A Fock Model and the Segal–Bargmann Transform for the Minimal Representation of the Orthosymplectic Lie Superalgebra $\mathfrak{osp}(m, 2|2n)$

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Abstract. The minimal representation of a semisimple Lie group is a ‘small’ infinite-dimensional irreducible unitary representation. It is thought to correspond to the minimal nilpotent coadjoint orbit in Kirillov’s orbit philosophy. The Segal–Bargmann transform is an intertwining integral transformation between two different models of the minimal representation for Hermitian Lie groups of tube type. In this paper we construct a Fock model for the minimal representation of the orthosymplectic Lie superalgebra $\mathfrak{osp}(m, 2|2n)$. We also construct an integral transform which intertwines the Schrödinger model for the minimal representation of the orthosymplectic Lie superalgebra $\mathfrak{osp}(m, 2|2n)$ with this new Fock model.

Key words: Segal–Bargmann transform; Fock model; Schrödinger model; minimal representations; Lie superalgebras; spherical harmonics; Bessel–Fischer product

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1 Introduction

The classical Segal–Bargmann transform

$$\text{SB}_f (z) := \exp\left(-\frac{1}{2}z^2\right) \int_{\mathbb{R}^m} \exp(2x \cdot z) \exp(-x^2) f(x) dx$$

is a unitary isomorphism from the space of square integrable functions on $\mathbb{R}^m$ to the Fock space of entire functions on $\mathbb{C}^m$ which are square integrable with respect to the weight function $\exp(-|z|^2)$. The Segal–Bargmann transform is defined in such a way that it maps the creation (resp. annihilation) operators on the Schrödinger space to coordinate multiplication (resp. differentiation) on the Fock space. This implies in particular that the harmonic oscillator becomes the much simpler Euler operator on the Fock space [7]. The Segal–Bargmann transform can also be interpreted as an intertwining operator between two models of the metaplectic representation (also known as the Segal–Shale–Weil or oscillator representation) of the metaplectic group, a double cover of the symplectic group. See [14] for more on the classical Segal–Bargmann transform and the metaplectic representation.

The (even part of the) metaplectic representation is a prominent example of a minimal representation. Another extensively studied example is the minimal representation of $O(p, q)$ [21, 22, 23, 20]. The minimal representation of a semisimple Lie group is the irreducible unitary representation that according to the orbit method should correspond to the minimal nilpotent coadjoint orbit [15]. The Segal–Bargmann transform has been generalized to this setting of minimal representations. Namely for a Hermitian Lie group of tube type, there exists an
explicit integral transform which intertwines the Schrödinger and Fock model of the minimal representation [18].

Lie superalgebras and Lie supergroups are generalisations of Lie algebras and Lie groups. They were introduced to mathematically describe supersymmetry. Their representation theory is an active field of study with still a lot of open questions, for instance a description of the unitary irreducible representations. Since most ingredients of the orbit method still exist in the super setting, it is believed that the orbit method should also in the super setting be a good tool for the study of irreducible representations [19, Chapter 6.3]. For example, the irreducible unitary representations of nilpotent Lie supergroups have been classified that way [25, 26].

An ambitious aim in this light would be to construct minimal representations and the intertwining Segal–Bargmann transform for Lie supergroups. Recently a first step in that direction has already been taken. Namely the construction of a minimal representation of the orthosymplectic Lie supergroup OSp(p,q|2n) was accomplished in [6]. In the bosonic case (i.e., n = 0) this realisation corresponds to the Schrödinger model for O(p,q) of [20].

In this article we achieve two further goals. First we construct a Fock model for the minimal representation of the Lie superalgebra osp(m,2|2n). We also define an integral transform which intertwines the Schrödinger model of the minimal representation of osp(m,2|2n) with this Fock model. Note that only for q = 2 the Lie group O(p,q) is Hermitian of tube type and thus only in that case do we have a Segal–Bargmann transform. For that reason we have only constructed a Segal–Bargmann transform in the super setting for osp(m,2|2n). Our main results hold for m − 2n ≥ 4. This restriction comes from [6], where key properties of the integral we use in the definition of the Segal–Bargmann transform are only proven for the case m − 2n ≥ 4.

We will work in this paper always on the algebraic level. So we will work with representations of the Lie superalgebra osp(m,2|2n) instead of the Lie supergroup OSp(m,2|2n), and we will act on super-vector spaces defined using superpolynomials instead of using global sections of a supermanifold. This allows us to circumvent the delicate technicalities associated with supergroups and supermanifolds. Note that in the bosonic case, the spaces we work with are dense in certain Hilbert spaces. Using standard techniques one can then integrate the representation to group level and extend to the whole Hilbert space, see for example [17, Theorem 2.30] or [18, Theorem 2.17]. These techniques no longer work/exist in the super case. There does exist an abstract way to integrate a so-called admissible (g,K)-module to group level [1] which was for example used in [6] to integrate the minimal representation of osp(p,q|2n) to OSp(p,q|2n). However, this approach is not very concrete.

Explicit examples such as the one constructed in this paper could help to develop such integration tools and to find the correct definitions in the super setting. For example our representations ought to be ‘unitary’ in some sense. A definition of unitary representations does exists in the supersetting [8, Definition 2]. However, a large class of Lie superalgebras, including osp(p,q|2n), do not allow for any super unitary representation in this sense [25, Theorem 6.2.1]. This highly unsatisfactory situation has inspired the search for a new or extended definition of a unitary representation [13, 27]. At the moment it is still unclear what the right definition should be, but we believe that the construction of explicit examples which ought to be ‘unitary’ could be useful for this endeavour.

1.1 Structure of the paper
We structure the paper as follows. In Section 2 we fix notations and introduce the spaces and algebras we will use throughout the paper. In Section 3 we recall the Schrödinger model of the minimal representation of osp(m,2|2n) defined in [6]. We also introduce an integral which leads to an osp(m,2|2n)-invariant, non-degenerate, superhermitian form.
The next three sections contain the main body of this paper. In Section 4 we construct the Fock space as a quotient of the space of superpolynomials. We then define the Bessel–Fischer product, which gives us a non-degenerate, superhermitian form on our Fock space (Propositions 4.7 and 4.12). In the bosonic case (n = 0), this Bessel–Fischer product is equivalent to the inner product coming from an integral on the Fock space [18, Proposition 2.6]. Since we do no longer have this integral in the super setting, we construct a direct proof for the superhermitian property. This seems new even in the bosonic case. We also show that our Fock space has a reproducing kernel (Theorem 4.11).

In Section 5 we endow this Fock space with an \( \mathfrak{osp}(m, 2|2n) \)-module structure leading to a Fock model of the minimal representation of \( \mathfrak{osp}(m, 2|2n) \). We prove that this is an irreducible representation and obtain a very explicit description (Theorem 5.3). In particular, we have complete branching rules for the subalgebras \( \mathfrak{osp}(m|2n) \) and \( \mathfrak{osp}(m−1|2n) \).

In Section 6, we define an integral transform which maps the space of functions used in the Schrödinger realisation to the space of functions of the Fock realisation (Definition 6.1). We show that this integral is an intertwining isomorphism which preserves the superhermitian form (Theorems 6.3 and 6.6). We also give an explicit inverse (Definition 6.7). As an application we use the Segal–Bargmann transform to define generalised Hermite functions.

In Appendix A we gather some definitions and results on special functions which are used throughout the paper. We have also put the technical and lengthy proof of Theorem 6.3 in Appendix B.

## 2 Preliminaries and notations

In this paper Jordan and Lie algebras will be defined over complex numbers \( \mathbb{C} \) if they have a \( \mathbb{C} \) in subscript, otherwise they are defined over the field of real numbers \( \mathbb{R} \). Function spaces will always be defined over the complex field \( \mathbb{C} \). We use the convention \( \mathbb{N} = \{0, 1, 2, \ldots\} \).

A super-vector space is defined as a \( \mathbb{Z}_2 \)-graded vector space, i.e., \( V = V_0 \oplus V_1 \), with \( V_0 \) and \( V_1 \) vector spaces. An element \( v \) of a super-vector space \( V \) is called homogeneous if it belongs to \( V_i \), \( i \in \mathbb{Z}_2 \). We call \( i \) the parity of \( v \) and denote it by \( |v| \). An homogeneous element \( v \) is even if \( |v| = 0 \) and odd if \( |v| = 1 \). When we use \( |v| \) in a formula, we are considering homogeneous elements, with the implicit convention that the formula has to be extended linearly for arbitrary elements. We denote the super-vector space \( V \) with \( V_0 = \mathbb{R}^m \) and \( V_1 = \mathbb{R}^n \) as \( \mathbb{R}^{m|n} \). We will always assume \( m \geq 2 \).

### 2.1 Superpolynomials

Let \( \mathbb{K} \) be either \( \mathbb{R} \) or \( \mathbb{C} \).

**Definition 2.1.** The space of superpolynomials over \( \mathbb{K} \) is defined as

\[
\mathcal{P}(\mathbb{K}^{m|2n}) := \mathcal{P}(\mathbb{K}^m) \otimes_\mathbb{C} \Lambda(\mathbb{K}^{2n}),
\]

where \( \mathcal{P}(\mathbb{K}^m) \) denotes the space of complex-valued polynomials over the field \( \mathbb{K} \) in \( m \) variables and \( \Lambda(\mathbb{K}^{2n}) \) denotes the Grassmann algebra in \( 2n \) variables. The variables of \( \mathcal{P}(\mathbb{K}^m) \) and \( \Lambda(\mathbb{K}^{2n}) \) are called even and odd variables, respectively. They satisfy the commutation relations

\[
x_i x_j = (-1)^{|i||j|} x_j x_i,
\]

where \( |i| := |x_i|, i \in \{0, 1, \ldots, m + 2n - 1\} \).

Let \( \langle \cdot, \cdot \rangle_\beta \) be a supersymmetric, non-degenerate, even bilinear form on \( \mathbb{K}^{m|2n} \) with basis \( \{x_i\}_{i=0}^{m+2n-1} \). We denote the matrix components by \( \beta_{ij} := \langle x_i, x_j \rangle_\beta \) and denote the components
of the inverse matrix by $\beta^{ij}$, i.e., $\beta^{ij}$ is defined such that $\sum_j \beta^{ij} \beta^{jk} = \delta_{ik}$. Set $x^j = \sum_i x_i \beta^{ij}$. The differential operator $\partial^i$ is defined as the unique derivation in End $\left(\mathcal{P}(\mathbb{K}^{m|2n})\right)$ such that $\partial^i(x_j) = \delta_{ij}$, with $\delta_{ij}$ the Kronecker delta. We also define $\partial_j = \sum_i \partial^i \beta_{ji}$. Then it holds that $\partial_i(x^j) = \delta_{ij}$.

When we are working with both real and complex polynomials at the same time, we will denote $\partial_i$ and $\partial^i$ for the real variable $x_i$ as $\partial_{x_i}$ and $\partial_{x_i}$, respectively. Similarly, we will denote $\partial_i$ and $\partial^i$ for the complex variable $z_i$ as $\partial_{z_i}$ and $\partial_{z_i}$, respectively.

We will make frequent use of the following operators:

$$R^2 := \sum_{i,j} \beta^{ij} x_i x_j, \quad E := \sum_{i,j} \beta^{ij} x_i \partial_j \quad \text{and} \quad \Delta := \sum_{i,j} \beta^{ij} \partial_i \partial_j. \quad (2.1)$$

Here, the operator $R^2$ is called the square of the radial coordinate and acts through multiplication. The operators $E$ and $\Delta$ are called the Euler operator and the Laplacian, respectively. We have the following lemma.

**Lemma 2.2.** The operators $R^2$, $E$ and $\Delta$ satisfy

$$[\Delta, R^2] = 4E + 2M, \quad [\Delta, E] = 2\Delta, \quad [R^2, E] = -2R^2,$$

where $M = m - 2n$ is the superdimension. In particular, $(R^2, E + M, -\Delta)$ forms an $\mathfrak{sl}_2(2)$-triple. Furthermore, they commute in End $\left(\mathcal{P}(\mathbb{K}^{m|2n})\right)$ with the operators

$$L_{ij} := x_i \partial_j - (-1)^{|i||j|} x_j \partial_i.$$

**Proof.** A straightforward calculation or see, for example, [12].

If we are working with two sets of variables we will add a variable indicator to avoid confusion. For example, we denote

$$R^2_x = \sum_{i,j} \beta^{ij} x_i x_j, \quad E_x = \sum_{i,j} \beta^{ij} x_i \partial_{x_j}, \quad \Delta_x = \sum_{i,j} \beta^{ij} \partial_{x_i} \partial_{x_j}$$

and $L_{ij}^x = x_i \partial_{x_j} - (-1)^{|i||j|} x_j \partial_{x_i}$ for the real variables and

$$R^2_z = \sum_{i,j} \beta^{ij} z_i z_j, \quad E_z = \sum_{i,j} \beta^{ij} z_i \partial_{z_j}, \quad \Delta_z = \sum_{i,j} \beta^{ij} \partial_{z_i} \partial_{z_j}$$

and $L_{ij}^z = z_i \partial_{z_j} - (-1)^{|i||j|} z_j \partial_{z_i}$ for the complex variables.

### 2.2 The orthosymplectic Lie superalgebra

Let $\mathbb{K}$ be either $\mathbb{R}$ or $\mathbb{C}$.

**Definition 2.3.** The **orthosymplectic Lie superalgebra** $\mathfrak{osp}_\mathbb{K}(m|2n, \beta)$ is defined as the subalgebra of $\mathfrak{gl}_\mathbb{K}(m|2n)$ preserving a supersymmetric non-degenerate even bilinear form $\beta$. Thus $\mathfrak{osp}_\mathbb{K}(m|2n, \beta)$ is spanned by $X \in \mathfrak{gl}_\mathbb{K}(m|2n)$ such that

$$\langle X(u), v \rangle_\beta + (-1)^{|u||X|} \langle u, X(v) \rangle_\beta = 0,$$

for all $u, v \in \mathbb{K}^{m|2n}$.

The orthosymplectic Lie superalgebra has a differential operator realisation on $\mathcal{P}(\mathbb{K}^{m|2n})$. A basis in this realisation is given by

$$L_{ij} := x_i \partial_j - (-1)^{|i||j|} x_j \partial_i, \quad \text{for } i < j,$$

$$L_{ii} := 2x_i \partial_i, \quad \text{for } |i| = 1.$$
2.3 Spherical harmonics

Let $\mathbb{K}$ be either $\mathbb{R}$ or $\mathbb{C}$. The space of homogeneous superpolynomials of degree $k$ is denoted by $\mathcal{P}_k(\mathbb{K}^m|2n) := \{ p \in \mathcal{P}(\mathbb{K}^m|2n) : \mathbb{E}p = kp \}$.

The space of spherical harmonics of degree $k$ is defined by $\mathcal{H}_k(\mathbb{K}^m|2n) := \{ f \in \mathcal{P}_k(\mathbb{K}^m|2n) : \Delta f = 0 \}$, i.e., it is the space of homogeneous polynomials of degree $k$ which are in the kernel of the Laplacian.

The Fischer decomposition gives a decomposition of the space of superpolynomials using these spherical harmonics [12, Theorem 3].

**Proposition 2.4.** If $m - 2n \neq -2N$, then $\mathcal{P}(\mathbb{K}^m|2n)$ decomposes as

$$\mathcal{P}(\mathbb{K}^m|2n) = \bigoplus_{k=0}^{\infty} \mathcal{P}_k(\mathbb{K}^m|2n) = \bigoplus_{k=0}^{\infty} \bigoplus_{j=0}^{\infty} R^{2j} \mathcal{H}_k(\mathbb{K}^m|2n).$$

In [24] the following generalisation of the Fischer decomposition was obtained that still holds for the exceptional case $M \in -2N$.

**Proposition 2.5** (generalised Fischer decomposition). The superspace $\mathcal{P}(\mathbb{K}^m|2n)$ decomposes as

$$\mathcal{P}(\mathbb{K}^m|2n) = \bigoplus_{k=0}^{\infty} \mathcal{P}_k(\mathbb{K}^m|2n) = \bigoplus_{k=0}^{\infty} \bigoplus_{j=0}^{\infty} (R^2 \Delta R^2)^j \tilde{\mathcal{H}}_k(\mathbb{K}^m|2n),$$

where

$$\tilde{\mathcal{H}}_k(\mathbb{K}^m|2n) = \{ f \in \mathcal{P}_k(\mathbb{K}^m|2n) : \Delta \Delta f = 0 \}$$

is the space of generalised spherical harmonics of degree $k$.

From [9, Theorem 5.2] we obtain the following.

**Proposition 2.6.** If $M \not\in -2N$, then $\mathcal{H}_k(\mathbb{K}^m|2n)$ is an irreducible $\mathfrak{osp}_\mathbb{K}(m|2n)$-module.

The dimension of the spherical harmonics of degree $k$ is given in [12, Corollary 1].

**Proposition 2.7.** The dimension of $\mathcal{H}_k(\mathbb{K}^m|2n)$, for $m \neq 0$ is given by

$$\dim \mathcal{H}_k(\mathbb{K}^m|2n) = \dim \mathcal{P}_k(\mathbb{K}^m|2n) - \dim \mathcal{P}_{k-2}(\mathbb{K}^m|2n),$$

with

$$\dim \mathcal{P}_k(\mathbb{K}^m|2n) = \sum_{i=0}^{\min(k,2n)} \binom{2n}{i} \binom{k - i + m - 1}{m - 1}.$$ 

We will also use the following formula for the dimension of the spherical harmonics of degree $k$.

**Proposition 2.8.** The dimension of $\mathcal{H}_k(\mathbb{K}^m|2n)$, for $m > 1$ is given by

$$\dim \mathcal{H}_k(\mathbb{K}^m|2n) = \dim \mathcal{P}_k(\mathbb{K}^{m-1}|2n) + \dim \mathcal{P}_{k-1}(\mathbb{K}^{m-1}|2n).$$
Proof. If we prove
\[\dim \mathcal{P}_k(\mathbb{K}^{m|2n}) - \dim \mathcal{P}_{k-2}(\mathbb{K}^{m|2n}) - \dim \mathcal{P}_k(\mathbb{K}^{m-1|2n}) - \dim \mathcal{P}_{k-1}(\mathbb{K}^{m-1|2n}) = 0,\]
then the proposition follows from Proposition 2.7. First suppose \(2n \leq k - 2\), then the above equation becomes
\[
\sum_{i=0}^{2n} \binom{2n}{i} \left( \binom{k-i+m-1}{m-1} - \binom{k-i+m-3}{m-1} \right) - \binom{k-i+m-2}{m-2} - \binom{k-i+m-3}{m-2} = 0,
\]
which is true since the recursive formula of binomial coefficients gives us that
\[
\binom{k-i+m-1}{m-1} - \binom{k-i+m-3}{m-1} - \binom{k-i+m-2}{m-2} - \binom{k-i+m-3}{m-2} = 0,
\]
for all \(i \in \{0,\ldots,2n\}\). For \(2n > k - 2\) we have the following extra terms
\[
\binom{2n}{k-1} \left( \binom{m}{m-1} - \binom{m-1}{m-2} \right) + \binom{2n}{k} \left( \binom{m-1}{m-1} - \binom{m-2}{m-2} \right),
\]
where we ignore the last term if \(2n = k - 1\). Using basic binomial properties, these terms are clearly equal to zero. \(\blacksquare\)

For \(n = 0\) a more insightful reasoning as to why this formula holds is given by Proposition 5 in [11].

2.4 The spin factor Jordan superalgebra \(J\)

To each Hermitian Lie group of tube type corresponds an Euclidean Jordan algebra. These Jordan algebras were a crucial ingredient in the unified approach to construct minimal representations and the Segal–Bargmann transform [17, 18]. More concretely, one can associate with Jordan algebras certain Lie algebras (the structure algebra and the TKK-algebra), and the representations and the Segal–Bargmann transform [17, 18].

More concretely, one can associate with Jordan algebras certain Lie algebras (the structure algebra and the TKK-algebra), and the Jordan algebra is also used in the construction of spaces on which these Lie algebras act. In this paper we will not use anything directly from Jordan theory, but introducing \(\mathfrak{osp}(m, 2|2n)\) via the spin factor Jordan superalgebra leads to a natural decomposition of \(\mathfrak{osp}(m, 2|2n)\) as well as to some interesting subalgebras that we will use.

Definition 2.9. A Jordan superalgebra is a supercommutative superalgebra \(J\) satisfying the Jordan identity
\[
(-1)^{|x||y|} [L_x, L_y] + (-1)^{|y||x|} [L_y, L_x] + (-1)^{|x||z|} [L_z, L_{xy}] = 0 \quad \text{for all } x, y, z \in J.
\]
Here the operator \(L_x\) is (left) multiplication with \(x\) and \([\cdot, \cdot]\) is the supercommutator, i.e.,
\[
[L_x, L_y] := L_x L_y - (-1)^{|x||y|} L_y L_x.
\]

Let \(\mathbb{K}\) be either \(\mathbb{R}\) or \(\mathbb{C}\). We will define the spin factor Jordan superalgebra associated with a supersymmetric, non-degenerate, even, bilinear form. Let \(V_\mathbb{K}\) be a super-vector space over \(\mathbb{K}\) with \(\dim(V_\mathbb{K}) = (m - 1|2n)\) and a supersymmetric, non-degenerate, even, bilinear form \(\langle \cdot, \cdot \rangle_\mathbb{K}\) where, for \(\mathbb{K} = \mathbb{R}\), the even part has signature \((m - 1, 0)\). Recall that we always assume \(m \geq 2\).

We choose a homogeneous basis \((e_i)_{i=1}^{m+2n-1}\) of \(V_\mathbb{K}\). For \(u = \sum_i u^i e_i\) and \(v = \sum_i v^i e_i\) we then have
\[
\langle u, v \rangle_\mathbb{K} = \sum_{i,j} u^i \bar{\beta}_{ij} v^j \quad \text{with } \bar{\beta}_{ij} := \langle e_i, e_j \rangle_\mathbb{K}.
\]
Definition 2.10. The spin factor Jordan superalgebra is defined as $J_{\mathbb{K}} := \mathbb{K}e_0 \oplus V_{\mathbb{K}}$ with $|e_0| = 0$. The Jordan product is given by

$$(\lambda e_0 + u)(\mu e_0 + v) = (\lambda \mu + \langle u, v \rangle) e_0 + \lambda v + \mu u,$$

for $u, v \in V_{\mathbb{K}}$ and $\lambda, \mu \in \mathbb{K}$.

Thus $e_0$ is the unit of $J_{\mathbb{K}}$. We extend the homogeneous basis $(e_i)_{i=1}^{m+2n-1}$ of $V_{\mathbb{K}}$ to a homogeneous basis $(\tilde{e}_i)_{i=0}^{m+2n-1}$ of $J_{\mathbb{K}}$ and extend the bilinear form $\langle \cdot, \cdot \rangle_{\beta}$ as follows. Set $\beta_{00} = -1$, $\beta_{0i} = 0 = \beta_{00}$ and $\beta_{ij} = \tilde{\beta}_{ij}$ for $i, j \in \{1, \ldots, m+2n-1\}$. Then the corresponding form $\langle \cdot, \cdot \rangle_{\beta}$ is a supersymmetric, non-degenerate, even bilinear form on the super-vector space $J_{\mathbb{K}}$ where, for $\mathbb{K} = \mathbb{R}$, the even part has signature $(m - 1, 1)$.

Define $(\beta^{ij})_{ij}$ as the inverse of $(\beta_{ij})_{ij}$. Let $(e^i)_i$ be the right dual basis of $(e_i)_i$ with respect to the form $\langle \cdot, \cdot \rangle_{\beta}$, i.e.,

$$\langle e_i, e^j \rangle_{\beta} = \delta_{ij}. \quad \text{Then}$$

$$e^j = \sum_i e_i \beta^{ij}.$$

In this paper we will assume that the orthosymplectic metric is standardized such that

$$\beta = (\beta_{ij})_{i,j=0}^{m+2n-1} = \begin{pmatrix} -I_{m-1} & 0 \\ 0 & -I_n \end{pmatrix},$$

with $I_d$ the $d$-dimensional identity matrix.

From now on the real spin factor Jordan superalgebra will always be denoted by $J$ or $J_{\mathbb{R}}$ and its complexified version by $J_{\mathbb{C}}$.

2.5 The TKK algebra

With each Jordan (super)algebra one can associate a 3-graded Lie (super)algebra via the TKK-construction. There exist different TKK-constructions in the literature, see [5] for an overview, but for the spin factor Jordan superalgebra $J_{\mathbb{K}}$ all constructions lead to the orthosymplectic Lie superalgebras $\mathfrak{osp}(m, 2|2n)$. We will quickly review the Koecher construction. First consider $\text{Inn}(J_{\mathbb{K}})$, the subalgebra of $\mathfrak{gl}(J_{\mathbb{K}})$ of inner derivations. It is generated by the operators $[L_u, L_v]$, $u, v \in J_{\mathbb{K}}$. If we add the left multiplication operators $L_u$ to the inner derivations we obtain the inner structure algebra:

$$\text{istr}(J_{\mathbb{K}}) := \{ L_u | u \in J_{\mathbb{K}} \} \oplus \text{Inn}(J_{\mathbb{K}}) = \text{span}_{\mathbb{K}} \{ L_u, [L_u, L_v] : u, v \in J_{\mathbb{K}} \}.$$

Let $J_{\mathbb{K}}^+$ and $J_{\mathbb{K}}^-$ be two copies of $J_{\mathbb{K}}$. As a vector space we define the TKK-algebra of $J_{\mathbb{K}}$ as

$$\text{TKK}(J_{\mathbb{K}}) := J_{\mathbb{K}}^- \oplus \text{istr}(J_{\mathbb{K}}) \oplus J_{\mathbb{K}}^+.$$

The Lie bracket on $\text{TKK}(J_{\mathbb{K}})$ is defined as follows. We interpret $\text{istr}(J_{\mathbb{K}})$ as a subalgebra of $\mathfrak{gl}(J_{\mathbb{K}})$ and for homogeneous $x, y \in J_{\mathbb{K}}^\pm$, $u, v \in J_{\mathbb{K}}^\pm$, $a, b \in J_{\mathbb{K}}$ we set

$$[x, u] = 2L_{xu} + 2[L_x, L_u], \quad [x, y] = [u, v] = 0,$$

$$[L_a, x] = ax, \quad [L_a, u] = -ax,$$

$$[[L_a, L_b], x] = [L_a, L_b]x, \quad [[L_a, L_b], u] = [L_a, L_b]u.$$

From [6, Proposition 3.1] we obtain the following
Theorem 2.11. We have
\[ \text{istr}(J_K) = \mathfrak{osp}_K(J_K) \oplus \mathbb{K}L_{e_0} \cong \mathfrak{osp}_K(m - 1, 1) \oplus \mathbb{K}L_{e_0}, \quad \text{TKK}(J_K) \cong \mathfrak{osp}_K(m, 2|2n), \]
where the direct sum decomposition is as algebras.

Using the bilinear form
\[ \beta = \begin{pmatrix}
1 & (\beta_{ij})_{i,j=1}^{m-1} \\
(\beta_{ij})_{i,j=1}^{m} & \beta_{00} \\
\beta_{00} & -1 \\
(\beta_{ij})_{i,j=1}^{m+2n-1}
\end{pmatrix}, \]
we have the following explicit isomorphism of \( \text{TKK}(J_K) \) with the differential operator realisation of \( \mathfrak{osp}_K(m, 2|2n) \):
\[ e_i^- \mapsto L_i,(m+1) + L_{i,0}, \quad e_0^- \mapsto L_{m,(m+1)} + L_{m,0}, \]
\[ L_{e_i} \mapsto L_{i,m}, \quad L_{e_0} \mapsto L_{0,(m+1)}, \]
\[ [L_{e_i}, L_{e_j}] \mapsto L_{i,j}, \]
\[ e_i^+ \mapsto L_{i,(m+1)} - L_{i,0}, \quad e_0^+ \mapsto -L_{m,(m+1)} + L_{m,0}. \]
Here \( \tilde{i} = i \) if \( |i| = 0 \) and \( \tilde{i} = i + 2 \) if \( |i| = 1 \).

3 The Schrödinger model of \( \mathfrak{osp}(m, 2|2n) \)

In the bosonic case (i.e., \( n = 0 \)), the Schrödinger model of the minimal representation of a Hermitean Lie group \( G \) of tube type can be seen as a representation realized on the Hilbert space \( L^2(C) \) where \( C \) is a minimal orbit for the structure group of \( G \), see [18]. In the super setting the classical definition of minimal orbits no longer works. Indeed, supermanifolds, in contrast to ordinary manifolds, are not completely determined by their points. In [6] an orbit was instead defined as the quotient supermanifold of the structure group by a stabilizer subgroup together with an embedding. Using this definition, a minimal orbit \( C \) was constructed which can be characterized by \( R^2 = 0 \), with \( R^2 \) as introduced in (2.1). We refer to Section 4 of [6] for a detailed description of this minimal orbit. We will now recall the Schrödinger model constructed in [6]. A critical role in this construction is played by the Bessel operators.

3.1 The Bessel operator

The Bessel operator \( B_\lambda(x_k) \) is a linear operator acting on \( \mathcal{P}(\mathbb{R}^{m|2n}) \). It depends on a complex parameter \( \lambda \) and an explicit expression is given by
\[ B_\lambda(x_k) := (-\lambda + 2\mathbb{E})\partial_k - x_k\Delta, \]
where \( \mathbb{E} \) and \( \Delta \) are the Euler operator and Laplacian introduced in (2.1).

From Proposition 4.9 of [6] we obtain the following.

Proposition 3.1. The Bessel operators map \( \langle R^2 \rangle \) into \( \langle R^2 \rangle \) if and only if \( \lambda = 2 - M \), where \( M = m - 2n \) is the superdimension of \( \mathbb{R}^{m|2n} \) and \( \langle R^2 \rangle \) is the ideal in \( \mathcal{P}(\mathbb{R}^{m|2n}) \) generated by \( R^2 \).

Therefore we will only use the Bessel operator with the parameter \( 2 - M \) in this paper and we set \( B(x_i) := B_{2-M}(x_i) \). We obtain the following two properties of the Bessel operator from Proposition 4.2 in [4].
Proposition 3.2 (supercommutativity). For all \( i, j \in \{0, \ldots, m + 2n - 1\} \) we have
\[
\mathcal{B}(x_i) \mathcal{B}(x_j) = (-1)^{|i||j|} \mathcal{B}(x_j) \mathcal{B}(x_i).
\]

Proposition 3.3 (product rule). For all \( i, j \in \{0, \ldots, m + 2n - 1\} \) we have
\[
\mathcal{B}(x_i)(\phi \psi) = \mathcal{B}(x_i)(\phi)\psi + (-1)^{|i||\phi|} \phi \mathcal{B}(x_i)(\psi) \\
+ 2(-1)^{|i||\phi|} \mathcal{E}(\phi) \partial_i(\psi) + 2\partial_i(\phi) \mathcal{E}(\psi) - 2x_i \sum_{r,s} (-1)^{|\phi|r} \beta^rs \partial_r(\phi) \partial_s(\psi).
\]

As a direct result from the product rule we have
\[
[B(x_i), x_j] = \beta_{ij}(M - 2 + 2\mathcal{E}) - 2L_{ij},
\]
for all \( i, j \in \{0, \ldots, m + 2n - 1\} \).

In what follows we will mostly use the following slightly modified version of the Bessel operator.

Definition 3.4. The modified Bessel operator \( \mathcal{B}_\lambda(x_k) \) is given by
\[
\mathcal{B}(0) := -\mathcal{B}(0), \quad \mathcal{B}(x_k) := \mathcal{B}(x_k),
\]
for \( k \in \{1, \ldots, m + 2n - 1\} \).

3.2 Radial superfunctions

Let us denote the supervariables \( x_m, \ldots, x_{m+2n-1} \) by \( \theta_1, \ldots, \theta_{2n} \). We keep the notations for \( x_0, \ldots, x_{m-1} \). Define \( \theta^I \) as \( \theta_1^{i_1} \theta_2^{i_2} \cdots \theta_n^{i_n} \) for \( I = (i_1, i_2, \ldots, i_{2n}) \in \mathbb{Z}_+^{2n} \). Consider a function \( h: \mathbb{R} \to \mathbb{R}, h \in C^2(\mathbb{R} \setminus \{0\}) \) and a superfunction \( f = f_0 + \sum_{I \neq 0} f_I \theta^I \), with \( f_0, f_I \in C^\infty(\mathbb{R}^m) \) and where \( f_0 \) has non-zero values. Then a new superfunction
\[
h(f) := \sum_{j=0}^{2n} \frac{1}{j!} \left( \sum_{I \neq 0} f_I \theta^I \right)^j h^{(j)}(f_0)
\]
is defined in [10, Definition 3]. Here \( h^{(j)} \) denotes the \( j \)th derivative of \( h \).

Set the supervariable
\[
r^2 := \sum_{i=1}^{m+2n-1} x^i x_i,
\]
so \( R^2 = -x_0^2 + r^2 \). We can use equation (3.2) with \( f = (x_0^2 + r^2)/2 \) and \( h \) the square root to define the superfunction \( |X| \) as
\[
|X| := \sqrt{x_0^2 + r^2}/2.
\]

Using equation (3.2) again, but now with \( f = |X| \) we define \( \exp(|X|) \) and \( \Lambda_{2,j}^{\mu,\nu}(|X|) \) as radial superfunctions. Here \( \Lambda_{2,j}^{\mu,\nu} \) is the generalised Laguerre function introduced in Appendix A.2.
3.3 The \((\mathfrak{g}, \mathfrak{k})\)-module \(W\)

We introduce the notations
\[
\mathfrak{g} := \text{TKK}(J) \cong \mathfrak{osp}(m, 2|2n),
\]
\[
\mathfrak{k} := \{(x, I, -x) : I \in \text{Inn}(J), x \in J\},
\]
\[
\mathfrak{k}_0 := \mathfrak{k} \cap \text{istr}(J) = \text{Inn}(J).
\]

**Theorem 3.5.** The following isomorphisms
\[
\mathfrak{k}_0 \cong \mathfrak{osp}(m - 1, 0|2n), \quad \mathfrak{k} \cong \mathfrak{osp}(m, 0|2n) \oplus \mathbb{R},
\]
hold as algebras.

**Proof.** This follows from a straightforward verification by, for example, looking at the matrix realisation of \(g\). □

In Section 5.2 of [6] the so-called Schrödinger model of \(g\) was constructed for \(M \geq 4\). Since this model will play an important role in this paper, we will give a short recall of its construction.

Firstly, we consider a representation \(\pi\) of \(g\) acting on smooth superfunctions on \(J^−\). Explicitly,
\[
\hat{\pi}(e_l, 0, 0) = -2i\tilde{\mathbb{B}}(x_l),
\]
\[
\hat{\pi}(0, L_{e_k}, 0) = -x_0\partial_k + x_k\partial_0,
\]
\[
\hat{\pi}(0, [L_{e_i}, L_{e_j}], 0) = x_i\partial_j - (-1)^{|i||j|}x_j\partial_i,
\]
\[
\hat{\pi}(0, L_{e_0}, 0) = \frac{2-M^2}{2} - \mathbb{E},
\]
\[
\hat{\pi}(0, 0, e_l) = -\frac{1}{2}i\tilde{\mathbb{B}}(x_l),
\]
with \(i, j, k \in \{1, 2, \ldots, m + 2n - 1\}, l \in \{0, 1, \ldots, m + 2n - 1\}\) and where \(i\) is the imaginary unit. For \(n = 0\), our convention corresponds to the Schrödinger realisation given in [18]. It only differs from the Schrödinger realisation given in [6] by a change of basis. It can be shown that all the operators occurring in \(\pi\) are tangential to \(R^2\), with \(R^2\) as in equation (2.1). So we can consider the representation obtained by quotienting out \(R^2\). This quotient representation has an interesting subrepresentation consisting of \(\mathfrak{k}\)-finite vectors. It is generated by \(\exp(-2|X|)\), with \(\exp(-2|X|)\) the smooth radial superfunction on \(J^−\) as defined in Section 3.2. This subrepresentation will be our Schrödinger model. So the Schrödinger model is given as follows:

\[
W := \frac{U(\mathfrak{g}) \exp(-2|X|)}{\langle R^2 \rangle},
\]

where the \(\mathfrak{g}\)-module structure is given by the Schrödinger representation \(\pi\).

Theorem 5.3 of [6] gives the following decomposition of \(W\).

**Theorem 3.6 (decomposition of \(W\)).** Assume \(M \geq 4\).

1. The decomposition of \(W\) as a \(\mathfrak{k}\)-module is given by

\[
W = \bigoplus_{j=0}^\infty W_j, \quad \text{with} \quad W_j = U(\mathfrak{k})\Lambda_{2,j}^{M-3,-1}(2|X),
\]

where \(W_j\) and thus also \(W\) are \(\mathfrak{k}\)-finite.

2. \(W\) is a simple \(\mathfrak{g}\)-module.
(3) An explicit decomposition of $W_j$ into irreducible $\mathfrak{k}_0$-modules is given by

$$W_j = \bigoplus_{k=0}^{j} \bigoplus_{l=0}^{1} \Lambda_{2j-k}^{m-3+2k,2l-1}(2|X|)(\mathcal{H}_k(\mathbb{R}^{m-1}|2n)) \otimes \mathcal{H}_l(\mathbb{R}).$$

Furthermore, if $m$ is even we also have the following $\mathfrak{k}$-isomorphism

$$W_j \cong \mathcal{H}_j(\mathbb{R}^{m+1}) \otimes \mathcal{H}_{M-2+j}(\mathbb{R}^2).$$

### 3.4 The integral and sesquilinear form

In Section 8 of [6] an integral which restricts to $W$ was constructed. We will use a renormalized version of that integral, restricted to $x_0 > 0$. To give the integral explicitly we consider spherical coordinates in $\mathbb{R}^{m-1}$ by setting $x_i = \omega_i s$ with $\omega_i \in S^{m-2}$, $i \in \{1, \ldots, m-1\}$ and

$$s^2 := \sum_{i=1}^{m-1} x_i^2.$$ 

We also introduce the following notations

$$\theta^2 := \sum_{i,j=m}^{m+2n-1} \beta^{ij} x_i x_j, \quad 1 + \eta := \sqrt{1 - \frac{\theta^2}{2s^2}}, \quad 1 + \xi := \sqrt{1 + \frac{\theta^2}{2x_0^2}}$$

and the morphism

$$\phi^\sharp(f) := \sum_{j=0}^{n} \frac{\theta^2 j!}{2^j} \left( \frac{1}{4x_0} \partial_{x_0} - \frac{1}{4s} \partial_s \right)^j f,$$

for $f \in C^\infty(\mathbb{R}^m \setminus \{0\}) \otimes \Lambda(\mathbb{R}^{2n})$. We remark that in [6, Lemma 8.2] it is shown that $\phi^\sharp$ is actually an algebra isomorphism. The Berezin integral on $\Lambda(\mathbb{R}^{2n})$ is defined as

$$\int_B := \partial^{m+2n-1} \partial^{m+2n-2} \ldots \partial^m.$$ 

**Definition 3.7.** Suppose $M \geq 4$. For $f \in W$ we define the integral $\int_W$ by

$$\int_W f := \frac{1}{\gamma} \int_{0}^{\infty} \int_{S^{m-2}} \int_{B} \rho^{m-3}(1+\eta)^{m-3}(1+\xi)^{-1} \phi^\sharp(f)_{|s=x_0=\rho} d\rho d\omega,$$

where $\gamma \in \mathbb{C}$ is the renormalisation factor such that $\int_W \exp(-4|X|) = 1$.

We can show that the integral is well defined modulo $\langle R^2 \rangle$. This follows from Section 8 of [6] together with the fact that $\gamma$ is non-zero.

**Proposition 3.8.** For $M = m - 2n \geq 4$ we have

$$\gamma = \frac{2^{5-2M}}{n!} \left( \frac{3 - m}{2} \right) \frac{\pi^{m-1}}{\Gamma(\frac{m-1}{2})} \Gamma(M - 2),$$

where we used the Pochhammer symbol $(a)_k = a(a+1)(a+2) \cdots (a+k-1)$. Note that $(\frac{3-m}{2})_n = 0$ implies $M = m - 2n \leq 1$. Therefore $\gamma$ is non-zero.
Proof. Let us denote the integral $f_W$ not normalized by $\gamma$ as $f_{W'}$, i.e., $f_{W'} = \gamma f_W$. We wish to calculate

$$\gamma = \int_{W'} \exp(-4|X|).$$

In [3, Lemma 6.3.5] a similar integral is calculated if one observes that $\tilde{K}_{-\frac{1}{2}}(t) = \frac{\sqrt{\pi}}{2} \exp(-t)$, (equation (A.1) in Appendix A.1) where $\tilde{K}_\alpha$ is the K-Bessel function introduced in Appendix A.1. Using the same calculations as in the proof of [3, Lemma 6.3.5], we then obtain

$$\gamma = \frac{1}{n!} \left(\frac{3 - m}{2}\right) \frac{\pi^{\frac{m-3}{2}}}{\Gamma\left(\frac{m-1}{2}\right)} \frac{\Gamma\left(M\right)}{\Gamma\left(M - 1\right)} \frac{\Gamma\left(M - \frac{1}{2}\right)^2}{\Gamma\left(M - \frac{1}{2}\right)},$$

provided we take into account that we need extra factors 2 in certain places and that we restrict ourselves to $x_0 > 0$. Note that in [3, Lemma 6.3.5] the tilde in $\tilde{K}_{-\frac{1}{2}}$ sometimes mistakenly disappears. If we use Legendre's duplication formula:

$$\Gamma\left(\frac{z+1}{2}\right) \Gamma\left(\frac{z}{2}\right) = 2^{1-z} \sqrt{\pi} \Gamma(z),$$

on $\Gamma\left(M\right) \Gamma\left(M - \frac{1}{2}\right)$ and $\Gamma\left(M - \frac{1}{2}\right) \Gamma\left(M - 1\right)$ the result follows.

Definition 3.9. For $f, g \in W$ we define the sesquilinear form $\langle \cdot, \cdot \rangle_W$ as

$$\langle f, g \rangle_W := \int_W f \overline{g}.$$

Theorem 8.13 and Lemma 8.14 in [6] give us the following two properties.

Proposition 3.10. Suppose $M = m - 2n \geq 4$. The Schrödinger representation $\pi$ on $W$ is skew-supersymmetric with respect to $\langle \cdot, \cdot \rangle_W$, i.e.,

$$\langle \pi(X)f, g \rangle_W = -(-1)^{|X||f|} \langle f, \pi(X)g \rangle_W,$$

for all $X \in g$ and $f, g \in W$.

Proposition 3.11. Suppose $M = m - 2n \geq 4$. The form $\langle \cdot, \cdot \rangle_W$ defines a sesquilinear, non-degenerate form on $W$, which is superhermitian, i.e.,

$$\langle f, g \rangle_W = (-1)^{|f||g|} \langle g, f \rangle_W,$$

for all $f, g \in W$.

Note that for both Theorem 8.13 and Lemma 8.14 in [6] there is an extra condition saying that $M$ must be even. However, since we are working in the exceptional case that corresponds with $q = 2$ in [6], the proofs still hold without this extra condition.

4 The Fock space

In [18, Section 2.3] an inner product on the polynomial space $P(\mathbb{C}^m)$ was introduced, namely the Bessel–Fischer inner product

$$\langle p, q \rangle_B := p(\widetilde{B}) \overline{q}(z)|_{z=0},$$

where $\overline{q}(z) = q(\overline{z})$ is obtained by conjugating the coefficients of the polynomial $q$. In [18, Proposition 2.6] it is proven that, for polynomials, the Bessel–Fischer inner product is equal to the $L^2$-inner product of the Fock space. Since there is no immediate extension of this $L^2$-inner product to the super setting, we will use the Bessel–Fischer inner product on polynomials as the starting point to generalize the Fock space to superspace.
4.1 Definition and properties

Definition 4.1. We define the polynomial Fock space as the superspace

\[ \mathcal{F} := \mathcal{P}(\mathbb{C}^{m|2n})/\langle R^2 \rangle. \]

From the generalised Fischer decomposition of Proposition 2.5 it follows that

\[ \mathcal{F} \cong \bigoplus_{l=0}^{\infty} \tilde{\mathcal{H}}_l(\mathbb{C}^{m|2n}). \]

In particular, if the superdimension \( M = m - 2n \) is such that \( M \notin -2\mathbb{N} \), then the Fischer decomposition from Proposition 2.4 gives us

\[ \mathcal{F} \cong \bigoplus_{l=0}^{\infty} \mathcal{H}_l(\mathbb{C}^{m|2n}). \]

Definition 4.2. For \( p, q \in \mathcal{P}(\mathbb{C}^{m|2n}) \) we define the Bessel–Fischer product of \( p \) and \( q \) as

\[ \langle p, q \rangle_B := \frac{p(\tilde{B}) \bar{q}(z)}{|z|}, \]

where \( \bar{q}(z) = \bar{q}(\bar{z}) \) is obtained by conjugating the coefficients of the polynomial \( q \) and \( \tilde{B} \) is the complex version of the modified Bessel operators introduced in Definition 3.4.

Explicitly for \( p = \sum_{\alpha} a_{\alpha} z^{\alpha} \) and \( q = \sum_{\beta} b_{\beta} z^{\beta} \) we have

\[ \langle p, q \rangle_B = \sum_{\alpha, \beta} a_{\alpha} b_{\beta} (-1)^{\alpha_{0}} \mathcal{B}(z_{0})^{\alpha_{0}} \cdots \mathcal{B}(z_{m+2n-1})^{\alpha_{m+2n-1}} \bar{z}_{0}^{\beta_{0}} \cdots \bar{z}_{m+2n-1}^{\beta_{m+2n-1}} \bigg|_{z=0}. \]

Note that it is only an inner product in the bosonic case. However, in [13] a new definition of Hilbert superspaces was introduced where the preserved form is no longer an inner product, but rather a non-degenerate, sesquilinear, superhermitian form. We will prove that the Bessel–Fischer product is such a form when restricted to \( \mathcal{F} \) with \( M - 2 \notin -2\mathbb{N} \).

Proposition 4.3 (sesquilinearity). For \( p, q, r, s \in \mathcal{P}(\mathbb{C}^{m|2n}) \) and \( \alpha, \beta, \gamma, \delta \in \mathbb{C} \) we have

\[ \langle \alpha p + \gamma r, \beta q + \delta s \rangle_B = \alpha \bar{\beta} \langle p, q \rangle_B + \alpha \delta \langle p, s \rangle_B + \gamma \bar{\beta} \langle r, q \rangle_B + \gamma \delta \langle r, s \rangle_B. \]

Proof. This follows from the linearity of the Bessel operators. \( \blacksquare \)

Proposition 4.4 (orthogonality). For \( p_k \in \mathcal{P}_k(\mathbb{C}^{m|2n}) \) and \( p_l \in \mathcal{P}_l(\mathbb{C}^{m|2n}) \) with \( l \neq k \) we have

\[ \langle p_k, p_l \rangle_B = 0. \]

Proof. This follows from the fact that Bessel operators lower the degree of polynomials by one. \( \blacksquare \)

Proposition 4.5. For \( p, q \in \mathcal{P}(\mathbb{C}^{m|2n}) \) and \( i \in \{0, 1, \ldots, m + 2n - 1\} \) we have

\[ \langle z_i p, q \rangle_B = (-1)^{|i||p|} \langle p, \tilde{B}(z_i) q \rangle_B. \]

Proof. This follows immediately from the definition of the Bessel–Fischer product. \( \blacksquare \)

To prove that the Bessel–Fischer product is superhermitian we will use induction on the degree of the polynomials. We will need the following lemma in the induction step of the proof.
Lemma 4.6. Suppose we have proven that \( \langle p, q \rangle_B = (-1)^{|p||q|} \langle q, p \rangle_B \) for all \( p, q \in \mathcal{P}(\mathbb{C}^m|2n) \) of degree lower than or equal to \( k \in \mathbb{N} \). Then for \( p, q \in \mathcal{P}_l(\mathbb{C}^m|2n) \), \( l \leq k \) we have

\[
\langle L_{ij} p, q \rangle_B = (-1)^{|i||j|+|p|} \langle p, L_{ij} q \rangle_B \quad \text{and} \quad \langle L_{0i} p, q \rangle_B = (-1)^{|i||p|} \langle p, L_{0i} q \rangle_B,
\]

for all \( i, j \in \{1, \ldots, m+2n-1\} \).

**Proof.** We will prove the \( L_{ij} \) case explicitly. The \( L_{0i} \) case is entirely analogous. First note that if we combine the given superhermitian property with Proposition 4.5, we get

\[
\langle \tilde{B}(z_i)p, q \rangle_B = (-1)^{|i||p|} \langle p, z_iq \rangle_B.
\]

for all \( p \in \mathcal{P}(\mathbb{C}^m|2n) \) of degree \( k \) or lower and all \( q \in \mathcal{P}(\mathbb{C}^m|2n) \) of degree \( k-1 \) or lower. Assume \( p, q \in \mathcal{P}_l(\mathbb{C}^m|2n) \), \( l \leq k \). We obtain

\[
\langle z_i \partial_j p, q \rangle_B = (-1)^{|i||p|+|j|} \langle \partial_j p, \tilde{B}(z_i)q \rangle_B
\]

This gives

\[
\langle L_{ij} p, q \rangle_B = (z_i \partial_j p, q \rangle_B - (-1)^{|i||j|} \langle z_i \partial_i p, q \rangle_B
\]

\[
= (-1)^{|i||j|+|p|+|j|} \langle p, z_i \partial_j q \rangle_B - (-1)^{|i||j|+|j|} \langle p, z_i \partial_j q \rangle_B
\]

\[
+ (-1)^{|i||p|+|j|} \left( \langle z_j \partial_j p, \partial_z q \rangle_B - \langle \partial_j p, z_i \partial_q q \rangle_B \right)
\]

\[
- (-1)^{|i||p|} \left( \langle z_i \partial_j p, \partial_z q \rangle_B - \langle \partial_j p, z_i \partial_q q \rangle_B \right)
\]

\[
= (-1)^{|i||p|+|j|} \langle p, L_{ij} q \rangle_B + (-1)^{|i||p|+|j|} \left( \langle z_j \partial_j p, \partial_z q \rangle_B - \langle \partial_j p, z_i \partial_q q \rangle_B \right)
\]

\[
- (-1)^{|i||p|} \left( \langle z_i \partial_j p, \partial_z q \rangle_B - \langle \partial_j p, z_i \partial_q q \rangle_B \right),
\]

from which the desired result follows if we prove

\[
0 = (-1)^{|i||p|+|j|} \langle z_j \partial_j p, \partial_z q \rangle_B - (-1)^{|i||p|+|j|} \langle \partial_j p, z_i \partial_q q \rangle_B
\]

\[
- (-1)^{|i||p|} \langle z_i \partial_j p, \partial_z q \rangle_B + (-1)^{|i||p|} \langle \partial_j p, z_i \partial_q q \rangle_B.
\]

(4.1)

For the first term in right hand side of this equation we have

\[
\langle z_j \partial_j p, \partial_z q \rangle_B = (-1)^{|p||j|} \langle \Delta p, \partial_z \tilde{B}(z_i) q \rangle_B
\]

\[
= (-1)^{|p||j|} \left( (M - 2 + 2(l - 1)) \langle \Delta p, \partial_j \partial_z q \rangle_B - \langle \Delta p, z_j \partial_i \partial_q q \rangle_B \right),
\]

such that, using similar calculations for the other three terms, equation (4.1) can be rewritten as

\[
\langle L_{ij} \Delta p, \Delta q \rangle_B = -(-1)^{|i||j|+|p|} \langle \Delta p, L_{ij} \Delta q \rangle_B.
\]

Since \( \Delta p \) and \( \Delta q \) are polynomials of degree lower than \( l \) the lemma follows from a straightforward induction argument on \( l \).

**Proposition 4.7** (superhermitianity). The Bessel–Fischer product is superhermitian, i.e.,

\[
\langle p, q \rangle_B = (-1)^{|p||q|} \langle q, p \rangle_B,
\]

for \( p, q \in \mathcal{P}(\mathbb{C}^m|2n) \).
Thus the Bessel–Fischer product is well-defined on \( F \).

**Proposition 4.9.** For all \( i, j \) for all \( w(x_L, y_L) \), we have

\[
\langle z_i p, z_j q \rangle_B = \langle z_i [B(z_i) p, B(z_i) q] \rangle_B + \langle z_i \beta_{ij} \rangle_B - 2 \langle z_i p, L_{ij} q \rangle_B.
\]

Using the induction hypothesis together with Proposition 4.5 this becomes

\[
\langle z_i p, z_j q \rangle_B = \langle z_i \beta_{ij} \rangle_B - 2 \langle z_i p, L_{ij} q \rangle_B.
\]

Switching the roles of \( z_i p \) and \( z_j q \) we also obtain

\[
\langle z_j q, z_i p \rangle_B = \langle z_j \beta_{ji} \rangle_B - 2 \langle z_j q, L_{ij} p \rangle_B.
\]

where we used the induction hypothesis on all three terms of the right hand side. If we use Lemma 4.6 on the last term and multiply both sides of this equation with \((-1)^{|i|+|j|(|q|+|j|)}\) we get

\[
\langle z_j q, z_i p \rangle_B = (-1)^{|i|+|j|(|q|+|j|)} \langle z_j q, z_i p \rangle_B
\]

where we made use of \( \beta_{ij} = 0 \) for \( |i| \neq |j| \) in the last step.

**Lemma 4.6** can now be extended to the following proposition.

**Corollary 4.8.** We have

\[
\langle L_{ij} p, q \rangle_B = -\langle z_i \beta_{ij} \rangle_B - \langle z_i p, L_{ij} q \rangle_B
\]

for all \( i, j \) and \( p, q \).

**Proposition 4.9.** For all \( p, q \) \( \in \mathcal{P}(\mathbb{C}^m) \) it holds that

\[
\langle R^2 p, q \rangle_B = 0 = \langle p, R^2 q \rangle_B.
\]

Thus the Bessel–Fischer product is well-defined on \( F \).
Proof. Because of the superhermitian property we only need to prove \( \langle p, R^2 q \rangle = 0 \) holds for all \( p, q \in \mathcal{P}(\mathbb{C}^{m|2n}) \). The complex version of Proposition 3.1 implies that for arbitrary \( p, q \in \mathcal{P}(\mathbb{C}^{m|2n}) \) there exists a \( q' \in \mathcal{P}(\mathbb{C}^{m|2n}) \) such that
\[
\langle p, R^2 q \rangle_B = p(\widehat{B}) R^2 q(z)|_{z=0} = R^2 q'(z)|_{z=0}.
\]
Since the constant term of \( R^2 q'(z) \) is always zero this proves the theorem.

Note that the above proposition also shows that the Bessel–Fischer product is degenerate on the space \( \mathcal{P}(\mathbb{C}^{m|2n}) \). In the following subsection we look at the non-degeneracy of the Bessel–Fischer product when we restrict it to \( \mathcal{F} \).

4.2 The reproducing kernel and non-degeneracy

In the bosonic case a reproducing kernel for the Fock space was constructed in Section 2.4 of [18]. We will prove the non-degeneracy of the Bessel–Fischer product on \( \mathcal{F} \) by first constructing a generalisation of this reproducing kernel in superspace.

Lemma 4.10. Suppose \( M - 2 \not\in -2\mathbb{N} \) and \( k \in \mathbb{N} \). Define the superfunction \( \mathbb{K}^k(z, w) \) by
\[
\mathbb{K}^k(z, w) := \frac{1}{4^k k!} \left( \frac{M}{2} - 1 \right)^{-1} (z|w)^k,
\]
where we used the Pochhammer symbol \( (a)_k = a(a+1)(a+2)\cdots(a+k-1) \) and \( z|w \) is defined as
\[
z|w := 2z_0 w_0 + 2 \sum_{i,j=1}^{m+2n-1} z_i \beta^{ij} w_j.
\]
For all \( p \in \mathcal{P}_k(\mathbb{C}^{m|2n}) \) we then have
\[
\langle p, \mathbb{K}^k(z, w) \rangle_B = p(w) \mod \langle R^2_w \rangle.
\]

Proof. We have
\[
\mathbb{B}(z_i)(z|w)^k = (-1)^{k0} ((M - 2 + 2\mathbb{E})\partial_t - z_l \Delta)(z|w)^k
\]
\[
= 2w_k k(M + 2k - 4)(z|w)^{k-1} - 4z_k k(k - 1)R^2_w(z|w)^{k-2}
\]
\[
= 4w_k \left( k + \frac{M}{2} - 2 \right) (z|w)^{k-1} - R^2_w 4z_k k(k - 1)(z|w)^{k-2}.
\]
Now suppose \( p \) is a monomial, i.e., \( p(z) = a \prod_{l=0}^{m+2n-1} z_l^{\alpha_l} \), with \( |\alpha| = k \) and \( a \in \mathbb{C} \). Iterating the previous calculation and working modulo \( R^2_w \) we obtain
\[
\langle p, (z|w)^k \rangle_B = p(\mathbb{B})(z|w)^k|_{z=0} = a \prod_{l=0}^{m+2n-1} \mathbb{B}(z_l)^{\alpha_l}(z|w)^k|_{z=0}
\]
\[
= 4^k (k(k - 1)\cdots 1) \left( k + \frac{M}{2} - 2 \right) \cdots \left( \frac{M}{2} - 1 \right) a \prod_{l=0}^{m+2n-1} w_l^{\alpha_l}
\]
\[
= 4^k k! \left( \frac{M}{2} - 1 \right)^k p(w),
\]
which gives us the desired result.
Theorem 4.11 (reproducing kernel of \( F \)). Suppose \( M - 2 \not\in -2\mathbb{N} \) and define the superfunction \( \mathbb{K}(z, w) \) by

\[
\mathbb{K}(z, w) := \Gamma \left( \frac{M}{2} - 1 \right) \tilde{T}_{M - 2} \left( \sqrt{(z|w)} \right) = \sum_{k=0}^{\infty} \frac{1}{4^k k!} \left( \frac{M}{2} - 1 \right)^{-1} \left( z|w \right)^k,
\]

where \( \tilde{T}_{\alpha} \) is the I-Bessel introduced in Appendix A.1. For all \( p \in F \) we have

\[
\langle p, \mathbb{K}(z, w) \rangle_B = p(w).
\]

Proof. By Lemma 4.10, the orthogonality property and the Fischer decomposition we find that

\[
\sum_{k=0}^{\infty} \mathbb{K}^k(z, w) = \sum_{k=0}^{\infty} \frac{1}{4^k k!} \left( \frac{M}{2} - 1 \right)^{-1} \left( z|w \right)^k,
\]

has the desired property.

The non-degeneracy of the Bessel–Fischer product on \( F \) is now an almost immediate result.

Proposition 4.12 (non-degenerate case). For \( M - 2 \not\in -2\mathbb{N} \) the Bessel–Fischer product is non-degenerate on the polynomial Fock space \( F \), i.e., if \( \langle p, q \rangle_B = 0 \), for all \( q \in F \), then \( p = 0 \).

Proof. Suppose \( p \in F \) is such that \( \langle p, q \rangle_B = 0 \) for all \( q \in F \). Using the reproducing kernel we obtain \( p(w) = \langle p, \mathbb{K}(z, w) \rangle_B = 0 \). Hence \( p = 0 \).

Note that the previous proposition only works when \( M - 2 \not\in -2\mathbb{N} \). For the \( M - 2 \in -2\mathbb{N} \) case the Bessel–Fischer product will always be degenerate.

Proposition 4.13 (degenerate case). For \( M - 2 \in -2\mathbb{N} \) the Bessel–Fischer product is degenerate on the polynomial Fock space \( F \), i.e., there exists a \( q \in F \), \( q \neq 0 \) such that \( \langle p, q \rangle_B = 0 \), for all \( p \in F \).

Proof. Suppose \( M - 2 \in -2\mathbb{N} \) and \( q \in \mathcal{H}_{2-\frac{M}{2}}(\mathbb{C}^{m|2n}) \subset \mathcal{H}_{2-\frac{M}{2}}(\mathbb{C}^{m|2n}) \subset F \). Then

\[
\tilde{B}(z_i)q = \pm((M - 2 + 2E)\partial_iq - z_i\Delta q) = 0,
\]

for all \( i \in \{0, 1, \ldots, m + 2n - 1\} \). For all \( p \in F \) it follows then immediately from the definition that \( \langle p, q \rangle_B = 0 \). Since

\[
\dim \mathcal{H}_{2-\frac{M}{2}}(\mathbb{C}^{m|2n}) \geq \dim \mathcal{P}_{2-\frac{M}{2}}(\mathbb{C}^{m-1|2n}) \geq 1,
\]

we conclude that such a \( q \neq 0 \) exists.

5 The Fock model of \( \mathfrak{osp}(m, 2|2n) \)

In [18] the Fock representation \( \rho := \pi_C \circ c \) is obtained by twisting the complexification of the Schrödinger representation \( \pi_C \) with the Cayley transform \( c \). This Cayley transform is an isomorphism of \( \mathfrak{g}_C \) which induces a Lie algebra isomorphism between \( \mathfrak{k}_C \) and \( \mathfrak{istr}(J_C) \). We will use a similar approach in our construction of the Fock model. We start by defining a Cayley transform \( c \) in our setting.
5.1 Definition and properties

Let \( g_C \) and \( \mathfrak{t}_C \) be the complexified versions of \( g \) and \( \mathfrak{t} \) introduced in Section 3.3, i.e.,

\[
\begin{align*}
g_C & = \text{TKK}(J_C) \cong \mathfrak{osp}_C(m + 2|2n), \\ \mathfrak{t}_C & = \{(z, I, -z): I \in \text{Inn}(J_C), z \in J_C\} \cong \mathfrak{osp}_C(m|2n) \oplus \mathbb{C},
\end{align*}
\]

Let \( i \) denote the complex unit. Define the Cayley transform \( c \in \text{End}(g_C) \) as

\[
c := \exp \left( \frac{i}{2} \text{ad}(e_0^-) \right) \exp \left( i \text{ad} \left( e_0^+ \right) \right),
\]

with \( e_0^- \) and \( e_0^+ \) the copies of \( e_0 \) in \( J^- \) and \( J^+ \), respectively.

**Proposition 5.1.** Using the decomposition \( g_C = J_C^- \oplus \text{istr}(J_C) \oplus J_C^+ \) we obtain the following explicit expression for the Cayley transform

\[
\begin{align*}
&c(a, 0, 0) = \left( \frac{a}{4}, iL_a, a \right), \\
c(0, L_a + I, 0) = \left( \frac{a}{4}, I, -ia \right), \\
c(0, 0, a) = \left( \frac{a}{4}, -iL_a, a \right),
\end{align*}
\]

with \( a \in J \) and \( I \in \text{Inn}(J_C) \). It induces a Lie superalgebra isomorphism:

\[
c: \mathfrak{t}_C \to \text{istr}(J_C), \quad (a, I, -a) \mapsto I + 2iL_a.
\]

**Proof.** Expanding \( \exp \left( \frac{i}{2} \text{ad}(e_0^-) \right) \exp \left( i \text{ad} \left( e_0^+ \right) \right) \) we obtain

\[
c = 1 + \frac{i}{2} \text{ad}(e_0^-) - \frac{1}{8} \text{ad}(e_0^-) \text{ad}(e_0^-) + i \text{ad}(e_0^+) - \frac{1}{2} \text{ad}(e_0^+) \text{ad}(e_0^+) - \frac{1}{2} \text{ad}(e_0^-) \text{ad}(e_0^+)
\]

\[
- \frac{i}{4} \text{ad}(e_0^-) \text{ad}(e_0^+) \text{ad}(e_0^+) - \frac{i}{8} \text{ad}(e_0^-) \text{ad}(e_0^-) \text{ad}(e_0^+)
\]

\[
+ \frac{1}{16} \text{ad}(e_0^-) \text{ad}(e_0^-) \text{ad}(e_0^+) \text{ad}(e_0^+).
\]

We have the following straightforward calculations

\[
\begin{align*}
c(a, 0, 0) & = a^- + 0 + 0 + 2iL_a + a^+ - a^- - iL_a + 0 + \frac{a^-}{4} = \left( \frac{a}{4}, iL_a, a \right), \\
c(0, L_a + I, 0) & = (L_a + I) + \frac{ia^-}{2} + 0 - ia^+ + 0 - L_a + 0 - \frac{ia^-}{4} + 0 = \left( \frac{a}{4}, I, -ia \right), \\
c(0, 0, a) & = a^+ - iL_a + \frac{a^-}{4} + 0 + 0 + 0 + 0 + 0 + 0 = \left( \frac{a}{4}, -iL_a, a \right),
\end{align*}
\]

proving the theorem.

We complexify the Schrödinger representation \( \pi \) given in Section 3.3 to obtain a representation \( \pi_C \) of \( g_C = J_C^- \oplus \text{istr}(J_C) \oplus J_C^+ \) acting on \( \mathcal{F} \). Explicitly, \( \pi_C \) is given by

\[
\begin{align*}
&\pi_C(e_i, 0, 0) = -2iz_i, \\
&\pi_C(0, L_{e_k}, 0) = -z_0 \partial_k + z_k \partial_0, \\
&\pi_C(0, [L_{e_i}, L_{e_j}], 0) = z_i \partial_j - (-1)^{|i||j|} z_j \partial_i, \\
&\pi_C(0, L_{e_0}, 0) = 2 - \frac{M}{2} - \mathcal{E}, \\
&\pi_C(0, 0, e_l) = -\frac{1}{2} \bar{B}(z_l),
\end{align*}
\]
with $i, j, k \in \{1, 2, \ldots, m + 2n - 1\}$ and $l \in \{0, 1, 2, \ldots, m + 2n - 1\}$. Since $L_{ij}, \mathbb{E}$ and $\overline{B}(z_l)$ map $\langle R^2 \rangle$ into $\langle R^2 \rangle$ this representation is well defined on $\mathcal{F}$. As in the bosonic case, we will define the Fock representation $\rho$ as the composition of $\pi_C$ with the Cayley transform $c$,

$$\rho := \pi_C \circ c.$$

So $\rho$ of $\mathfrak{g} = J^- \oplus i\mathfrak{str}(J) \oplus J^+$ acting on $\mathcal{F}$ is given as follows

- $\rho(e_0, 0, 0) = \frac{i}{2}(z_0 + \overline{B}(z_0) + M - 2 + 2\mathbb{E})$,
- $\rho(e_k, 0, 0) = \frac{i}{2}(z_k + \overline{B}(z_k) + 2(z_0 \partial_k - z_k \partial_0))$,
- $\rho(0, L_{e_0}, 0) = \frac{1}{2}(z_0 - \overline{B}(z_0))$,
- $\rho(0, L_{e_k}, 0) = \frac{1}{2}(z_k - \overline{B}(z_k))$,
- $\rho(0, [L_{e_i}, L_{e_j}], 0) = z_i \partial_j - (-1)^{|i||j|} z_j \partial_i$,
- $\rho(0, 0, e_k) = \frac{i}{2}(z_k + \overline{B}(z_k) - 2(z_0 \partial_k - z_k \partial_0))$,
- $\rho(0, 0, e_0) = \frac{i}{2}(z_0 + \overline{B}(z_0) + 2 - M - 2\mathbb{E})$,

with $i, j, k \in \{1, 2, \ldots, m + 2n - 1\}$.

**Proposition 5.2** ($\mathfrak{osp}(m, 2|2n)$-invariance). The Fock representation $\rho$ on $\mathcal{F}$ is skew-supersymmetric with respect to the Bessel–Fischer product, i.e.,

$$\langle \rho(X)p, q \rangle_B = -(-1)^{|X||p|}\langle p, \rho(X)q \rangle_B,$$

for all $X \in \mathfrak{g}$ and $p, q \in \mathcal{F}$.

**Proof.** Suppose $p, q \in \mathcal{F}$. From Corollary 4.8 we obtain

$$\langle \rho(e_i, 0, -e_i)p, q \rangle_B = \langle -2\mathbb{E}L_0p, q \rangle_B = -(-1)^{|i||p|}\langle p, 2\mathbb{E}L_0q \rangle_B$$

and

$$\langle 0, [L_{e_i}, L_{e_j}], 0)p, q \rangle_B = \langle L_{ij}p, q \rangle_B = -(-1)^{(|i|+|j|)|p|}\langle p, L_{ij}q \rangle_B$$

for $i, j \in \{1, \ldots, m + 2n - 1\}$. Furthermore, we have

$$\langle \rho(e_k, 0, e_k)p, q \rangle_B = \langle \tau(z_k + \overline{B}(z_k))p, q \rangle_B = -\tau\langle z_k p, q \rangle_B + \langle \overline{B}(z_k)p, q \rangle_B$$

and similarly

$$\langle 0, L_{e_k}, 0)p, q \rangle_B = \langle \frac{1}{2}(z_k - \overline{B}(z_k))p, q \rangle_B = -(-1)^{|k||p|}\langle p, \rho(0, L_{e_k}, 0)q \rangle_B,$$

for $k \in \{0, \ldots, m + 2n - 1\}$. Because of Proposition 4.4 we may assume $p$ and $q$ are homogeneous polynomials the same degree. We now have

$$\langle \rho(e_0, 0, -e_0)p, q \rangle_B = \langle -2\mathbb{E}(M - 2 + 2\mathbb{E})p, q \rangle_B = -\langle p, -2\mathbb{E}(M - 2 + 2\mathbb{E})q \rangle_B$$

which proves the theorem. □
5.2 The \((g, \mathfrak{t})\)-module \(F\)

We define

\[
F := U(g)1 \mod \langle R^2 \rangle,
\]

where the \(g\) module structure is given by the Fock representation \(\rho\). We also introduce the notation

\[
F_k := \bigoplus_{l=0}^{k} z_0^l \mathcal{H}_{k-l}(\mathbb{C}^{m-1|2n}) \mod \langle R^2 \rangle
\]

and reintroduce \(r^2\) from Section 3.2 as its complexified version:

\[
r^2 := \sum_{i=1}^{m+2n-1} z_i^2.
\]

We have \(R^2 = -z_0^2 + r^2\) and since we are working modulo \(\langle R^2 \rangle\) this implies \(z_0^2 = r^2\). In the following, we will work modulo \(\langle R^2 \rangle\) but omit \(\langle R^2 \rangle\) from our notation. For \(M - 1 \not\equiv -2N\) we now find

\[
F_k = \bigoplus_{l=0}^{k} z_0^l \mathcal{H}_{k-l}(\mathbb{C}^{m-1|2n}) = \bigoplus_{l=0}^{\frac{k}{2}} z_0^{2l} \mathcal{H}_{k-2l}(\mathbb{C}^{m-1|2n}) \oplus \bigoplus_{l=0}^{\frac{k+1}{2} - 1} z_0^{2l+1} \mathcal{H}_{k-2l-1}(\mathbb{C}^{m-1|2n})
\]

\[
= \bigoplus_{l=0}^{\frac{k}{2}} r^{2l} \mathcal{H}_{k-2l}(\mathbb{C}^{m-1|2n}) \oplus \bigoplus_{l=0}^{\frac{k+1}{2} - 1} z_0 r^{2l} \mathcal{H}_{k-2l-1}(\mathbb{C}^{m-1|2n})
\]

\[
\cong \mathcal{P}_k(\mathbb{C}^{m-1|2n}) \oplus z_0 \mathcal{P}_{k-1}(\mathbb{C}^{m-1|2n}),
\]

where we made use of the Fischer decomposition (Theorem 2.4) in the last step. In particular, by Proposition 2.8,

\[
\dim F_k = \dim \mathcal{P}_k(\mathbb{C}^{m-1|2n}) + \dim \mathcal{P}_{k-1}(\mathbb{C}^{m-1|2n}) = \dim \mathcal{H}_k(\mathbb{C}^{m|2n}).
\]

If \(M \not\equiv -2N\), then for \(p \in F_k\) the Fischer decomposition on \(\mathcal{P}_k(\mathbb{C}^{m|2n})\) also gives

\[
p = \sum_{l=0}^{\frac{k}{2}} R^{2l} h_{k-2l} = h_k \mod \langle R^2 \rangle,
\]

with \(h_{k-2l} \in \mathcal{H}_{k-2l}(\mathbb{C}^{m|2n})\). This implies \(F_k \cong \mathcal{H}_k(\mathbb{C}^{m|2n})\) for \(M \geq 2\).

**Theorem 5.3 (decomposition of \(F\)).** For \(M \geq 3\), we have the following:

1. \(F_k\) is an irreducible \(\mathfrak{t}\)-module.
2. \(F\) is an irreducible \(g\)-module and its \(\mathfrak{t}\)-type decomposition is given by

\[
F = \bigoplus_{k=0}^{\infty} F_k.
\]

3. An explicit decomposition of \(F_k\) into irreducible \(\mathfrak{t}_0\)-modules is given by

\[
F_k = \bigoplus_{l=0}^{k} z_0^l \mathcal{H}_{k-l}(\mathbb{C}^{m-1|2n}) \mod \langle R^2 \rangle.
\]
Proof. We have the following elements of the action of $g$:

\[
\begin{align*}
\rho_0^+ &:= \rho\left(c^{-1}\left(-e_0, 0, 0\right)\right) = iz_0, \\
\rho_0^- &:= \rho(c^{-1}(0, 0, -2e_0)) = i\bar{B}(z_0), \\
\rho_{0i} &:= \rho\left(-\frac{e_i}{2}, 0, \frac{e_i}{2}\right) = iL_{0i}, \\
\rho_{ij} &:= \rho(0, [e_i, e_j], 0) = L_{ij},
\end{align*}
\]

with $i, j \in \{1, \ldots, m + 2n - 1\}$. The elements $\rho_{ij}$ for $i, j \in \{1, \ldots, m + 2n - 1\}, i \leq j$ give rise to an irreducible representation of $\mathfrak{k}_0$ on $\mathcal{H}_k(\mathbb{C}^{m-1}|2n)$ as a result of Proposition 2.6. These elements leave $r^2 = z_0^2$ invariant and therefore also leave powers of $z_0$ invariant, which proves (3).

Again by Proposition 2.6 the elements $\rho_{ij}$ and $\rho_{0i}$ give rise to an irreducible representation of $\mathfrak{k}$ on $\mathcal{H}_k(\mathbb{C}^{m}|2n) \cong F_k$, which proves (1). For the first two elements we have

\[
\begin{align*}
\rho_0^+ (z^k_0) &= iz_0^{k+1}, \\
\rho_0^- (z^k_0) &= i\bar{B}(z_0)z_0^k = ik(M + 2k - 4)z_0^{k-1} - ik(k - 1)z_0^{k-1} = ik(M + k - 3)z_0^{k-1},
\end{align*}
\]

which shows that $\rho_0^+$ allows us to go to polynomials of higher degrees while $\rho_0^-$ allows us to go to the other direction for $M \geq 3$. Therefore we obtain (2). \hfill \blacksquare

The following isomorphism is a direct result of this theorem.

Corollary 5.4. Suppose $M \geq 3$ and let

\[
\mathcal{F} = \mathcal{P}(\mathbb{C}^{m}|2n)/\langle R^2 \rangle
\]

be the polynomial Fock space defined in Definition 4.1. We have $\mathcal{F} \cong F$.

6 The Segal–Bargmann transform

In this section we construct the Segal–Bargmann transform and show that it is an isomorphism from $W$ as defined in Section 3.3 to $F$ as defined in Section 5.2. It will make use of the integral $\int_W$ we defined in Definition 3.7. This integral is only defined for $M \geq 4$. Therefore we will always assume $M \geq 4$ throughout this section.

6.1 Definition and properties

Let $\tilde{I}_\alpha(t)$ be the I-Bessel function as introduced in Appendix A.1. We define an entire function $I_\alpha$ on $\mathbb{C}$ by

\[
I_\alpha(t) := \Gamma\left(M - 1\right)\tilde{I}_{\frac{M}{2} - 2 + \alpha}(2\sqrt{t}) = \Gamma\left(M - 1\right)\sum_{l=0}^{\infty} \frac{1}{l!\Gamma\left(l + \frac{M}{2} - 1 + \alpha\right)}t^l.
\]

Clearly we have $I_\alpha(0) = 1$ and

\[
\partial^j_t I_\alpha(t) = \Gamma\left(M - 1\right)\partial^j_t \tilde{I}_{\frac{M}{2} - 2 + j}(2\sqrt{t}) = \Gamma\left(M - 1\right)\tilde{I}_{\frac{M}{2} - 2 + j}(2\sqrt{t}) = I_j(t).
\]

We are now able to state the Segal–Bargmann transform that extends the one from the bosonic case obtained in [18].
**Definition 6.1.** For \( f \in W \) the *Segal–Bargmann transform* is defined as

\[
\text{SB} f(z) := \exp(-z_0) \int_W I_0(x|z) \exp(-2x_0)f(x),
\]

where \( x|z \) is defined as

\[
x|z := 2x_0z_0 + 2 \sum_{i,j=1}^{m+2n-1} x_i \beta_{ij} z_j
\]

and we view \( I_\alpha(x|z) \) as a radial superfunction in the sense of equation (3.2).

Note that \( I_0(4(x|z)) \) is the reproducing kernel \( K(x,z) \) of the Fock space we found in Theorem 4.11.

**Proposition 6.2.** For \( M \geq 4 \) the Segal–Bargmann transform \( \text{SB} \) is well defined.

**Proof.** We wish to prove that the integral

\[
\int_W I_0(x|z) \exp(-2x_0)f(x)
\]

is convergent for all \( f \in W \) and that \( \text{SB}(R^2) = 0 \). As shown in the proof of Theorem 8.13 in [6], the elements of \( W \) can be decomposed into elements of the form

\[
P_k \tilde{K}_{-\frac{1}{2}+\alpha_1+\alpha_2}(2|X|),
\]

with \( P_k \) a homogeneous polynomial of degree \( k \). Here \( \tilde{K}_\alpha \) is the K-Bessel function introduced in Appendix A.1 interpreted as a radial superfunction as in Section 3.2. Furthermore \( \alpha_1, \alpha_2 \in \mathbb{N} \) are subject to the relations \( k \geq \alpha_1 + 2\alpha_2 \) and \( M \geq 2\alpha_1 + 2 \). Also, observe that

\[
|X| = \sqrt{\frac{x_0^2 + r^2}{2}} = \sqrt{x_0^2 + \frac{R^2}{2}} = \sqrt{x_0^2} \mod \langle R^2 \rangle,
\]

which is equal to \( x_0 \) within the domain of integration of \( \int_W \). Because of all this and equation (A.1) it suffices to prove

\[
\int_W P_k I_0(x|z) \tilde{K}_{-\frac{1}{2}+\alpha_1+\alpha_2}(2|X|)
\]

is convergent for all \( k \in \mathbb{N} \) and \( \alpha_1, \alpha_2 \in \mathbb{N} \) subject to the above mentioned relations. We will use the explicit description of \( \int_W \) given in equation (3.3). The morphism \( \phi^\sharp \) leaves the degree of a polynomial unchanged. Hence, we can expand

\[
(\phi^\sharp(P_k))_{\theta=x_0=\rho} = \sum_{j=0}^{k} \rho^{-j} a_j(\theta)b_j(\omega),
\]

where \( a_j(\theta) \) is a polynomial in \( \mathcal{P}([0,2\pi]) \) of degree \( j \) and \( b_j(\omega) \) is a function depending on the spherical coordinates \( \omega \). For \( c \in \mathbb{Z} \) we obtain

\[
(1 + \eta)^c = \sum_{j=0}^{n} \frac{1}{j!} \left( \frac{-c}{2} \right)^j \frac{\theta^{2j}}{2^j s^{2j}}, \quad (1 + \xi)^c = \sum_{j=0}^{n} \frac{(-1)^j}{j!} \left( \frac{-c}{2} \right)^j \frac{\theta^{2j}}{2^j s^{2j}}
\]
and

$$\phi^x(\widetilde{K}_\alpha(c|X|)) = \widetilde{K}_\alpha(c|X|) = \sum_{j=0}^{n} \frac{(-1)^j c^{2j} \theta^{2j}}{j!s^j} K_{\alpha+j}(c\rho),$$

from the proof of Lemma 8.6 in [6]. Here $\eta$, $\xi$ and $\theta^2$ were defined in Section 3.4. We introduce the notations

$$\omega|z := 2 \sum_{i=1}^{m-1} \omega_i z_i \quad \text{and} \quad \theta|z := 2 \sum_{i,j=m}^{m+2n-1} x_i \beta^j z_j.$$

We can use equation (3.2) with $h = \mathbb{I}_0$ and $f = x|z$ as a function in the $x$ variables to obtain

$$\mathbb{I}_0(x|z) = \mathbb{I}_0(2x_0z_0 + s\omega|z + \theta|z) = \sum_{j=0}^{2n} \frac{1}{j!} (\theta|z)^j \mathbb{I}_j(2x_0z_0 + s\omega|z).$$

Using the properties of $\phi^x$ described in Lemma 8.3 of [6] and the expansion of $(1 + \xi)$ and $(1 + \eta)$, we now find

$$\phi^x(\mathbb{I}_0(x|z))|_{s = x_0 = \rho} = \sum_{l_1=0}^{2n} \frac{1}{l_1!} (\theta|z)^{l_1} \mathbb{I}_{l_1}(2\rho(1 + \xi)z_0 + \rho(1 + \eta)\omega|z))|_{s = x_0 = \rho}$$

$$= \sum_{l_1=0}^{2n} \frac{1}{l_1!} (\theta|z)^{l_1} \mathbb{I}_{l_1} \left( \rho \sum_{l_2=0}^{n} \frac{1}{l_2!} \left( -\frac{1}{2} \right)^{l_2} \frac{\theta^{2l_2}}{2l_2 \rho^{2l_2}} (2(-1)^{l_2}z_0 + \omega|z) \right).$$

We use equation (3.2) again, this time with $h = \mathbb{I}_{l_1}$ and $f$ equal to the sum over $l_2$. Note that the $l_2 = 0$ term corresponds with $f_0$. We obtain

$$\phi^x(\mathbb{I}_0(x|z))|_{s = x_0 = \rho} = \sum_{l_1, l_3=0}^{2n} \frac{1}{l_1! l_3!} (\theta|z)^{l_1} \left( \rho \sum_{l_2=1}^{n} \frac{1}{l_2!} \left( -\frac{1}{2} \right)^{l_2} \frac{\theta^{2l_2}}{2l_2 \rho^{2l_2}} (2(-1)^{l_2}z_0 + \omega|z) \right)^{l_3}$$

$$\mathbb{I}_{l_1 + l_3} (\rho(2z_0 + \omega|z)).$$

Combining all this, we see that

$$\frac{1}{\gamma} \int_0^\infty \int_0^{2m-2} \int_B \rho^{m-3} (1 + \eta)^{m-3} (1 + \xi)^{-1} \times \phi^x (P_k \mathbb{I}_0(x|z) \tilde{K}_{\frac{1}{2}}(2|X|) \tilde{K}_{\rho^{1/2} + \alpha_1 + \alpha_2}(|X|))|_{s = x_0 = \rho} \, d\rho \, d\omega,$$

converges if

$$\int_0^\infty \int_B \rho^{m-3} \sum_{j_1=0}^{k} \sum_{j_2=0}^{n} \sum_{l_1, l_3, j_3=0}^{2n} \frac{1}{l_1! l_3!} \frac{\theta^{2j_2}}{2j_2 \rho^{2j_2}} \left( \frac{3 - m}{2} \frac{1}{j_2!} \left( -\frac{1}{2} \right)^{j_2} \frac{\theta^{2j_2}}{2j_2 \rho^{2j_2}} \right)^{l_3} \times \rho^{k-j_1} \left( \frac{1}{l_1! l_3!} (\theta|z)^{l_1} \left( \rho \sum_{l_2=0}^{n} \frac{1}{l_2!} \left( -\frac{1}{2} \right)^{l_2} \frac{\theta^{2l_2}}{2l_2 \rho^{2l_2}} \right)^{l_3} \mathbb{I}_{l_1 + l_3} (\rho(2z_0 + \omega|z)) \right)$$

$$\times \frac{(-1)^{j_2} \theta^{2j_2}}{j_4! 2j_4} \tilde{K}_{\frac{1}{2} + j_4} (2\rho) \left( \frac{(-1)^{j_5} \theta^{2j_5}}{j_5! 2j_5} \tilde{K}_{\rho^{1/2} + \alpha_1 + \alpha_2} (2\rho) \right) d\rho.$$
Proof. Since \( \exp(\theta) \) converges for all \( c_1, c_2 \subseteq \mathbb{C} \). This in turn converges if
\[
\int_0^\infty \int_B \rho^{m-3+k-j_1+l_3-2l_2-2j_2-2j_3} a_{j_1}(\theta)(\theta|z)^{l_1} \theta^{2j_2+2j_3+2j_4+2j_5+2l_3} \|_{l_1+l_3}(c\rho) \\
\times \tilde{K}_{\frac{1}{2}+j_4}(2\rho) \tilde{K}_{\frac{1}{2}+\alpha_1+\alpha_2+j_5}(2\rho) \rho \, d\rho
\]
converges for all \( 0 \leq j_1 \leq k, 0 \leq j_2, j_3, j_4, j_5 \leq n, 0 \leq l_1, l_3 \leq 2n, 1 \leq l_2 \leq n \) and all \( c \in \mathbb{C} \). The Berezin integral is zero unless \( j_1 + l_1 + 2j_2 + 2j_3 + 2j_4 + 2j_5 + 2l_3l_2 = 2n \). The integral
\[
\int_0^\infty \rho^{2\sigma-1} I_{\beta_3}(\sqrt{\rho}) \tilde{K}_{\beta_3}(2\rho) \tilde{K}_{\beta_3}(2\rho) \rho \, d\rho,
\]
with \( \beta_3 \geq 0 \) converges if \( \sigma > 2 \max\{\beta_2, 0\} + 2 \max\{\beta_3, 0\} \). This follows from the asymptotic behaviour of the Bessel functions, see Appendix A.1. Therefore we get the following condition
\[
m - 2 + k - j_1 + l_3 - 2l_2 - 2j_2 - 2j_3 \\
> 2 \max\left\{-\frac{1}{2} + j_4, 0 \right\} + 2 \max\left\{-\frac{1}{2} + \alpha_1 + \alpha_2 + j_5, 0 \right\},
\]
with \( j_1 + l_1 + 2j_2 + 2j_3 + 2j_4 + 2j_5 + 2l_3l_2 = 2n \). Taking into account \( k \geq \alpha_1 + 2\alpha_2 \) and \( M \geq 2\alpha_1 + 2 \) the condition reduces to \( M > 2 \). We still need that \( \text{SB}(R^2) = 0 \), but this follows easily from \( \left(\phi^2(R^2)\right)_{|s=x_0=\rho} = (-x_0^2 + s^2)_{|s=x_0=\rho} = 0 \).

We can now show that \( \text{SB} \) intertwines the Schrödinger model with the Fock model.

**Theorem 6.3** (intertwining property). For \( M \geq 4 \) the Segal–Bargmann transform intertwines the action \( \pi \) on \( W \) with the action \( \rho \) on \( F \), i.e.,
\[
\text{SB} \circ \pi(X) = \rho(X) \circ \text{SB},
\]
for all \( X \in \mathfrak{g} \).

**Proof.** The proof of this theorem is a technical and long but rather straightforward calculation. We refer to Appendix B for more details.

**Proposition 6.4.** The Segal–Bargmann transform \( \text{SB} \) induces a \( \mathfrak{g} \)-module isomorphism between \( W \) and \( F \).

**Proof.** From the way we normalized the integral \( \int_W \) and equation (6.1) it is clear that
\[
\text{SB}(\exp(-2|X|))(0) = \int_W \exp(-4|X|) = 1.
\]
Therefore the Segal–Bargmann transform maps a non-zero element of \( W \) to a non-zero element of \( F \). It also intertwines the actions \( \pi \) and \( \rho \). Since Theorems 3.6 and 5.3 give us that \( W \) and \( F \) are irreducible \( \mathfrak{g} \)-modules, we conclude that \( \text{SB} \) is an isomorphism of \( \mathfrak{g} \)-modules.

**Lemma 6.5.** We have \( \text{SB}(\exp(-2|X|))(z) = 1 \).

**Proof.** Since \( \exp(-2|X|) \) is in \( W_0 \) Proposition 6.4 implies that \( \text{SB}(\exp(-2|X|))(z) \) is in \( F_0 = \mathbb{C} \). Hence \( \text{SB}(\exp(-2|X|))(z) \) is a constant. From the way we normalized the integral \( \int_W \) we have \( \text{SB}(\exp(-2|X|))(0) = 1 \) and therefore \( \text{SB}(\exp(-2|X|))(z) = 1 \).
Theorem 6.6 (unitary property). For $M \geq 4$ the Segal–Bargmann transform preserves the sesquilinear forms, i.e.,

$$\langle \text{SB} f, \text{SB} g \rangle_B = \langle f, g \rangle_W,$$

for all $f, g \in W$.

**Proof.** We first look at the case $f = \exp(-2|X|)$. Because of Lemma 6.5 and the superhermitian property of the Bessel–Fischer product we have

$$\langle \text{SB}(\exp(-2|X|)), \text{SB} g \rangle_B = \langle 1, \text{SB} g \rangle_B = \langle \text{SB} g, 1 \rangle_B = \text{SB}(g(x))(\tilde{B})1|_{z=0} = \int_W \exp(-2x_0)(I_0(x)|\tilde{B}(z)) \exp(-\tilde{B}(z_0))1 \exp(x)|_{z=0},$$

for all $g \in W$. Here $I_0(x)|\tilde{B}(z))$ and $\exp(-\tilde{B}(z_0))$ should be considered as infinite power sums of the Bessel operator with

$$x|\tilde{B}(z) := 2x_0 \tilde{B}(z_0) + 2 \sum_{i,j=1}^{m+2n-1} x_i \beta^{ij} \tilde{B}(z_j) = 2 \sum_{i,j=0}^{m+2n-1} x_i \beta^{ij} \tilde{B}(z_j).$$

Since they act on a constant with respect to the variable $z$ we get

$$I_0(x)|\tilde{B}(z)) \exp(-\tilde{B}(z_0))1 = I_0(0) \exp(0)1 = 1,$$

which gives

$$\langle \text{SB}(\exp(-2|X|)), \text{SB} g \rangle_B = \int_W \exp(-2x_0)g(x) = \langle \exp(-2|X|), g \rangle_W,$$

if we use equation (6.1). Now suppose $f, g \in W$. Since $W$ is an irreducible $\mathfrak{g}$-module (Theorem 3.6), there exists a $Y \in U(\mathfrak{g})$ such that $f = \pi(Y) \exp(-2|X|)$. Therefore we can reduce the general case to the previous case using the intertwining property (Theorem 6.3) and the fact that the sesquilinear forms are skew symmetric for $\pi$ and $\rho$ (Propositions 3.10 and 5.2):

$$\langle \text{SB} f, \text{SB} g \rangle_B = \langle \text{SB}(\pi(Y) \exp(-2|X|)), \text{SB} g \rangle_B = \langle \rho(Y) \text{SB}(\exp(-2|X|)), \text{SB} g \rangle_B = -\langle \text{SB}(\exp(-2|X|)), \rho(Y) \text{SB} g \rangle_B = -\langle \text{SB}(\exp(-2|X|)), \text{SB}(\pi(Y)g) \rangle_B = -\langle \exp(-2|X|), \pi(Y)g \rangle_W = \langle \pi(Y) \exp(-2|X|), g \rangle_W = \langle f, g \rangle_W,$$

which proves the theorem. \openbullet

### 6.2 The inverse Segal–Bargmann transform

**Definition 6.7.** For $p \in \mathcal{P}(\mathbb{C}^{m|2n})$ the inverse Segal–Bargmann transform is defined as

$$\text{SB}^{-1} p(x) := \exp(-2|X|) I_0(x)|\tilde{B}(z)) \exp(-\tilde{B}(z_0))p(z)|_{z=0},$$

with

$$x|\tilde{B}(z) := 2x_0 \tilde{B}(z_0) + 2 \sum_{i,j=1}^{m+2n-1} x_i \beta^{ij} \tilde{B}(z_j) = 2 \sum_{i,j=0}^{m+2n-1} x_i \beta^{ij} \tilde{B}(z_j).$$

Note that both $I_0(x)|\tilde{B}(z))$ and $\exp(-\tilde{B}(z_0))$ are infinite power sums of the Bessel operator. However, they are well defined operators on polynomials in $z$ since the Bessel operator lowers the degree of the polynomials and therefore the power operators become zero after a finite number of terms. Thus $\text{SB}^{-1}$ is a well-defined operator on $\mathcal{P}(\mathbb{C}^{m|2n})$. Because of Proposition 3.1 it maps $\langle R^2 \rangle$ to zero and thus $\text{SB}^{-1}$ can be restricted to $F$. Moreover, it is also well defined as the inverse of the Segal–Bargmann transform. This follows from the following proposition.
Proposition 6.8. The inverse Segal–Bargmann transform is well defined as the inverse of the Segal–Bargmann transform defined in Definition 6.1.

Proof. From Proposition 6.4, we know that SB has an inverse. Suppose the operator $A$ is this inverse. Using Theorem 6.6 we then have the following calculation:

$$\langle A_p, \psi \rangle_W = \langle SB(A_p), SB \psi \rangle_B = (-1)^{|p||\psi|} \langle SB \psi, p \rangle_B = (-1)^{|p||\psi|} SB \psi(\overline{B})p(z) \big|_{z=0}$$

$$= (-1)^{|p||\psi|} \exp(-\overline{B}(z_0)) \int_W \overline{\Pi}_0(x|\overline{B}(z)) \exp(-2x_0\overline{\psi}(x)p(z)) \big|_{z=0}$$

$$= \int_W \exp(-\overline{B}(z_0)) \overline{\Pi}_0(x|\overline{B}(z)) \exp(-2x_0)p(z) \big|_{z=0} \overline{\psi}(x)$$

$$= \langle \exp(-\overline{B}(z_0)) \Pi_0(x|\overline{B}(z)) \exp(-2|X|)p(z) \big|_{z=0}, \psi \rangle_W,$$

where we used equation (6.1) in the last step. Since the sesquilinear form $\langle \cdot, \cdot \rangle_W$ is non-degenerate we obtain $A = SB^{-1}$.

We can make the inverse Segal–Bargmann transform more explicit on the space of homogeneous polynomials. To the best of our knowledge, this explicit expression is also new for the bosonic case.

Proposition 6.9. For $p \in \mathcal{P}_k(\mathbb{C}^{m|2n})$, $k \in \mathbb{N}$ the inverse Segal–Bargmann transform $SB^{-1}$ is given by

$$SB^{-1}p(x) = \exp(-2|X|) \sum_{j=0}^{k} \frac{(-1)^j}{j!(k-j)!} \Gamma\left(\frac{M}{2} - 1\right) \Gamma\left(k-j + \frac{M}{2} - 1\right) \frac{1}{l!} \overline{\Pi}_0(x|z)^j \langle z_0^j, \overline{\psi} \rangle_B.$$  

Proof. For $p \in \mathcal{P}_k(\mathbb{C}^{m|2n})$ we have

$$SB^{-1}p(x) = \exp(-2|X|) \Pi_0(x|\overline{B}(z)) \exp(-\overline{B}(z_0))p(z) \big|_{z=0}$$

$$= \exp(-2|X|) \langle \Pi_0(x|z) \exp(-z_0), p \rangle_B.$$  

Because of the orthogonality of the Bessel–Fischer product we only need to look at the homogeneous polynomial term of degree $k$ in the expansion of $\Pi_0(x|z) \exp(-z_0)$. Explicitly, we need the homogeneous term of degree $k$ in

$$\Gamma\left(\frac{M}{2} - 1\right) \sum_{l=0}^{\infty} \frac{1}{l!\Gamma(l + \frac{M}{2} - 1)} \langle x|z \rangle^l \sum_{j=0}^{\infty} \frac{(-1)^j}{j!} z_0^j,$$

which is

$$\Gamma\left(\frac{M}{2} - 1\right) \sum_{j=0}^{k} \frac{1}{(k-j)!\Gamma(k-j + \frac{M}{2} - 1)} \langle x|z \rangle^{k-j} \frac{(-1)^j}{j!} z_0^j,$$

as desired.

6.3 The generalized Hermite functions

As a standard application of the Segal–Bargmann transform, we can construct generalized Hermite functions which extend the ones of the bosonic case given in [18].
Definition 6.10. The generalized Hermite functions on \( W \) are defined by
\[
h_\alpha(x) := \exp(2|X|) \left( \frac{1}{2} \tilde{B} \right)^\alpha \exp(-4|X|), \quad \text{with} \quad \left( \frac{1}{2} \tilde{B} \right)^\alpha := \prod_i \frac{1}{2^{\alpha_i}} \tilde{B}(e_i)^{\alpha_i},
\]
for \( \alpha \in \mathbb{N}^{m|2n} \). The generalized Hermite polynomials \( H_\alpha \) are defined by the equation
\[
h_\alpha(x) = H_\alpha(x) \exp(-2|X|).
\]

Proposition 6.11 (Hermite to monomial property). We have
\[
SB \ h_\alpha = (2z)^\alpha.
\]

Proof. We will use the fact that \( \int_W \) is supersymmetric with respect to the Bessel operators \([6, \text{Proposition 8.9}]:\)
\[
\int_W (B(x_k)f)g = (-1)^{|f||k|} \int_W f(B(x_k)g).
\]
Combining this with equation (B.3) of Lemma B.1 we find
\[
SB \ h_\alpha(z) = \exp(-z_0) \int_W \mathbb{I}_0(x|z) \exp(-2x_0) h_\alpha(x)
= \exp(-z_0) \int_W \mathbb{I}_0(x|z) \prod_i \frac{1}{2^{\alpha_i}} \tilde{B}(e_i)^{\alpha_i} \exp(-4|X|)
= \exp(-z_0) \int_W \prod_i \frac{1}{2^{\alpha_i}} \tilde{B}(e_i)^{\alpha_i} (\mathbb{I}_0(x|z)) \exp(-4|X|)
= \exp(-z_0) \int_W \prod_i \frac{1}{2^{\alpha_i}} (4z_0)^{\alpha_i} (\mathbb{I}_0(x|z)) \exp(-4|X|)
= \exp(-z_0) \int_W (2z)^\alpha \mathbb{I}_0(x|z) \exp(-4|X|)
= (2z)^\alpha SB(\exp(-2|X|))(z).
\]
Because of Lemma 6.5 the theorem follows.

A Special functions

A.1 Bessel functions

The I-Bessel function \( I_\alpha(t) \) (or modified Bessel function of the first kind) is defined by
\[
I_\alpha(t) := \left( \frac{t}{2} \right)^\alpha \sum_{k=0}^{\infty} \frac{1}{k! \Gamma(k + \alpha + 1)} \left( \frac{t}{2} \right)^{2k}
\]
and the K-Bessel function \( K_\alpha \) (or modified Bessel function of the third kind) by
\[
K_\alpha(t) := \frac{\pi}{2 \sin(\pi \alpha)} (I_{-\alpha}(t) - I_\alpha(t)),
\]
for \( \alpha, t \in \mathbb{C} \), see \([2, \text{Section 4.12}]\). In this paper we will need the following renormalisations
\[
\tilde{I}_\alpha(t) := \left( \frac{t}{2} \right)^{-\alpha} I_\alpha(t), \quad \tilde{K}_\alpha(t) := \left( \frac{t}{2} \right)^{-\alpha} K_\alpha(t).
\]
Remark that we have the following special case [2, equation (4.12.4)]

\[ \tilde{K}_{-\frac{1}{2}}(t) = \frac{\sqrt{\pi}}{2} \exp(-t). \]  

(A.1)

The asymptotic behaviour of the I-Bessel function can be deducted from equations (4.12.7) and (4.12.8) of [2],

\[ \tilde{I}_\alpha(t) = \frac{1}{\sqrt{2\pi}} (-t^2)^{-\alpha} \left( \exp \left( -i \left( \frac{(2\alpha + 1)\pi}{4} - \sqrt{-t^2} \right) \right) + \exp \left( i \left( \frac{(2\alpha + 1)\pi}{4} - \sqrt{-t^2} \right) \right) \right) \left( 1 + O \left( \frac{1}{t} \right) \right), \]

for \( |t| \to +\infty \). The asymptotic behaviour of the K-Bessel function for \( t \in \mathbb{R} \) is given in Appendix B.2 of [6],

\[
\begin{align*}
&\text{for } t \to 0: \quad \tilde{K}_\alpha(t) = \begin{cases} 
\frac{\Gamma(\alpha)}{2} \left( \frac{t}{2} \right)^{-2\alpha} + o(t^{-2\alpha}) & \text{if } \alpha > 0, \\
-\log \left( \frac{t}{2} \right) + o \left( \log \left( \frac{t}{2} \right) \right) & \text{if } \alpha = 0, \\
\frac{\Gamma(-\alpha)}{2} + o(1) & \text{if } \alpha < 0,
\end{cases} \\
&\text{for } t \to +\infty: \quad \tilde{K}_\alpha(t) = \frac{\sqrt{\pi}}{2} \left( \frac{t}{2} \right)^{-\alpha} \sqrt{\pi} e^{-t} \left( 1 + O \left( \frac{1}{t} \right) \right).
\end{align*}
\]

A.2 Generalised Laguerre functions

Consider the generating function

\[ G_2^{\mu,\nu}(t, x) := \frac{1}{(1 - t)^{\mu + \nu + 1}} \tilde{I}_\nu \left( \frac{tx}{1 - t} \right) \tilde{K}_\frac{\nu}{2} \left( \frac{x}{1 - t} \right), \]

for complex parameters \( \mu \) and \( \nu \). The generalised Laguerre functions \( \Lambda_2^{\mu,\nu}(x) \) are defined in [16] as the coefficients in the expansion

\[ G_2^{\mu,\nu}(t, x) = \sum_{j=0}^{\infty} \Lambda_2^{\mu,\nu}(x) t^j. \]

B Proof of Theorem 6.3

To give the proof of Theorem 6.3 we first need a few technical lemmas.

Lemma B.1 (properties of \( I_0 \)). For \( k \in \{1, \ldots, m + 2n - 1\} \) we have

\[
\begin{align*}
\partial_{z_k} I_0(x|z) &= 2z_k I_1(x|z), & \partial_{x_k} I_0(x|z) &= 2z_k I_1(x|z), \\
\partial_{x_0} I_0(x|z) &= -2x_0 I_1(x|z), & \partial_{z_0} I_0(x|z) &= -2z_0 I_1(x|z), \\
E_z I_0(x|z) &= (x|z) I_1(x|z), & E_x I_0(x|z) &= (x|z) I_1(x|z),
\end{align*}
\]

and for \( i \in \{0, \ldots, m + 2n - 1\} \) we have

\[
\begin{align*}
\tilde{B}(z_i) I_0(x|z) &= 4z_i I_0(x|z), & \tilde{B}(x_i) I_0(x|z) &= 4z_i I_0(x|z).
\end{align*}
\]

(B.3)

The last equation expresses that \( I_0(x|z) \) is an eigenfunction of \( \tilde{B} \).
**Proof.** Equation (B.1) follows from the chain rule. Equation (B.2) follows immediately from equation (B.1) and the definition of the Euler operator. Using the same calculation as in the proof of Lemma 4.10, we obtain

\[
\widetilde{B}(z_k)(x|z)' = 4x_k l \left( l + \frac{M}{2} - 2 \right) (x|z)' - 1.
\]

We then find

\[
\widetilde{B}(z_k) l_0(x|z) = \Gamma \left( \frac{M}{2} - 1 \right) \sum_{l=0}^{\infty} \frac{1}{l! \Gamma (l + \frac{M}{2} - 1)} \widetilde{B}(z_k)(x|z)',
\]

\[
= 4x_k \Gamma \left( \frac{M}{2} - 1 \right) \sum_{l=0}^{\infty} \frac{l(l + \frac{M}{2} - 2)}{l! \Gamma (l + \frac{M}{2} - 1)} (x|z)' - 1
\]

\[
= 4x_k \Gamma \left( \frac{M}{2} - 1 \right) \sum_{l=0}^{\infty} \frac{1}{(l - 1)! \Gamma ((l - 1) + \frac{M}{2} - 1)} (x|z)' - 1
\]

\[
= 4x_k l_0(x|z).
\]

The calculations for the case \(\widetilde{B}(x_k) l_0(x|z)\) is analogous. 

**Lemma B.2** (properties of exp). For \(k \in \{1, \ldots, m + 2n - 1\}\) we have

\[
E_z \exp(-z_0) = -z_0 \exp(-z_0), \quad E_x \exp(-2x_0) = -2x_0 \exp(-2x_0), \quad (B.4)
\]

\[
\widetilde{B}(z_k) \exp(-z_0) = z_k \exp(-z_0), \quad \widetilde{B}(x_k) \exp(-2x_0) = 4x_k \exp(-2x_0), \quad (B.5)
\]

\[
\widetilde{B}(z_0) \exp(-z_0) = (2 - M + z_0) \exp(-z_0). \quad (B.6)
\]

**Proof.** Equation (B.4) is immediate. For equation (B.6) we have

\[
\widetilde{B}(z_0) \exp(-z_0) = (2 - M - 2E) \partial_0 \exp(-z_0) + z_0 \Delta \exp(-z_0)
\]

\[
= (2 - M - 2E) \exp(-z_0) - z_0 \partial_0 \partial_0 \exp(-z_0)
\]

\[
= (2 - M + 2z_0) \exp(-z_0) - z_0 \exp(-z_0)
\]

\[
= (2 - M + z_0) \exp(-z_0),
\]

while for equation (B.5) we compute

\[
\widetilde{B}(z_k) \exp(-z_0) = 0 - z_k \Delta \exp(-z_0) = z_k \partial_0 \partial_0 \exp(-z_0) = z_k \exp(-z_0).
\]

A similar calculation shows \(\widetilde{B}(x_k) \exp(-2x_0) = 4x_k \exp(-2x_0).\) 

**Lemma B.3** (properties of SB). We have

\[
E_z \text{SB} f(z) = -z_0 \text{SB} f(z) + \int_W (x|z) l_1(x|z) \exp(-z_0 - 2x_0) f(x), \quad (B.7)
\]

\[
\frac{1}{2} \widetilde{B}(z_0) \text{SB} f(z) = \frac{1}{2} (2 - M + z_0) \text{SB} f(z) + 2 \text{SB}(x_0 f)(z)
\]

\[
- \int_W (x|z) l_1(x|z) \exp(-z_0 - 2x_0) f(x), \quad (B.8)
\]

\[
\frac{1}{2} \widetilde{B}(z_k) \text{SB} f(z) = \frac{1}{2} z_k \text{SB} f(z) + 2 \text{SB}(x_k f)(z)
\]

\[
- 2 \int_W (z_0 x_k + z_k x_0) l_1(x|z) \exp(-z_0 - 2x_0) f(x), \quad (B.9)
\]

\[
L_{0k} \text{SB} f(z) = -z_k \text{SB} f(z) + 2 \int_W (z_0 x_k + z_k x_0) l_1(x|z) \exp(-z_0 - 2x_0) f(x). \quad (B.10)
\]
**Proof.** Equation (B.7) follows from (B.2) and (B.4). To prove equation (B.8) we apply the product rule (Proposition 3.3) to $-B(z_0)(\exp(-z_0)I_0(x|z))$ and substituting equations (B.3), (B.6), and the following easily verified identities

$$
\begin{align*}
\mathbb{E}_z(\exp(-z_0))\partial_{x^0}(I_0(x|z)) &= 2z_0x_0 \exp(-z_0)I_1(x|z), \\
\partial_{x^0}(\exp(-z_0))\mathbb{E}_z(I_0(x|z)) &= (x|z) \exp(-z_0)I_1(x|z), \\
z_0 \sum_{r,s} \beta^{rs} \partial_{x^r}(\exp(-z_0))\partial_{x^s}(I_0(x|z)) &= 2z_0x_0 \exp(-z_0)I_1(x|z).
\end{align*}
$$

Equation (B.9) follows in the same way using equations (B.3), (B.5), and while equation (B.10) follows immediately from

$$
\begin{align*}
L^{\tilde{z}}_{0k}(\exp(-z_0)I_0(x|z)) &= L_{0k}^{\tilde{z}}(\exp(-z_0))I_0(x|z) + \exp(-z_0)L_{0k}^{\tilde{z}}(I_0(x|z)) \\
&= -z_k \exp(-z_0)I_0(x|z) + \exp(-z_0)(z_0(2x_kI_1(x|z)) - z_k(-2x_0I_1(x|z))) \\
&= -z_k \exp(-z_0)I_0(x|z) + 2\exp(-z_0)(z_0x_k + z_kx_0)I_1(x|z).
\end{align*}
$$

This proves the lemma. \[\square\]

We can now prove Theorem 6.3. For convenience we restate it here.

**Theorem B.4** (intertwining property). For $M \geq 4$ the Segal–Bargmann transform intertwines the action $\pi$ on $W$ with the action $\rho$ on $F$, i.e.,

$$
\text{SB} \circ \pi(X) = \rho(X) \circ \text{SB},
$$

for all $X \in \mathfrak{g}$.

**Proof.** We will use the decomposition $\mathfrak{g} = J^- \oplus \text{istr}(J) \oplus J^+$ to prove equation (B.11) case by case.

**Case 1:** $X = (e_0, 0, 0)$. We wish to prove

$$
\text{SB}(2x_0f)(z) = \frac{1}{2}z_0 \text{SB} f(z) + \frac{1}{2} \tilde{B}(z_0) \text{SB} f(z) + \left(\frac{M}{2} - 1\right) \text{SB} f(z) + \mathbb{E}_z \text{SB} f(z).
$$

If we substitute (B.7) and (B.8) into the equation the result follows.

**Case 2:** $X = (e_k, 0, 0)$, $k \neq 0$. Substituting (B.9) and (B.10) in

$$
\text{SB}(2x_kf)(z) = \frac{1}{2}z_k \text{SB} f(z) + \frac{1}{2} \tilde{B}(z_k) \text{SB} f(z) + L_{0k}^{\tilde{z}} \text{SB} f(z)
$$

proves equation (B.11) for $X = (e_k, 0, 0)$.

**Case 3:** $X = (0, L_{0k}, 0)$. We wish to prove

$$
\frac{1}{2} \text{SB}(|2 - M|f) - \text{SB}(\mathbb{E}_x f)(z) = \frac{1}{2}z_0 \text{SB} f(z) - \frac{1}{2} \tilde{B}(z_0) \text{SB} f(z).
$$

Using (B.8) this becomes

$$
\text{SB}(|2 - M|f) = \text{SB}(\mathbb{E}_x f)(z) - 2 \text{SB}(x_0 f)(z) + \int_W (x|z)I_1(x|z) \exp(-z_0 - 2x_0) f(x).
$$
From the proof of [6, Proposition 8.9] it follows that \( \int_W (\mathbb{E}_x + M - 2)f = 0 \) when \( \int_W f \) is well defined. This gives

\[
\text{SB}((2 - M)f) = \exp(-z_0) \int_W (2 - M) I_0(x\vbar z) \exp(-2x_0)f(x) \\
= \exp(-z_0) \int_W \mathbb{E}_x(I_0(x\vbar z) \exp(-2x_0)f(x)) \\
= \int_W (x\vbar z) I_1(x\vbar z) \exp(-z_0 - 2x_0)f(x) - 2 \text{SB}(x_0f)(z) + \text{SB}(\mathbb{E}_x f)(z),
\]

where we used (B.2) and (B.4) to obtain the last equality.

**Case 4:** \( X = (0, L_{e_k}, 0), k \neq 0 \). In a similar fashion to (B.10), we find

\[
- \text{SB} \left( L_{0k}^x f \right)(z) = -\exp(-z_0) \int_W I_0(x\vbar z) \exp(-2x_0)L_{0k}^x f(x) \\
= \exp(-z_0) \int_W L_{0k}^x(I_0(x\vbar z) \exp(-2x_0)) f(x) \\
= 2 \int_W (x_0z_k + z_0x_k) I_1(x\vbar z) \exp(-z_0 - 2x_0)f(x) - 2 \text{SB}(x_k f)(z).
\]

Because of (B.9), this is equivalent to

\[
- \text{SB} \left( L_{0k}^x f \right)(z) = \frac{1}{2} z_k \text{SB} f(z) - \frac{1}{2} \tilde{B}(z_k) \text{SB} f(z),
\]

proving equation (B.11) for \( X = (0, L_{e_k}, 0) \).

**Case 5:** \( X = (0, [L_{e_i}, L_{e_j}], 0), i, j \neq 0 \). Using Proposition 3.10, we obtain

\[
\text{SB} \left( L_{ij}^x f \right)(z) = \exp(-z_0) \int_W I_0(x\vbar z) \exp(-2x_0)L_{ij}^x f(x) \\
= -\exp(-z_0) \int_W L_{ij}^x(I_0(x\vbar z) \exp(-2x_0)) f(x) \\
= -2 \exp(-z_0) \int_W (x_i z_j - (-1)^{|i||j|} x_j z_i) I_1(x\vbar z) \exp(-2x_0)f(x) \\
= \exp(-z_0) \int_W L_{ij}^z(I_0(x\vbar z)) \exp(-2x_0)f(x) \\
= L_{ij}^z \text{SB} f(z),
\]

thus equation (B.11) holds.

**Case 6:** \( X = (0, 0, e_0) \). Using (B.7) and (B.8), we can rewrite

\[
\frac{1}{2} z_0 \text{SB} f(z) + \frac{1}{2} \tilde{B}(z_0) \text{SB} f(z) + \left(1 - \frac{M}{2}\right) \text{SB} f(z) - \mathbb{E}_x \text{SB} f(z)
\]

as

\[
2z_0 \text{SB} f(z) + 2 \text{SB}(x_0f)(z) + (2 - M) \text{SB} f(z) - 2 \int_W (x\vbar z) I_1(x\vbar z) \exp(-z_0 - 2x_0)f(x).
\]

In a similar fashion to (B.8), we find

\[
\frac{1}{2} \text{SB} \left( \tilde{B}(x_0) f \right)(z) = \frac{1}{2} \exp(-z_0) \int_W I_0(x\vbar z) \exp(-2x_0) \tilde{B}(x_0) f(x) \\
= \frac{1}{2} \exp(-z_0) \int_W \tilde{B}(x_0) (I_0(x\vbar z) \exp(-2x_0)) f(x)
\]
So we conclude that equation (B.11) holds for $X = (0, 0, e_0)$.

**Case 7:** $X = (0, 0, e_k), k \neq 0$. To show

$$\frac{1}{2} \text{SB} \left( \tilde{B}(x_k) f \right) (z) = \frac{1}{2} z_k \text{SB} f (z) + \frac{1}{2} \tilde{B}(z_k) \text{SB} f (z) - L_{0k}^z \text{SB} f (z),$$

we substitute (B.9) and (B.10) into the equation. So we obtain

$$\frac{1}{2} \text{SB} \left( \tilde{B}(x_k) f \right) (z) = 2z_k \text{SB} f (z) + 2 \text{SB}(x_k f)(z)$$

$$- \frac{4}{2} \int_W (z_0 x_k + z_k x_0) \mathbb{I}_1(x|z) \exp(-z_0 - 2x_0) f(x).$$

In a similar fashion to (B.9), we find

$$\frac{1}{2} \text{SB} \left( \tilde{B}(x_k) f \right) (z) = \frac{1}{2} \exp(-z_0) \int_W \mathbb{I}_0(x|z) \exp(-2x_0) \tilde{B}(x_k) f(x)$$

$$= \frac{1}{2} \exp(-z_0) \int_W \tilde{B}(x_k) (\mathbb{I}_0(x|z) \exp(-2x_0)) f(x)$$

$$= 2z_k \text{SB} f (z) + 2 \text{SB}(x_k f)(z)$$

$$- \frac{4}{2} \int_W (z_0 x_k + z_k x_0) \mathbb{I}_1(x|z) \exp(-z_0 - 2x_0) f(x).$$

This proves the theorem. 

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**References**


A Fock Model and the Segal–Bargmann Transform for $\mathfrak{osp}(m,2|2n)$


