) \otimes P_1) \\ &\quad - \frac{\xi^2}{2}(P_+ \otimes \Pi_+^{-1}(\kappa \ln \Pi_+)^2 + (\kappa \ln \Pi_+)^2 \Pi_+ \otimes P_+) \\ &\quad + \frac{\xi}{\kappa}(P_+ \otimes (\kappa \ln \Pi_+)P_1 \Pi_+^{-1} - P_1(\kappa \ln \Pi_+) \otimes P_+ \Pi_+^{-1}) \\ &\quad + \frac{\xi}{\kappa}P_+(\kappa \ln \Pi_+) \otimes P_1 \Pi_+^{-1} + \frac{\xi^2}{2\kappa}P_+(\kappa \ln \Pi_+)^2 \otimes P_+ \Pi_+^{-1}, \\ \Delta_{L1}(M_{-1}) &= M_{-1} \otimes \Pi_+^{-1} + 1 \otimes M_{-1} - \frac{1}{\kappa}M_{21} \otimes P_2 \Pi_+^{-1} + M_{+-} \otimes \Pi_+^{-1}(\xi \kappa \ln \Pi_+) \\ &\quad - (\xi \kappa \ln \Pi_+) \otimes M_{+-} - \xi M_{+1} \otimes P_1 \Pi_+^{-1} + \xi P_1 \Pi_+^{-1} \otimes \Pi_+^{-1} M_{+1} \\ &\quad + M_{+1} \otimes \Pi_+^{-1} \left(-\frac{1}{\kappa} \left(P_- + \frac{1}{2\kappa}C_+\right) + \frac{1}{2}(\xi \kappa \ln \Pi_+)^2\right) \\ &\quad + \xi \ln \Pi_+ M_{+1} \otimes P_1 \Pi_+^{-1} + \frac{1}{2}(\xi \kappa \ln \Pi_+)^2 \frac{1}{\kappa} M_{+1} \otimes P_+ \Pi_+^{-1} \end{aligned}$$

$$\begin{aligned}
& + \frac{1}{2}(\xi\kappa \ln \Pi_+)^2 \otimes M_{+1} - \frac{1}{\kappa}M_{+2} \otimes (\xi\kappa \ln \Pi_+)P_2\Pi_+^{-1}, \\
\Delta_{L1}(M_{-2}) &= M_{-2} \otimes \Pi_+^{-1} + 1 \otimes M_{-2} - \frac{1}{\kappa}M_{12} \otimes P_1\Pi_+^{-1} - \xi(\kappa \ln \Pi_+) \otimes M_{12} \\
& + \xi M_{12} \otimes \Pi_+^{-1}(\kappa \ln \Pi_+) - \xi M_{+1} \otimes P_2\Pi_+^{-1} + \xi P_2\Pi_+^{-1} \otimes \Pi_+^{-1}M_{+1} \\
& - M_{+2} \otimes \Pi_+^{-1} \left(\frac{1}{2}(\xi\kappa \ln \Pi_+)^2 + \frac{1}{\kappa} \left(P_- + \frac{1}{2\kappa}C_+ \right) \right) \\
& + \frac{1}{2\kappa}(\xi\kappa \ln \Pi)^2 M_{+2} \otimes P_+\Pi_+^{-1} - \frac{1}{2}(\xi\kappa \ln \Pi_+)^2 \otimes M_{+2} \\
& + \xi M_{+2} \otimes \ln \Pi_+ P_1\Pi_+^{-1} - \xi \ln \Pi_+ M_{12} \otimes P_+\Pi_+^{-1} + \xi \ln \Pi_+ M_{+2} \otimes P_1\Pi_+^{-1}, \\
\Delta_{L1}(M_{+b}) &= M_{+b} \otimes 1 + 1 \otimes M_{+b}, \quad b = 1, 2, \\
\Delta_{L1}(M_3) &= M_3 \otimes 1 + 1 \otimes M_3 - \xi(M_{+2} \otimes \kappa \ln \Pi_+ - \kappa \ln \Pi_+ \otimes M_{+2}), \\
\Delta_{L1}(M_{+-}) &= M_{+-} \otimes \Pi_+^{-1} + 1 \otimes M_{+-} - \frac{1}{\kappa}M_{+a} \otimes P^a\Pi_+^{-1} + M_{+1} \otimes \Pi_+^{-1}\xi\kappa \ln \Pi_+ \\
& - \xi\kappa \ln \Pi_+ \otimes M_{+1} - \xi P_+\Pi_+^{-1} \otimes M_{+1}\Pi_+^{-1} - \frac{1}{\kappa}M_{+1}(\xi\kappa \ln \Pi_+ - 1) \otimes P_+\Pi_+^{-1}.
\end{aligned}$$

This constitutes the twisted algebra $U_{\kappa,\tau}^{L1}(\text{iso}(1,3))$.

One should notice that after twisting we are still able to construct q -analog version. It is due to the fact that above expressions are polynomial in the new parameter ξ as well. It agrees with the previous observation that the corresponding spacetime algebra type does not depend on ξ .

Another remark is that $\lim_{\kappa \rightarrow \infty} (\kappa \ln \Pi_+) = P_+$. This allows us to calculate easily the limit $\Delta_{0,L1} = \lim_{\kappa \rightarrow \infty} \Delta_{L1}$.

Twist F_{L2} . The corresponding unitary twist to the classical r -matrix r_{L2} is¹⁹

$$F_{L2} = \exp(i\xi\kappa M_3 \wedge \ln \Pi_+).$$

The (further) twisting via relation (4.2) of the deformed coalgebra structure Δ_{LC} results in

$$\begin{aligned}
\Delta_{L2}(P_1) &= \left(\Pi_0 - 1 + \frac{1}{2}(\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) \right) \otimes P_1 + P_1 \otimes \frac{1}{2}(\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) \\
& - \frac{1}{2}(\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) \otimes iP_2 + iP_2 \otimes \frac{1}{2}(\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}), \\
\Delta_{L2}(P_2) &= (\Pi_0 - 1) \otimes P_2 + P_2 \otimes \frac{1}{2}(\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) + \frac{1}{2}(\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) \otimes P_2 \\
& - iP_1 \otimes \frac{1}{2}(\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) + \frac{1}{2}(\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) \otimes iP_1, \\
\Delta_{L2}(P_+) &= P_+ \otimes 1 + \Pi_+ \otimes P_+, \\
\Delta_{L2}(P_-) &= P_- \otimes \Pi_+^{-1} + \Pi_+ \otimes P_- - \frac{1}{\kappa}P_+ \otimes \left(P_- + \frac{1}{2\kappa}C \right) \Pi_+^{-1} \\
& - \frac{1}{\kappa}P_a \otimes P^a\Pi_+^{-1} \frac{1}{2}(\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) + \frac{i}{\kappa}P_1 \frac{1}{2}(\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) \otimes P_2\Pi_+^{-1} \\
& - \frac{i}{\kappa}P_2 \frac{1}{2}(\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) \otimes P^1\Pi_+^{-1} - \frac{1}{\kappa}P_1 \left(-1 + \frac{1}{2}(\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) \right) \otimes P_2\Pi_+^{-1} \\
& - \frac{1}{\kappa}P_2 \left(-1 + \frac{1}{2}(\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) \right) \otimes P_2\Pi_+^{-1} + \frac{i}{\kappa}P_1 \otimes P_2\Pi_+^{-1} \frac{1}{2}(\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) \\
& - \frac{i}{\kappa}P_2 \otimes P_1\Pi_+^{-1} \frac{1}{2}(\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}),
\end{aligned}$$

¹⁹Abelian form of the twist is due to similar reasons as explained previously.

$$\begin{aligned}
\Delta_{L2}(M_{ab}) &= \Delta_0(M_{ab}), \quad a, b = 1, 2, \quad \alpha, \beta = 1, 2, \\
\Delta_{L2}(M_{+-}) &= M_{+-} \otimes \Pi_+^{-1} + 1 \otimes M_{+-} - \frac{1}{\kappa} M_{+\alpha} \otimes \frac{1}{2} (\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) P^\alpha \Pi_+^{-1} \\
&\quad - \frac{1}{\kappa} \left(-1 + \frac{1}{2} (\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) \right) M_{+\alpha} \otimes P^\alpha \Pi_+^{-1} \\
&\quad + \frac{i}{2\kappa} (\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) M_{+1} \otimes P_2 \Pi_+^{-1} - \frac{i}{2\kappa} M_{+1} \otimes (\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) P_2 \Pi_+^{-1} \\
&\quad + \frac{i}{2\kappa} M_{+2} \otimes (\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) P_1 \Pi_+^{-1} - \frac{i}{2\kappa} (\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) M_{+2} \otimes P_1 \Pi_+^{-1}, \\
\Delta_{L2}(M_{+1}) &= M_{+1} \otimes \frac{1}{2} (\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) + \frac{1}{2} (\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) \otimes M_{+1} \\
&\quad + \frac{1}{2} (\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) \otimes iM_{+2} - iM_{+2} \otimes \frac{1}{2} (\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}), \\
\Delta_{L2}(M_{+2}) &= M_{+2} \otimes \frac{1}{2} (\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) + \frac{1}{2} (\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) \otimes M_{+2} \\
&\quad + \frac{1}{2} (\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) \otimes iM_{+1} - iM_{+1} \otimes \frac{1}{2} (\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}), \\
\Delta_{L2}(M_{-1}) &= \frac{1}{2} (\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) \otimes M_{-1} + M_{-1} \otimes \Pi_+^{-1} \frac{1}{2} (\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) \\
&\quad + \frac{1}{2} (\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) \otimes iM_{-2} - iM_{-2} \otimes \frac{1}{2} (\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) \Pi_+^{-1} \\
&\quad + i \frac{1}{\kappa} M_{+2} \otimes \frac{1}{2} (\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) \left(P_- + \frac{1}{2\kappa} C \right) \Pi_+^{-1} \\
&\quad - \frac{1}{\kappa} M_{+1} \otimes \frac{1}{2} (\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) \left(P_- + \frac{1}{2\kappa} C \right) \Pi_+^{-1} \\
&\quad + \frac{1}{\kappa} M_{21} \frac{1}{2} (\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) \otimes i P_1 \Pi_+^{-1} - \frac{1}{\kappa} M_{21} \otimes \frac{1}{2} (\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) P_2 \Pi_+^{-1} \\
&\quad + \xi (P_+ \Pi_+^{-1} \otimes M_3 \Pi_+^{-1} - M_3 \otimes P_+ \Pi_+^{-1}), \\
\Delta_{L2}(M_{-2}) &= M_{-2} \otimes \frac{1}{2} (\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) \Pi_+^{-1} + \frac{1}{2} (\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) \otimes M_{-2} \\
&\quad + iM_{-1} \otimes \frac{1}{2} (\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) \Pi_+^{-1} - \frac{1}{2} (\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) \otimes iM_{-1} \\
&\quad - \frac{1}{\kappa} M_{+2} \otimes \frac{1}{2} (\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) \left(P_- + \frac{1}{2\kappa} C \right) \Pi_+^{-1} \\
&\quad - \frac{i}{\kappa} M_{+1} \otimes \frac{1}{2} (\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) \left(P_- + \frac{1}{2\kappa} C \right) \Pi_+^{-1} \\
&\quad - \frac{1}{\kappa} M_3 \otimes \frac{1}{2} (\Pi_+^{i\xi\kappa} + \Pi_+^{-i\xi\kappa}) P_1 \Pi_+^{-1} - \frac{i}{\kappa} M_3 \frac{1}{2} (\Pi_+^{i\xi\kappa} - \Pi_+^{-i\xi\kappa}) \otimes P_2 \Pi_+^{-1} \\
&\quad - \xi (M_3 \otimes P_2 \Pi_+^{-1} - P_2 \Pi_+^{-1} \otimes M_3 \Pi_+^{-1}).
\end{aligned}$$

Here we notice that after twisting we are unable to construct q -analog version. It is caused by the fact that above expressions are formal power series in the new parameter ξ as well. The isomorphism class of the corresponding spacetime algebra does depend on the value of $\xi\kappa$.

Since $\lim_{\kappa \rightarrow \infty} \Pi_0^{\pm\kappa} = \exp(\pm P_0)$ we are able to calculate the limit $\Delta_{0,L2} = \lim_{\kappa \rightarrow \infty} \Delta_{L2}$ by replacing

$$\Pi_0^{\pm 1} \mapsto 1, \quad \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) \mapsto \cos(\xi P_0), \quad \frac{1}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) \mapsto i \sin(\xi P_0)$$

and dropping out all terms proportional to $\frac{1}{\kappa}$.

Twisting of κ -Poincaré. The algebra part of the twisted $U_{\kappa, \tau}^{\text{T1}}(\text{iso}(1, 3))$ will be still described by (2.1), (2.2), but the coalgebra part will be deformed accordingly to (4.2). By defor-

ming (3.6)–(3.9) with F_{T_1} we obtain²⁰

$$\begin{aligned} \Delta_{T_1}(P_0) &= P_0 \otimes \Pi_0 + \Pi_0^{-1} \otimes P_0 - \frac{\tau^2}{\kappa} P_3 \Pi_0^{-1} \otimes P_3 - i \frac{\tau^2}{\kappa} P_1 \Pi_0^{-1} \frac{1}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) \otimes P_2 \\ &\quad + i \frac{\tau^2}{\kappa} P_2 \Pi_0^{-1} \frac{1}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) \otimes P_1 + i \frac{\tau^2}{\kappa} P_2 \Pi_0^{-1} \otimes \frac{1}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) P_1 \\ &\quad - i P_1 \frac{\tau^2}{\kappa} \Pi_0^{-1} \otimes \frac{1}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) P_2 - \frac{\tau^2}{\kappa} P^\alpha \Pi_0^{-1} \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) \otimes P_\alpha \\ &\quad - \frac{\tau^2}{\kappa} P^\alpha \Pi_0^{-1} \otimes \left[\frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) - 1 \right] P_\alpha, \quad \alpha, \beta = 1, 2, \end{aligned}$$

$$\begin{aligned} \Delta_{T_1}(P_1) &= P_1 \otimes (\Pi_0 - 1) + P_1 \otimes \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) + \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) \otimes P_1 \\ &\quad + \frac{i}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) \otimes P_2 - P_2 \otimes \frac{i}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}), \end{aligned}$$

$$\begin{aligned} \Delta_{T_1}(P_2) &= P_2 \otimes (\Pi_0 - 1) + P_2 \otimes \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) + \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) \otimes P_2 \\ &\quad + i P_1 \otimes \frac{1}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) - i \frac{1}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) \otimes P_1, \end{aligned}$$

$$\Delta_{T_1}(P_3) = P_3 \otimes \Pi_0 + 1 \otimes P_3,$$

$$\begin{aligned} \Delta_{T_1}(M_1) &= M_1 \otimes \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) + \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) \otimes M_1 \\ &\quad + \frac{i}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) \otimes M_2 - M_2 \otimes \frac{i}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}), \end{aligned}$$

$$\begin{aligned} \Delta_{T_1}(M_2) &= M_2 \otimes \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) + \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) \otimes M_2 \\ &\quad + \frac{i}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) \otimes M_1 - M_1 \otimes \frac{i}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}), \end{aligned}$$

$$\Delta_{T_1}(M_3) = M_3 \otimes 1 + 1 \otimes M_3,$$

$$\begin{aligned} \Delta_{T_1}(M_{01}) &= M_{01} \otimes \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) + \Pi_0^{-1} \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) \otimes M_{01} \\ &\quad + M_3 \Pi_0^{-1} \otimes \xi \tau^2 P_1 \Pi_0^{-1} - \tau^2 \xi P_1 \Pi_0^{-1} \otimes M_3 \\ &\quad - M_{02} \otimes \frac{i}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) + \Pi_0^{-1} \frac{i}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) \otimes M_{02} \\ &\quad + \frac{\tau^2}{\kappa} P_2 \Pi_0^{-1} \otimes \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) M_3 - \frac{\tau^2}{\kappa} P_3 \Pi_\tau^{-1} \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) \otimes M_2 \\ &\quad + i \frac{\tau^2}{\kappa} P_1 \Pi_0^{-1} \otimes \frac{1}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) M_3 + i \frac{\tau^2}{\kappa} \frac{1}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) P_3 \Pi_\tau^{-1} \otimes M_1, \end{aligned}$$

$$\begin{aligned} \Delta_{T_1}(M_{02}) &= M_{02} \otimes \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) + \Pi_0^{-1} \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) \otimes M_{02} \\ &\quad - \tau^2 \xi P_2 \Pi_0^{-1} \otimes M_3 + \tau^2 \xi M_3 \Pi_0^{-1} \otimes P_2 \Pi_0^{-1} \\ &\quad + M_{01} \otimes \frac{i}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) - \frac{i}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) \Pi_0^{-1} \otimes M_{01} \\ &\quad + \frac{\tau^2}{\kappa} P_3 \Pi_\tau^{-1} \otimes \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) M_1 + i \frac{\tau^2}{\kappa} \frac{1}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) P_3 \Pi_\tau^{-1} \otimes M_2 \\ &\quad + i \frac{\tau^2}{\kappa} P_2 \Pi_\tau^{-1} \otimes M_3 \frac{1}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) - \frac{\tau^2}{\kappa} P_1 \Pi_\tau^{-1} \otimes M_3 \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}), \end{aligned}$$

$$\Delta_{T_1}(M_{03}) = M_{03} \otimes 1 + \Pi_0^{-1} \otimes M_{03} - \xi \tau^2 P_3 \Pi_0^{-1} \otimes M_3 + \xi \tau^2 M_3 \Pi_0^{-1} \otimes P_3 \Pi_0^{-1}$$

²⁰Here the following standard notation for Lorentz rotations is used: $M_i = \frac{1}{2} \epsilon_{ijk} M_{jk}$.

$$\begin{aligned}
& -\frac{\tau^2}{\kappa} P_2 \Pi_0^{-1} \otimes \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) M_1 - i \frac{\tau^2}{\kappa} P_1 \Pi_0^{-1} \otimes \frac{1}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) M_1 \\
& - i \frac{\tau^2}{\kappa} \frac{1}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) P_1 \Pi_0^{-1} \otimes M_1 - \frac{\tau^2}{\kappa} \left[\frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) - 1 \right] P_2 \Pi_0^{-1} \otimes M_1 \\
& + \frac{\tau^2}{\kappa} \frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) P_1 \Pi_0^{-1} \otimes M_2 - i \frac{\tau^2}{\kappa} \frac{1}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) P_2 \Pi_0^{-1} \otimes M_2 \\
& - i \frac{\tau^2}{\kappa} P_2 \Pi_0^{-1} \otimes \frac{1}{2} (\Pi_0^{i\xi\kappa} - \Pi_0^{-i\xi\kappa}) M_2 + \frac{\tau^2}{\kappa} P_1 \Pi_0^{-1} \otimes \left[\frac{1}{2} (\Pi_0^{i\xi\kappa} + \Pi_0^{-i\xi\kappa}) - 1 \right] M_2.
\end{aligned}$$

One can compare the above results with the ones in the bicrossproduct basis included in [55].

Again by the similar to the previous rules one can calculate $\lim_{\kappa \rightarrow \infty} \Delta_{T1}$.

Now the special values $\xi = \pm \frac{1}{2\kappa}, \pm \frac{1}{\kappa}, \pm \frac{2}{\kappa}$ provide six new deformations for which, in contrast to the general case, specialization of κ is possible.

Appendix A. Some classes of 4-dimensional solvable Lie algebras

For readers convenience we partially summarize the recent classification results of [36] on which our description is based (see also [72, 76, 79] for earlier results and broader context). For the sake of completeness we begin by recalling the definition. For given Lie algebra \mathfrak{g} we define a sequence of subalgebras of \mathfrak{g} (the so-called lower derived series) by $\mathfrak{g}_{(0)} = \mathfrak{g}$, $\mathfrak{g}_{(1)} = [\mathfrak{g}_{(0)}, \mathfrak{g}_{(0)}], \dots, \mathfrak{g}_{(i)} = [\mathfrak{g}_{(i-1)}, \mathfrak{g}_{(i-1)}]$. We call \mathfrak{g} solvable if $\mathfrak{g}_{(n)} = 0$ for some finite n . In a similar manner, the upper sequence $\mathfrak{g}^{(0)} = \mathfrak{g}$, $\mathfrak{g}^{(1)} = [\mathfrak{g}, \mathfrak{g}^{(0)}], \dots, \mathfrak{g}^{(i)} = [\mathfrak{g}, \mathfrak{g}^{(i-1)}]$ determines nilpotent Lie algebras. For example, nilpotent (e.g. Abelian) algebras are solvable, whereas semisimple algebras are definitely nonsolvable. Moreover, a finite-dimensional Lie algebra \mathfrak{g} over a field of characteristic zero is solvable if and only if $\mathfrak{g}_{(1)} \equiv \mathfrak{g}^{(1)}$ is nilpotent.

The strategy for the classification of all 4-dimensional solvable Lie algebras undertaken in [36] is based on the following observation. Any n -dimensional solvable Lie algebra L over a field \mathbb{F} admits a presentation as $L = \mathbb{F}D \oplus K$, where K is a solvable Lie algebra of dimension $n-1$ and D is a derivation of K . Moreover D is an outer derivation for non-Abelian L .

Therefore one should firstly know corresponding candidates for such subalgebras. Classification of all 3-dimensional real Lie algebras is well known for a long time since Bianchi (Lie himself had earlier classified the complex ones). Here we repeat after [36] all non-isomorphic classes of solvable ones²¹:

L^1 : the Abelian Lie algebra;

L^2 : $[x^3, x^1] = x^1, [x^3, x^2] = x^2$ (3-dimensional κ -Minkowski spacetime algebra);

L_a^3 : $[x^3, x^1] = x^2, [x^3, x^2] = ax^1 + x^2$, where $a \in \mathbb{R}$ (or \mathbb{C});

L_a^4 : $[x^3, x^1] = x^2, [x^3, x^2] = ax^1$, where $a = 0, 1, -1$ in the real case (or $a = 0, 1$ in the complex one).

One should notice that only two of them L^1 and L_0^4 (Heisenberg Lie algebra) are nilpotent.

Thus 4-dimensional solvable Lie algebras are classified by adding derivations to the algebras listed above. The final classification is done for arbitrary field \mathbb{F} and can be found in [36]. Here we are interested only in the real (or complex) cases. We are listing only those equivalence classes which are important in the context of extended κ -Minkowski spacetime algebras studied in this paper²². Following [36] isomorphism classes are denoted by M_a^i , $i = 1, \dots, 14$ with a suitable (discrete or continuous) subscript a (below x^0 is a derivation of $K = \text{gen}\{x^1, x^2, x^3\}$):

²¹We write down only nonzero Lie brackets.

²²We do not know if the remaining classes can be obtained by twisting.

I. $K = L^1$:

- i) M^2 , where $[x^0, x^1] = x^1$, $[x^0, x^2] = x^2$, $[x^0, x^3] = x^3$ (4-dimensional κ -Minkowski spacetime algebra);
- ii) M_a^3 : $[x^0, x^1] = x^1$, $[x^0, x^2] = x^3$, $[x^0, x^3] = -ax^2 + (a+1)x^3$, where $a \in \mathbb{R}$ (or \mathbb{C});
- iii) $M_{a,b}^6$: $[x^0, x^1] = x^3$, $[x^0, x^2] = x^1$, $[x^0, x^3] = x^3 + ax^2 + bx^1$, where $a, b \in \mathbb{R}$ (or \mathbb{C}).

II. $K = L^2$:

- i) M^8 : $[x^1, x^2] = x^2$, $[x^0, x^3] = x^3$.

III. $K = L_0^4$:

- i) M_b^{13} : $[x^0, x^1] = x^1 + bx^3$, $[x^0, x^2] = x^2 = [x^3, x^1]$, $[x^0, x^3] = x^1$, where $b \in \mathbb{R}$ (or \mathbb{C}).

One can notice that algebra M^8 is a direct sum of two 2-dimensional κ -Minkowski algebras. It turns out (by Gröbner basis analysis) that as a complex Lie algebra it is isomorphic to the family of Lie algebras denoted as K_v in [36], where K_v : $[x^0, x^1] = x^1 + vx^2$, $[x^0, x^2] = x^1 = [x^3, x^1]$, $[x^3, x^2] = x^2$, $v \in \mathbb{C}$.

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